

# Geomet

# Junior

## User Guide

Version 6.66  
December 2006

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*Helmel Engineering Products, Inc*

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6520 Lockport Road

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Niagara Falls, NY 14305

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(716) 297-8644

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(716) 297-9405 fax

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[www.helmel.com](http://www.helmel.com)

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[www.geomet-cmm-software.com](http://www.geomet-cmm-software.com)

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# Geomet Junior

Universal CMM Software

Version 6.66  
December 2006

Covering Geomet Junior  
and Geomet JuniorPlus

*By*  
*Edward R. Yaris*  
*Software Development Manager*

***Hemel Engineering Products, Inc.***

6520 Lockport Road  
Niagara Falls, NY 14305  
(716) 297-8644  
(716) 297-9405 fax

[www.hemel.com](http://www.hemel.com)  
[www.geomet-cmm-software.com](http://www.geomet-cmm-software.com)



# Geomet

## Universal CMM Software

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### ***Helmel Engineering Products, Inc.***

6520 Lockport Road  
Niagara Falls, NY 14305  
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(716) 297-9405 fax

[www.helmel.com](http://www.helmel.com)  
[www.geomet-cmm-software.com](http://www.geomet-cmm-software.com)



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# Chapter 1 – Geomet Versions

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## Geomet Version Comparison Chart

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Geomet operates in different levels designed to match your inspection needs. These levels are known as:

- Geomet Junior
- Geomet Junior Plus
- Geomet 101
- Geomet 301

**NOTE: Keep current with the latest changes in Geomet by visiting:**

**[www.geomet-cmm-software.com](http://www.geomet-cmm-software.com)**

## Geomet Junior

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Geomet Junior is the entry-level full 3D-inspection system of the Geomet series, yet it is packed with most of the functions needed for basic inspection. It favors one touch access to all basic geometric elements in addition to a highly visible set of icons on the screen for intuitive measuring without extensive training. Ideal for use with touch screen applications. Geomet Junior includes a powerful set of Part Coordinate System (PCS) generation tools that Geomet is famous for. Geomet Junior is limited to one PCS and one qualified stylus. Geomet Junior is included with the purchase of all Helmel manual Coordinate Measuring Machines.

## Geomet Junior Plus

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Geomet Junior Plus expands Geomet Junior by expanding support for unlimited stylus qualifications, unlimited part coordinate systems and part program runs. This option provides full inspection tools to support full 3D inspections in a production environment. It does not provide graphical support, which is reserved, for 101 and 301 levels.

## Geomet 101

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Geomet 101, our most popular package, offers great flexibility for inspecting parts in the lab or on the production floor. The graphical area on the right side of the display generates a pictorial representation of the measured features which serves as a visual guide for part programs and as a link to the final inspection results. Program writing is done in the self-teach mode, editing is easy and efficient. Geomet 101 includes a full suite of reverse engineering tools. The GeoPlus option expands Geomet 101 to include powerful features such as Vector Point, customized tagging for printing and exporting and analytical tools for circular features. Geomet 101 is designed for the production environment where obtaining and tracking numerical solutions is preferred.

## Geomet 301

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Geomet 301, our most advanced system, offers the sophisticated user unbridled measuring power with the typical user friendliness of Geomet. It contains all the power of Geomet 101 and a host of other analytical tools to review and manipulate your part inspections. The time proven and inherent quality of the Geomet algorithms guarantee meaningful results when creating new and difficult relationships out of measured features and PCS's. Geomet 301 offers an optional expansion package to unlock the power of surface point analysis against a CAD model. This power allows the user to align the CAD model with the part to be inspected. Then capturing of data points can be calculated against the model to obtain position within a profile zone.

## Geomet Comparison Chart

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Due to its dynamic nature, the full comparison chart can be viewed on the Geomet web site at:

<http://www.geomet-cmm-software.com/KB/Chapter1/KB10091.htm>

This chart details the differences between the various levels of Geomet.

# Chapter 2 – System Setup

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## Chapter 2 – System Setup

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# Chapter 2 – System Setup

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## **Geomet Junior Installation Guide - Introduction**

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### **Summary of basic steps**

1. Uninstall the current version of Geomet.
2. Install the new Geomet Junior.
3. Install the Crypkey license driver.
4. Run Geomet Junior and Obtain Site Code.
5. Contact Helmेल Engineering for the GeoSecure Code
6. Enter the GeoSecure Code to activate your Geomet products.

### **IMPORTANT: Changes to the Protection Device**

With the introduction of Geomet version 6.66, the new protection scheme for the Geomet family of software incorporates the Crypkey software license system. Earlier versions of Geomet required the use of a hardware “dongle” that plugged into the parallel port. This protection dongle will only be required if you are using GeoCAD. Once Geomet version 6.66 is installed and running, the hardware dongle should be returned to Helmेल.

The Crypkey software protection scheme utilizes information from the PC to generate the Geomet Junior authorization codes. The codes are unique to your computer system, and cannot be used on another system. The system will run with Windows 98 SE and Windows 2000/XP. Windows 2000/XP systems need to have the Crypkey license installed and running as a Windows service. On a Windows 98 SE system, the protection device runs as a system driver, not a service.

## Chapter 2 – System Setup

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### **The Geomet Junior Installation Program - Summary**

The Geomet Junior installation program will install Geomet Junior, GeoClean, GeoStat, and Gage R&R. When Geomet Junior has been authorized, your GeoStat and Gage R&R will also be authorized if those options have been purchased. Both GeoStat and Gage R&R can be authorized without enabling Geomet Junior, for stand alone cases in which a PC separate from the CMM is to be used for data analysis.

### **Microsoft Direct X**

Geomet Junior uses Microsoft DirectX for sound and image support. The installation process will verify the current installed version and determine if an upgrade is used.

### **Additional Drivers and System Support Files**

Driver and System Support files (\*.sys, \*.inf and \*.ocx) for all Geomet Junior operations are installed. Changes have been made to the CMM interface drivers. Previously there was an entry in the Windows Registry that no longer is required. The new CMM drivers are registered with the Windows System. The installation process will guide you to setting up your interface.

## Before Installing Geomet Junior

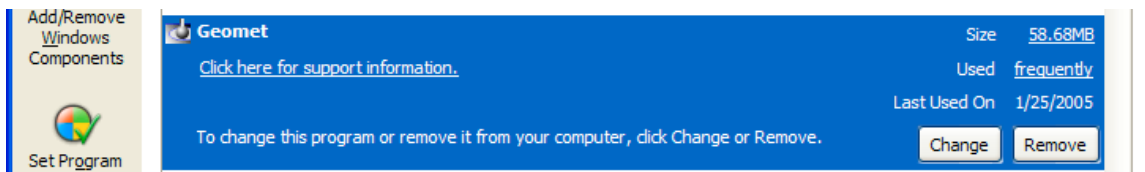
### Uninstall Previous Geomet Versions

Before you run the installation program, it is important that you uninstall all existing Geomet related programs. This includes GeoStat and Gage R&R. Use the Control Panel tool provided in Windows to uninstall the Geomet software. In the example below, we show the Control Panel on a Windows XP system.



*Windows XP Control Panel*

Locate the program **Add or Remove Programs** and start that application by double clicking. A listing of all programs for which Windows has uninstall options will be listed. Locate the Geomet listing, see figure 2, and select the <Remove> button.



*Windows XP Control Panel*

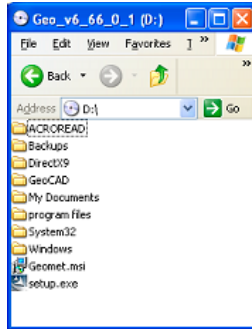
You will be asked to confirm that Geomet should be removed. Answer by accepting <Yes> and Geomet and all associated program files will be removed.

The uninstall process does not remove any Windows registry settings, inspection programs, library or stylus database files associated with Geomet. Therefore, the updated Geomet will retain the preference settings previously active. We recommend as a normal operating procedure that you always make a backup copy of your inspection part programs. If required, repeat the uninstall process for GeoStat and Gage R&R programs.

# Chapter 2 – System Setup

## Installing Geomet Junior – Step-by-Step Guide

To install Geomet Junior, place the CD in your system's drive. This CD does not contain an auto run option and you should open and view the contents of the CD with Windows Explorer or similar method. Please ensure all programs are closed before performing the installation. On the root directory, there are several folders and text files.



*Geomet Junior Installation CD Root Directory*

### Step 1 – Readme.pdf

Before you begin the installation please take a quick review of the Readme.pdf latest instructions for any changes to the installation process not covered here. Should your system not have Adobe Acrobat Reader installed, please see the section on installing the Acrobat Reader later in this document.

To start the Geomet Junior installation, double click on the file setup.exe. The setup routine will launch and guide you through the required steps.

### Step 2 – Welcome to the Installer

This first step is the welcome screen for the installer, press <Next> to proceed.

### Step 3 – License Agreement

This step requires that you have read and agreed to the terms and conditions in regard to using Geomet Junior.

### Step 4 – Customer Information

Complete the required fields as appropriate.

### Step 5 – CMM Interface

Choose the CMM Interface as noted on the Geomet Junior Software Security Code sheet.

## Chapter 2 – System Setup

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### Step 6 – Custom Setup

Press the <Next> button to accept the defaults. By default all help files and driver files are installed. You can choose to remove these files from the installation.

### Step 7 – Ready to Install

The final step, when accepted by pressing the <Install> button, will begin the installation of Geomet Junior to your system. Installation also installs the files necessary for the uninstall process.

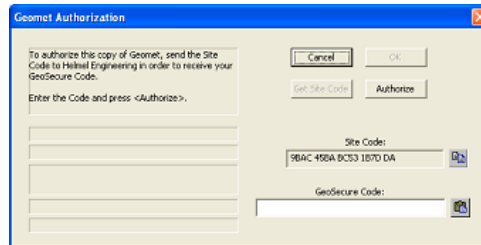
Once completed, the installer will notify you of the success of the installation process. Should any errors occur, you will be notified. The most common error noted has been leaving Geomet Junior active (open) while attempting to upgrade. This will cause an error and the installation process will fail.



## Chapter 2 – System Setup

### Authorizing the Geomet Junior Software

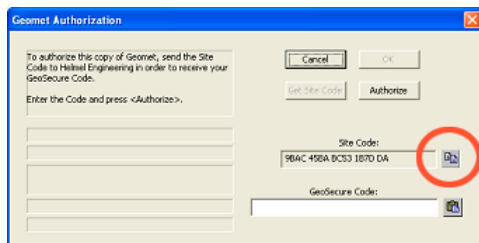
The authorization process for Geomet Junior will also provide the authorization for both GeoStat and Gage R&R. Unlike previous versions, GeoClean no longer has the responsibility for the authorization process. When launching Geomet Junior v6.66 the first time, a message will indicate that the authorization needs to be established. Click the <OK> button to open the authorization dialog, as seen below.



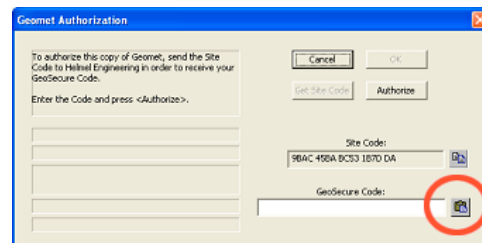
Geomet Junior Authorization Screen

The Site Code is automatically generated by the Crypkey License service and is specific to your PC. This Site Code needs to be sent to Helmel Engineering so that your GeoSecure Code can be generated.

It is the combination of Site Code and GeoSecure Code that will authorize the Geomet Junior software. Each time the Geomet Junior Authorization screen is displayed, a new Site Code will be generated. Since the Site Code must match the GeoSecure code, ***do not close the Geomet Junior Authorization dialog before entering the matching GeoSecure Code. If the dialog is closed, a new Site Code will be needed.***



Site Code Copy Button



GeoSecure Code Paste Button

Copy the Site Code and send it to Helmel Engineering using the Geomet web site Authorization form:

<http://www.geomet-cmm-software.com/Authorize.htm>

Please include the Copy of the Site Code (Edit⇒Paste) into the Authorization Form and include your **Name, Phone Number, CMM Serial Number (99-99)** and the return email address.

## Chapter 2 – System Setup

We will contact you as soon as possible with a GeoSecure Code. When you receive the return email, highlight the supplied GeoSecure Code and copy (Edit⇒Copy) and Paste it into your Geomet Junior Authorization dialog. Press <Authorize> after the GeoSecure code has been entered.

If your email service is not on the same computer as the Geomet Junior system, copy the GeoSecure Code and enter it manually.

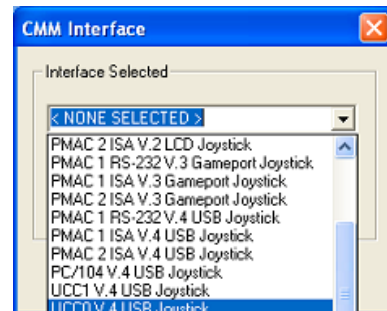
Once Geomet Junior has been authorized, click the <OK> button to continue starting Geomet Junior. To check the enabled options while Geomet Junior is running, press Ctrl-Alt-U from the main screen of Geomet Junior to show the Geomet Junior Authorization dialog. Should you want to change your options, you can generate a new Site Code from this dialog, which can be sent to Helmel Engineering in order to change the enabled levels and options.

If the authorization of Geomet Junior included the options for GeoStat and Gage R&R, these programs can be opened at any time. Otherwise when attempting to open the program, an authorization screen similar to Geomet Junior's will be displayed, requiring a GeoSecure code to enable the program.

### Switching CMM Interfaces

By default, the Geomet Junior installation creates a folder in the Program Files\Hemel Engineering\Geomet 101 folder named Interfaces. This folder will contain the CMM interface (Table Control file) for each of the different systems. To switch from the currently registered interface, close Geomet Junior, open GeoClean, and from the Registry pull-down menu, choose Select Interface.

Choose the desired interface from the pull-down list, and hit the <OK> button. Answer <Yes> to the confirmation screen, and GeoClean will register the appropriate interface with Windows. Windows will provide a message indicating the success of the registration. Open Geomet Junior to see that the new interface has been properly configured.



Since Geomet Junior uses the interface registered with Windows, and ignores any setting of the interface in the Geomet 101 SYSTEM SETTINGS registry, GeoClean will only register the new interface with Windows. The registry will be unchanged.

### Installing Acrobat

Run the AdbeRdr60\_enu\_full.exe file located on the Geomet CD under the ACROREAD\Installers folder.



# Chapter 2 – System Setup

## Geomet Junior System Options

Keyboard: F9

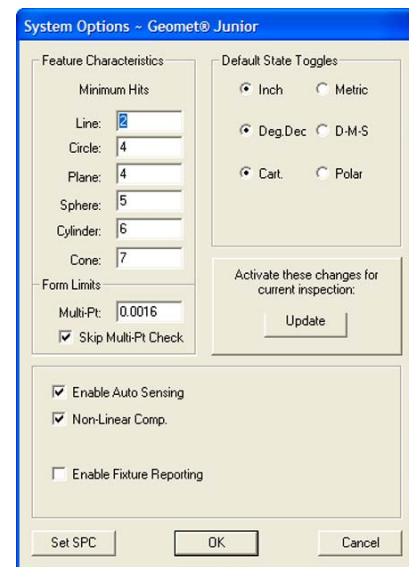
Menu: System ⇒ System Options

The Geomet Junior system has many options and system characteristics that control the behavior of the system. These include optional hardware, file locations, default features setting to name a few.

### Feature Characteristics

The Feature Characteristics provides access to establishing the minimum number of data points for all multi-point features. For example, launch the circle measurement function and the default number of data points are provided, in this example 4. If your inspection process require that you need more than 4 data points on every circle, enter a new value as the default.

It is recommended that on a multi point feature, the minimum number of hits should be set 1 greater than the minimum allowed for solving for that feature. This allows for form fit testing to ensure the data points created a sound feature. The table below lists the minimum and recommended number of data points required in Geomet Junior for a feature.



Feature Type	Minimum	Recommended
Line	2	2
Circle	3	4
Plane	3	4
Cylinder	6	6
Cone	6	7
Sphere	4	5

NOTE: On Cylinder and Cone features, Geomet requires minimum + 1 for its internal algorithm used to solve the feature.

## Form Limits

### Multi-Point Error Limit

This value is used during the measuring process to validate the form of a multi-point feature before it is committed to the inspection report. For example, when measuring a circle, it is expected that the circularity is better than the form error limit. If during the measuring process the circularity exceeds this form limit (0.001" by default), then a warning is provided to allow the operator to accept or re-measure the feature. This validation process helps to minimize errant data points or poor fitting features.

Default: 0.001"

### Skip Multi-Point Check

When NOT checked, Geomet Junior performs the Multi-Point Error Limit test on all measured multi-point features.

### Enable Auto Sensing

Default: Not Checked. When checked Geomet Junior reconfigures to sense for the current probe direction vector, *see Auto-Direction in Chapter 8 for a complete description*. This option is only available on some CMM interfaces that allow time based monitoring of CMM motion.

Default: Checked

### Non-Linear Compensation

The use of non-linear compensation is set by the factory or by the technician performing calibration on the CMM. This option involves the mapping of your scales on the X, Y, and Z-axes. *See Technical Note #2 for enhanced description*.

## Default Toggle State

The Default Toggle State page controls the reporting formats used at startup or globally changed during the self-teach mode.

### Reporting Characteristics

Select the small button next to the reporting characteristic.

Description	Option 1	Option 2
Unit of Measure	Inch	Metric
Angular Reporting	xx.xx°	dd mm ss°
Reporting Format	Cartesian	Polar

## Activate these changes for current inspection

By selecting this option, all selections in Report States will activate immediately. Under normal conditions, Report States control the behavior of the inspection when it creates a new inspection report.

### CMM Scale Compensation

Coordinate Measuring Machines utilize scales that are mounted to each axis of motion will require compensation. This compensation will correct for any linear deviations identified during CMM calibration.

A certified Master Scale or Laser system is used to compare against the reported position from the CMM Digital Readout. This deviation can then be mathematically corrected. This information must be supplied to your CMM software to properly measure. There are two main types of scale comparison technologies. These are **Linear** and **Non-Linear** Compensation.

For additional information refer to Technical Note #2, Inherent Errors located in Appendix 1.

### Linear Compensation

Linear Compensation is a single correction value used to compensate the full length of travel. For example; if your CMM has a Y-axis travel of 10.0”, you would test the reported position at its extent against the master scale.

Position Reported by Laser	CMM Digital Readout	Compensation value
10.00000	10.00235	0.99976505

The value, 0.99976505, would be entered in the Linear Setup Tool for the Y-axis and that value becomes the multiplier for all positions. Geomet Junior will use the following formula to compensate for position:

$$\begin{aligned} X_{\text{DRO Reported Value}} * X_{\text{Compensation}} &= X_{\text{Corrected Position}} \\ Y_{\text{DRO Reported Value}} * Y_{\text{Compensation}} &= Y_{\text{Corrected Position}} \\ Z_{\text{DRO Reported Value}} * Z_{\text{Compensation}} &= Z_{\text{Corrected Position}} \end{aligned}$$

All reported values that pass into Geomet Junior will be passed through the Linear Compensation tool prior to being used for any calculations.

## Activating the Linear Setup Tool

Keyboard: <Alt + Ctrl + shift + F2>

## Taking a Tour of the Linear Setup Tool

The controlled data is shown in the upper section of the tool where the entered and calculated axis values are shown.

*Calculate Compensation*

When performing a calibration, there are three values per axis. Two of which must be entered and the third will be calculated. In the example above, the operator enters the Reference Length and reported Measured Length. The third value, Compensation Value will be calculated.

### Reference Length:

This is the reported position from the Master Scale or Laser.

### Measured Length:

This is the reported *uncompensated* Digital Readout value scale position.

### Compensated Value:

The compensated value is the result of Reference Length / Measured Length.

## Position Comparison Group

### Selecting the Active Axis

In this area choose the axis you wish to calibrate.

### **No Compensation**

This data field shows the current position directly from the CMM scales with no compensation applied.

### **With Compensation**

As the name suggests, this is the reported position with the current compensation applied. This is the result of (Using the x-axis as the example):

$$X_{\text{No Compensation Position}} * X_{\text{Compensation}} = X_{\text{With Compensation Position}}$$

### **Difference**

This reported value is the spread between the **No Compensation** and **With Compensation** positions.

### **Min, Max, Spread**

These values will update when the <Start / Stop Test> button has been pressed. This reports the difference value while moving the CMM along the selected axis. Use it to determine the total spread that will occur over the full length of travel.

## **Functions**

### **<DRO>**

Toggles the visible state of the standard Geomet Junior Digital Readout.

### **<DRO Xfer>**

Copies the current position into the Measured Length data field. This value is the un-compensated position shown in the No Compensation data field.

### **<Zero Axis>**

Sends an offset position to the internal counter that changes the current position to 0.000. This is used to zero the current position and is done in conjunction with the setting of the zero position for the Master Scale or Laser making both devices equal at that position.

When the zero option has been applied to an axis, there is a visual reminder, “Zero Set”, next to the axis.

### **<Clear Zero>**

Removes a previous zero offset value from the selected axis.

### **<Update Compensation>**

This command transfers the calculated Compensation Value from the Setup Tool into Geomet Junior. This is used when displaying the Geomet Junior DRO for comparison. This command is optional.

### <Enter Compensation Factors>

This command is a push-on / push-off button. It toggles the disabled state of the Measured Length and Compensation Values columns. When providing the Reference Length and Measured Value, this button is off which will disable the Compensation Value. It is used when only the Compensation Value is provided for calibration.

### <Start / Stop Test>

The test is designed to capture the minimum, maximum and spread for the entire length of the selected axis. To use, start the test by pressing the button once. A message will appear indicating the test is active. Move the CMM along the selected axis. The test values will display providing the variations along the travel.

## Setting the Compensation Value

The process of determining the compensation values requires the use of a Master Scale or Laser system.

### Master Scale

If used a master scale, a reader head is mounted on the CMM probe bar and the certified scale is mounted inline with the axis to test. The reader head is adjusted to read the scale over the full length of travel. Once the alignment has been completed, move the CMM back to a starting point. For example in the Y-axis, move the CMM to its most –Y position.

Zero the digital Readout that is used to report the position along the master scale. In the Linear Setup Tool, ensure the correct axis is elected (Y Position) and press the <Zero Axis> button. This action will result in the master scale and CMM readout both reporting 0.000.

Move the CMM slowly in the +Y direction until you reach the furthest position. The master scale will report a linear position, which is then entered into the **Ref. Lgth** column for the y-axis. In the No Compensation position field you will find the CMM readout value. Transfer this value into the **Meas. Lgth** column by pressing the <DRO Xfer> button. When this is accomplished, the compensation Value is automatically updated and the updated position in the **With Compensation** field should match the master scale position.

Repeat this procedure for each axis. To verify the compensation value, use the <Start / Stop Test> function.

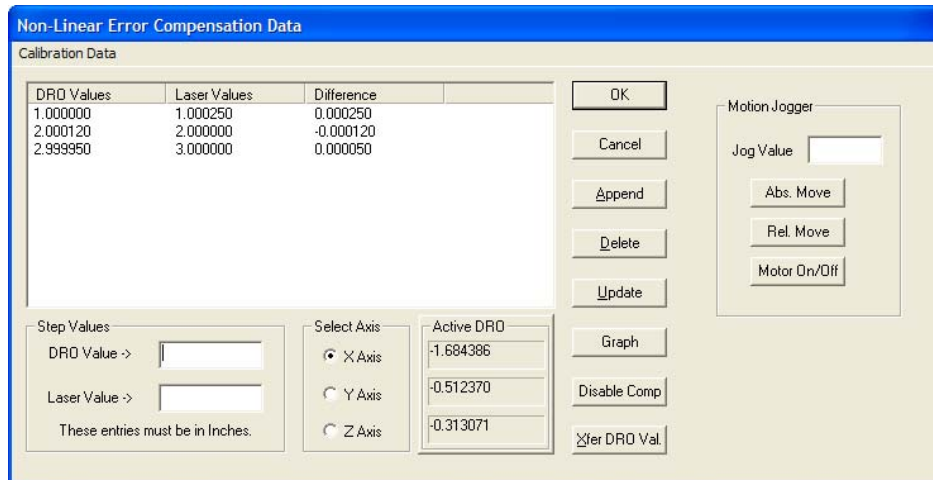
### Using a Laser

The procedure is the same as described for Master Scale.

## Non-Linear Compensation Tables

This form of compensation provides a more accurate solution for determining scale corrections using many segments over the axis of travel. A typical scale when mounted to the CMM can stretch and shrink over its length. The compensation required between 10.000” - 11.000” may be different than between 20.000” – 21.000”.

The method to determine the compensation is done by taking position readings along the full travel, for example, every 1.000”. A table is built using the Master Scale or Laser position and the reported CMM position.



Non-Linear Setup Tool

## Non-Linear Setup Tool

Activating the Non-Linear Setup Tool requires that the Non-Linear Compensation flag be checked in the [System Option].

### Activating the Non-Linear Setup Tool

Keyboard: <Alt + Ctrl + shift + F2>

## Taking a Tour of the Linear Setup Tool

### Calibration Data List

The list of Master Scale or Laser readings along with its corresponding DRO positions are shown under Calibration Data. This list does not show the compensation value, which is calculated as:

$$X_{\text{Reference Value}} / X_{\text{DRO Reported Value}} = X_{\text{Compensation Value}}$$

## Chapter 2 – System Setup

---

Selecting an entry in the data list will bring the position values down into edit controls labeled **DRO Value ->** and **Laser Value ->**. From the edit controls changes can be made when performing or editing a calibration.

### <Append>

When building the data list, new entries are added by entering the reference and DRO positions in the Step Value Group. Pressing <Append> will then transfer that data into the list. This list performs a sort to keep the list in linear order.

### <Delete>

Removes the selected position from the data list.

### <Update>

When a position record is selected, changes can be made to the laser and DRO position values. Once the changes have been completed, press <Update> to transfer the changes into the data list.

### <Graph>

Displays a graph of the position difference values. This graph can be printed for the current axis or for all three axes.

### <Disable Comp>

When <Disable Comp> is active, Non-Linear compensation is deactivated and the CMM will use Linear Calibration. When pressing, the Non-Linear tables are saved to the data file.

### <Xfer DRO Val.>

Moves the current position displayed in the Active DRO Group into the edit control labeled **DRO Value ->**.

## Motion Jogger Group

The Motion Jogger Group is available on CMMs that have a motion controller.

### <Abs. Move>

Positions the CMM under DCC to the absolute position entered in Jog Value.

### <Rel. Move>

Positions the CMM under DCC to the relative step position entered in Jog Value.

### <Motor On/Off>

Toggles the state of the motors between On or Off.



# Chapter 2 – System Setup

## Geomet Junior Toolbar

Geomet Junior provides an iconic toolbar for access to the most common functions. This toolbar contains validation control that will enable or disable certain features based on the last operation Geomet Junior has completed.



		Open existing inspection file.
		Save-As current inspection file.
		Prints the current inspection report.
		Launches the System Options Tool.
		In standard Junior mode, launches the calibration tools. In Junior-Plus mode, launches the Stylus Manager.
		Activates the Report Header Tool.
		Orientation Tool.
		Alingment Tool.
		Origin Tool.
		Establishes an Interin Coordinate System (ICS⇒PCS).
		Rotate the existing PCS around one axis.
		Translate the existing PCS in XYZ coordinates.
		Available in Junior-Plus. Activates the Recall PCS Tool.
		Activates the Enter Text or Coomment Tool.
		Point Measurement (1D, 2D or 3D).
		Circle Measurement Tool.
		Line Measurement Tool.
		Plane Measurement Tool.
		Sphere Measurement Tool.
		Cylinder Measurement Tool.
		Cone Measurement Tool.
		Contrsct a Line from existing features.
		Contrsct a Circle from existing features.
		Contrsct a Plane from existing features.
		Activate the GeoTol, Form Tolerance Tool.
		Feature Bisect Tool.
		Feature Intersect Tool.
		Distance Tool.
		Angle Tool.
		Feature Recall Tool.

## Chapter 2 – System Setup

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# Chapter 3 – Stylus Management

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## Chapter 3 – Stylus Management

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## Chapter 3 – Stylus Management

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# Chapter 3 – Stylus Management

## Stylus Qualification – Geomet Junior

Geomet Junior is limited to qualifying one stylus tip. Geomet Junior also does not support articulating, manual and motorized, probe heads.

The Qualify Ball Stylus is activated by:

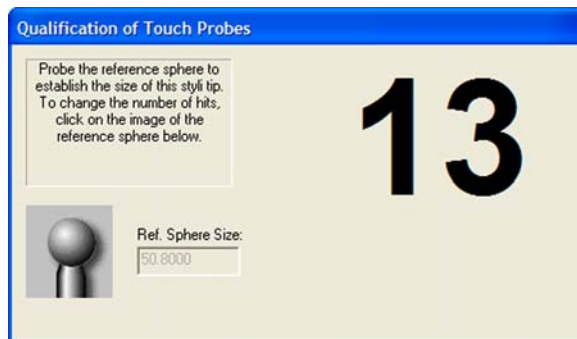
Keyboard: w

Menu: Qualify->Qualify Ball Stylus



Qualify Icon

Geomet Junior will display the Qualify count down box

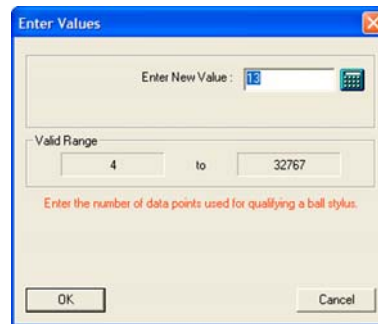
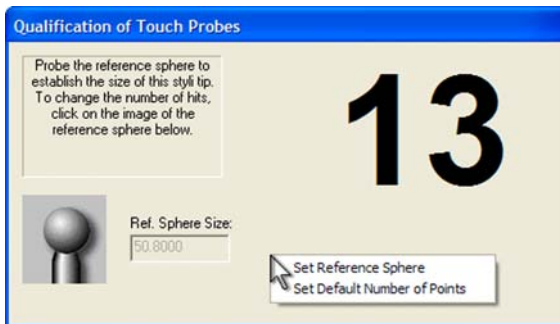


Capture the required number of data points around the reference sphere.

### Set the default number of hits

All Geomet products default to 5 data points for the qualification process. To change this value, there are two methods.

Activate the sub menu by right clicking on the Qualification count down box as shown in the figure below.



## Chapter 3 – Stylus Management

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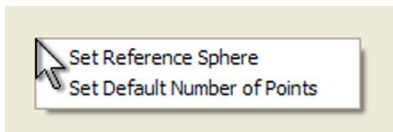
Select from the sub menu [Set Default Number of Points]. The Enter Values dialog will appear where you can change the number of hits.



The second method is too left-click on the sphere image. The Enter Values dialog will appear where you can change the number of hits.

### Setting the Reference Sphere Size

To change the size of the reference sphere, activate the qualification sub menu by right clicking on the Qualification count down dialog.

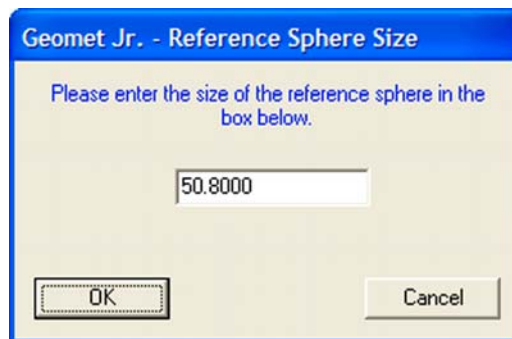


Choose [Set Reference Sphere] from the sub menu. The data field below “Ref. Sphere Size” will become active and you can enter a new value. When you have completed entering the new size, press the < ↵ Enter > key on you keyboard which will save the new size.

You can also change the Reference Sphere size when not in the Qualify mode by selecting from the main menu:

Qualify ⇒ Reference Sphere

You will then be prompted to enter the new diameter of the Reference Sphere.



## Chapter 3 – Stylus Management

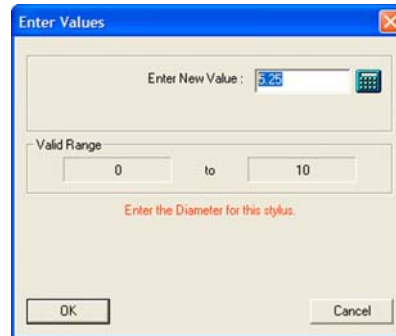
---

### Enter the Stylus Size Manually

To enter the Stylus diameter manually, from the main menu choose:

Qualify ⇒ Enter Diameter

Enter your new diameter and press <Ok>. NOTE: If using a cross hair generator on a video camera as you stylus, enter 0.00 in the size.



### Other Qualifying Options

Geomet Junior has the ability to Re-Qualify the existing stylus. This allows you the ability to change your stylus to another size and to qualify that new stylus tip against the reference sphere. Full help details can be found later in this chapter in the Geomet Junior Plus section.

# Chapter 3 – Stylus Management

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## Stylus Manager – Geomet Junior Plus Only

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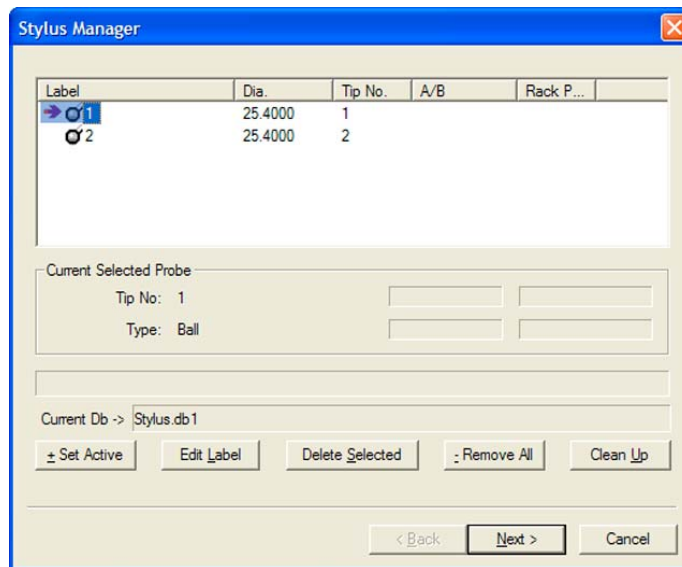
Geomet Junior maintains a database of known, qualified styli. Each stylus used is qualified against a standard reference sphere to identify the size and MCS location. Knowing the size and location allows Geomet Junior to properly apply compensation to all measured features. Knowing the location allows the switching of the styli between positions in a cluster.

Stylus Management is handled by the Stylus Manager that contains all the tools necessary for qualifying, re-qualifying and choosing a stylus for use in measuring. The configuration of all your stylus hardware is maintained in the System Options on the Probes and Sensors page.

The Stylus Manager is activated by:

Keyboard:     w

Menu:           Qualify->Stylus Manager



## Probe Qualification Process

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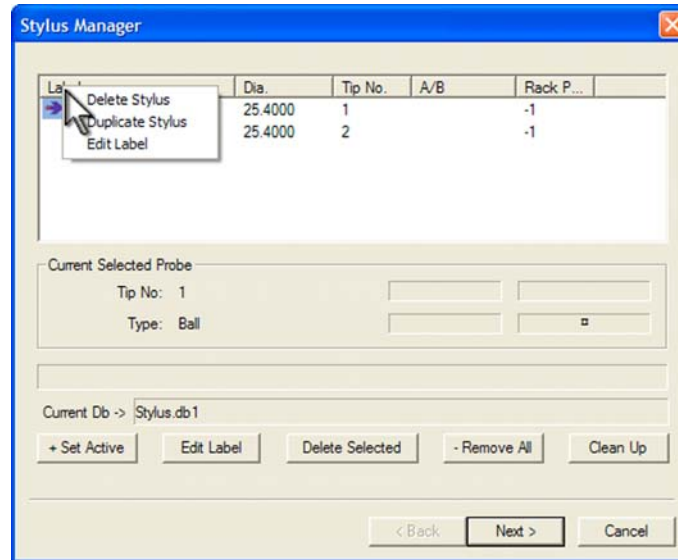
After qualifying the first stylus, Geomet Junior maintains that position as the reference position for the entire stylus database. When adding additional styli, Geomet Junior maintains the location relationship between the newly qualified stylus and the first stylus. This relationship is applied when setting any stylus active and allows correct compensation for any qualified position, even in the same feature, without loss of accuracy.



# Chapter 3 – Stylus Management

## Stylus Manager Sub Menu Tools

There exists a sub menu that can be called up to react directly with the list of stylus records. To activate the sub menu, right-click in the list area and the sub menu will appear.



Through the sub menu you have access to three functions. These are:

- Delete Stylus
- Duplicate Stylus
- Edit Label

All three functions work on the highlighted stylus, but only the Delete Stylus has more than one feature. When a stylus is highlighted, the delete function will delete only that stylus. When there are no stylus selected, the delete will clear all stylus information from the database.

# Chapter 3 – Stylus Management

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## Deleting Stylus from the Stylus Manager

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### Summary

Deleting a stylus will remove from the database all information regarding position and size. Caution should be taken when deleting a stylus from the database. Geomet Junior will mark any styli missing as Pre-Qualify when opening an inspection that requires the deleted tip.

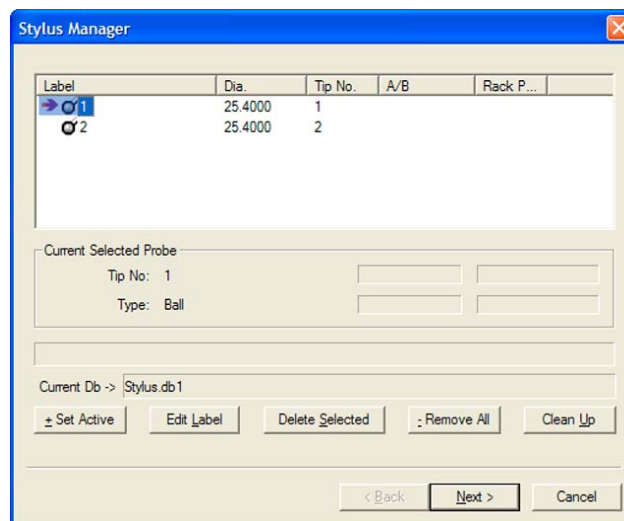
- Delete a single Stylus
- Delete all Stylus
- Remove all Pre-Qualified Stylus

## Delete a Single Stylus

---

### Step 1

Activating the Stylus Manager can be done through the use of the 'w' keystroke or through the drop down menus [Qualify->Stylus Manager].



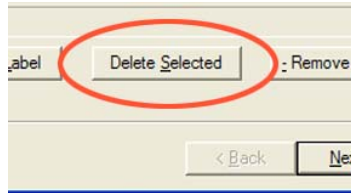
The Stylus Manager will display all current, qualified styli and pre-qualified styli. The current active stylus is shown with an arrow located next to it.

# Chapter 3 – Stylus Management

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## Step 2

Highlight the desired stylus to delete and click on the <- Delete Selected> button, or press <Alt + S> on the keyboard. You will be prompted to confirm your request. A message will appear to confirm the deletion of the selected stylus, click on the <Ok> button to delete the stylus. NOTE: If you are attempting to delete the primary stylus (#1), you will invalidate all styli in the database. A message will prompt you explaining this before you delete.



## Delete all Stylus

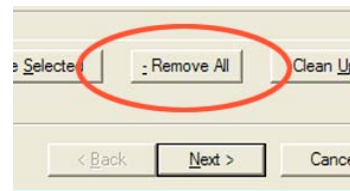
---

### Step 1

Activating the Stylus Manager can be done through the use of the 'w' keystroke or through the drop down menus [Qualify => Stylus Manager].

### Step 2

With no stylus highlighted in the selection, click on the <- Remove All> button or press the '-' (minus) key on the keyboard. You will be prompted to confirm your request. To confirm the deletion of all styli, click on the <Ok> button in the message dialog.



# Chapter 3 – Stylus Management

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## Remove all Pre-Qualified Stylus

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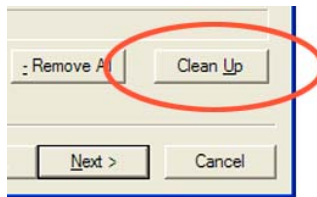
### Step 1

Activating the Stylus Manager can be done through the use of the 'w' keystroke or through the drop down menus [Qualify->Stylus Manager].

Pre-Qualified stylus are inserted into the stylus database only when opening a previous part inspection file that uses styli that are not currently part of the active stylus database. For example, if a part inspection was done that required the use of stylus numbers 1, 2, 3, 4, and 5 those references are stored in the part inspection file. Should the current stylus database be changed to have only stylus numbers 1, 2, and 3 qualified and the part inspection file was opened, Geomet Junior would insert stylus 4 and 5 and mark them as pre-qualified. You will not be allowed to proceed with the inspection without first qualifying stylus 4 and 5.

However, should you want to just remove the pre-qualified stylus, the button <Clean Up> will be made available.

### Step 2



When there are 1 or more styli marked as Pre-Qualify, you can delete all of them with the use of the <Clean Up> button.

# Chapter 3 – Stylus Management

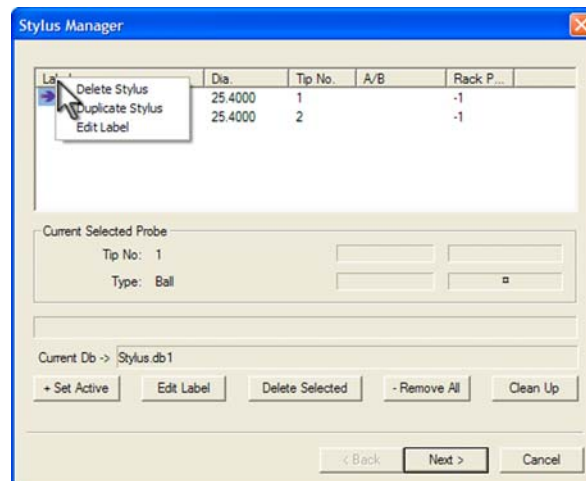
## Duplicate a Stylus

### Summary

To create a copy of an existing stylus can be accomplished with the Duplicate Stylus command. This command is especially helpful when creating a stylus database on manual friction style probing systems where the need to re-qualify multiple positions are required.

### Procedure

To duplicate a stylus, start by highlighting an existing and qualified stylus tip. Right-click to activate the sub-menu and choose the [Duplicate Stylus] command, *see figure below*. An exact copy of the highlighted stylus is created and is appended to the Stylus database.

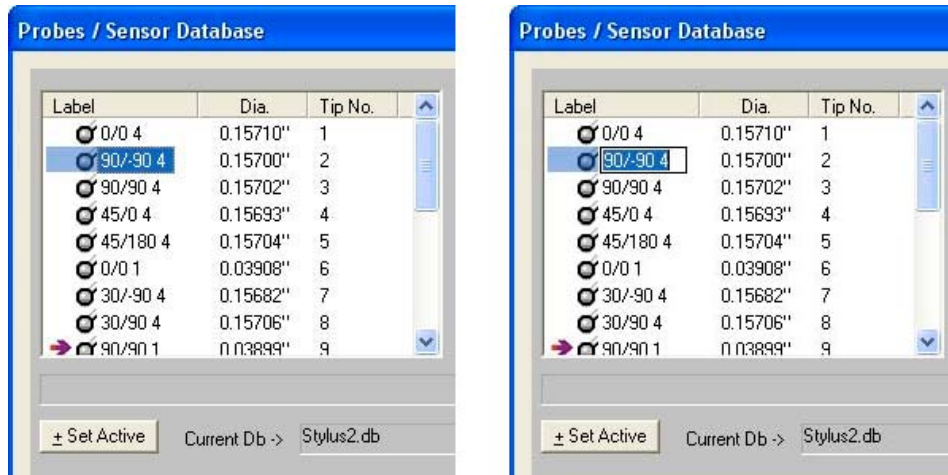


To see an example on the importance of this command, see Re-Qualify a Stylus.

# Chapter 3 – Stylus Management

## Labeling Stylus

Labeling an individual stylus is helpful in identifying its unique characteristics. In Geomet Junior, when a new stylus is qualified, and by default, is given the next available tip number. This is not very helpful in describing the characteristic of the stylus. For example, the tip may be the "left tip" on a stylus cluster.



To attach a label on a single stylus, two methods can be employed. The first involves the standard Windows interface where you highlight the desired tip by left clicking once on the stylus under the Label column header. Then pause and left-click on the stylus again, Windows acknowledges the second left-click, and an edit box surrounds the current label and you can type directly into the Stylus Manager list.

Should Windows not provide the edit label tool, you can activate the edit label tool by selecting the stylus as described above and press the "l" <lowercase L> key on the keyboard. This will start the edit process for that selected stylus. To complete the labeling processes, press the <Enter> key on the keyboard, or highlight another stylus.

# Chapter 3 – Stylus Management

## Basic Ball Style Electronic Touch Probe

This Qualification process is based on the hardware configuration consisting of a ball stylus touch probe on an electronic probe head. This configuration is similar to a Renishaw TP-ES or a PH1 with a TP2 probe body.



### Step 1

To start the qualification process, activate the stylus manager by pressing the "w" key on the keyboard or the [Qualify->Stylus Manager] from the drop down menus. To add a new stylus qualification, press the <Next> button found on the Stylus Manager. Note: For more efficient operations, the <Next> button is also activated by pressing the <Enter> key on the keyboard.

### Step 2

This step will prompt you to enter the qualification type. This describes the type of stylus attached to your system. The choices are ball, taper, cylinder, video cross hair and manually entered diameter. By default the qualification type will show "Ball". To continue the qualification process, press the <Next> button on this dialog or press the <Enter> key on the keyboard.

### Step 3

The final step will prompt you to proceed capturing the data points required to solve the qualification of the stylus.

We are prompted to capture the current default number of data points required. At this time, capture the data points on the reference sphere and the count required would descend until all data points have been captured.

The process used to capture the data points will influence the quality of the solution. If you were to capture your data points close together, or with inconsistent speed, there can be error introduced in the end result of size and location, so try to capture points spread evenly around the calibration sphere with consistent probing speed.

## Chapter 3 – Stylus Management

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We recommend that when using 5 data points, the first point should be taken on the top of the reference sphere and the remaining 4 taken at the equator.

Should you require to abort a single data point that has been captured, press the <F2> key on the keyboard and the required count of data points will increase as it discards the last data point in the buffer.

### Qualifying Ball Styli in Multiple Positions

---

This Qualification example is based on the hardware configuration consisting of a ball stylus touch probe in different locations attached to one or more electronic touch probes. One example would be a manual articulating electronic probe head such as the Renishaw MIP. Another example would be a Cluster probe located on an electronic probe with multiple ball styli installed.

The process of qualifying more than one physical location involves the same steps as described above in Basic Ball Style Electronic Touch Probe. The first probe should be qualified exactly as stated in steps 1-3. When the first probe has been qualified, you will return to the main screen of the Stylus Manager. To add another position on a cluster, or another location on an articulating probe, follow steps 1-3 described above.

Geomet Junior will qualify the MCS location and size and assign the next stylus tip number to the stylus database. The location it stores is the XYZ variation from stylus tip number 1.

#### NOTE on Reference Sphere Location

*On DCC style CMMs there is a "Home" position which is repeatable for inspection results. The MCS origin is the Home position of the CMM. This allows adding additional stylus positions to the current stylus database without loss of position.*

*On manual CMMs that do not offer a Home procedure, the origin of the MCS is the location the CMM was at the time of power up, or the location when Geomet Junior was launched. Therefore the origin position of the MCS is not reliable or repeatable. When you qualify multiple positions, all qualifications should be done during one session to ensure correct relationships between all the stylus centers. Should you have to add positions after a system restart, you should always clear your stylus database and add all positions required for your inspection..*



# Chapter 3 – Stylus Management

## Entering a Known Diameter

The Stylus Manager provides a process where you can enter the known size of the stylus manually. This is often done when using hard probes or when you desire to enter a specified diameter.

Caution should be taken when entering the size manually. The ball center location is not established and therefore can not be used with other qualified styli in the same coordinate system.

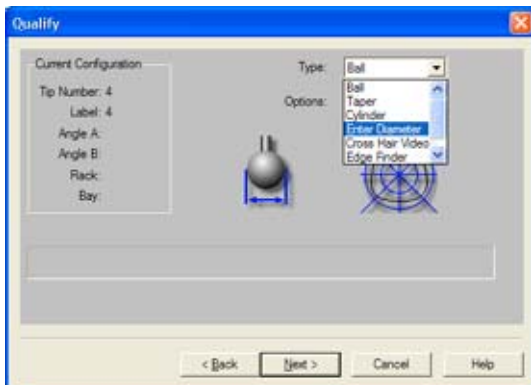
A manually entered diameter will not equal the reported diameter of the same stylus when qualified against the reference sphere. This condition is a result of the touch probe pre-travel distance. When an electronic touch probe comes in contact with the reference sphere, it must travel a small distance after contact until the trigger is activated. This results in a smaller diameter than one measured with a micrometer.

### Step 1

To start the qualification process, activate the stylus manager by pressing the "w" key on the keyboard or the [Qualify->Stylus Manager] from the drop down menus. To add a new stylus qualification, press the <Next> button found on the Stylus Manager.

### Step 2

On the Qualification Type page choose "Entered" from the drop down list. Press <Next> to proceed.



### Step 3

On the final page, enter the known diameter size in the space provided.

# Chapter 3 – Stylus Management

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## Stylus Multiple Tip Relationships

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To ensure accurate and repeatable inspections, it is important to understand the relationship between qualified stylus positions when you require more than one in your inspection.

In your Stylus Database, the first stylus qualified is considered the primary or reference position for all qualified styli. The first qualification will record the center location in the MCS of the Reference Sphere and assign it to tip number 1.

All subsequent qualifications will record the deviation to the primary tip. This allows Geomet Junior to use multiple styli in a single coordinate system without a shift in position. Geomet Junior also allows the use of multiple styli when measuring a single feature such as a cylinder.

Therefore certain conditions must be met to allow safe requalifications and modifications to the Stylus Database. The first rule is that any stylus can be deleted, except stylus tip number 1. Should you delete stylus tip number 1, then all styli should be removed and qualified again.

### Re-Qualify a Stylus

Re-Qualifying a stylus updates the current stylus with a new size and MCS location. Re-Qualification has two main functions, to validate the current size and location of your qualified stylus, or to reposition the current stylus during the inspection process using a manual indexing friction probe.

The use of the Re-Qualify command as a validation tool is useful when it is necessary to perform checks on your stylus database. These validation tests would look for damaged probes, worn stylus balls, movement of stylus clusters or any other abnormal conditions that can adversely affect your inspection results. You may want to create a Re-Qualify Stylus part program which will report and update changes in size and location of the stylus.

Re-Qualifying during the inspection process can be used to extend the usefulness of a friction style articulating probe head such as the Renishaw PH1 or PH8.

The Re-Qualification process can be done manually on a single stylus, or as part of a motion program which can automatically update the size and MCS location of all attached styli.

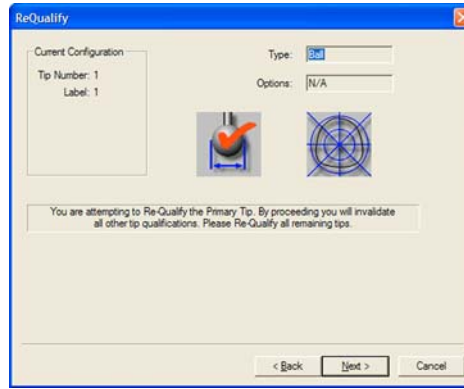
***NOTE: In Geomet Junior, the following dialogs associated with Geomet Junior Plus will not appear. When you request a Re-Qualify, you will be prompted to capture the required number of data points.***

## Chapter 3 – Stylus Management

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### Re-Qualifying an existing Stylus

When you start the Re-Qualification process, the first step will show you the previous stylus definitions, see figure below.



For example, if stylus number 2 was a ball style when created, this step will show "Ball" in the Type control and you will not be allowed to change it. Press the <Next> button to proceed to the next operation.

The final step will prompt you to capture the data points required. Once this step has been completed, the Stylus Database will be updated with the latest size and MCS location for the selected stylus.

### Stylus Relationships

Stylus number 1 is considered the origin position for the entire stylus database. The relationship between any stylus and stylus 1 is the MCS offset value in XYZ values. This offset is applied in calculations when measuring features. By knowing this offset value, Geomet Junior can measure a single feature with multiple probe tip locations.

Therefore, when Re-Qualifying stylus number 1, all other stylus in the database will be marked as "Pre-Qual". Each stylus tip will have to be Re-Qualified before it can be eligible for use in measuring.

## Chapter 3 – Stylus Management

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### Example Re-qualify Stylus Tips for Friction Probe Heads

One limitation of using a friction style probe head is that you can not return to the same articulated position with any degree of accuracy. Geomet Junior allows the various positions of the probe head to be used in the part program without establishing new coordinate systems for every qualified stylus. This can be accomplished by following these basic steps.

Assuming we are starting with no current stylus qualified, we will qualify the first position for your inspection using the Stylus Manager as defined in Qualifying a Stylus above. This will become Stylus Number 1 in your Probe and Sensor Database.

Do not move the stylus, but qualify it again at the same location which becomes Stylus Number 2. You can also use the Duplicate Stylus command to create Stylus Number 2.

Start your inspection with Stylus Number 2 as the active stylus. Do not start your inspection with Stylus Number 1. Proceed measuring features until it is required to articulate the probe position. Reposition the probe and perform a Re-Qualify, <Ctrl + w>, on the current stylus number 2. You will be prompted to capture data points on the reference sphere. Once this operation has been completed, you can return to inspecting new features without any loss of position. This re-qualify step becomes part of your part inspection and during a program run, you will be prompted automatically.

This can be done to Stylus Number 2 as many times as required to satisfy your inspection needs. Since Stylus Number 1 was not changed, all styli starting with number 2 and beyond can be used and re-qualified many times.

***Should you have moved Stylus Number 1 and performed a Re-Qualify on it, all known locations would have moved. This includes established Part Coordinate Systems. The Stylus Database retains the reference sphere location in the MCS based on stylus number 1. All Part Coordinate Systems also are referenced to the MCS. Moving stylus number 1 will cause PCSs to move.***

Note: This process can also be used when it is necessary to change styli on the probe head. For example, you are required to install a stylus with an extension, or install a small diameter stylus for use on selected features in your inspection.

***TIP: When you want to rotate the probe head, or change the stylus to another size, press the space bar which will "Disable" the probe preventing data points from entering Geomet Junior. When you have completed the change, press the space bar again and your probe will enable.***

## Chapter 3 – Stylus Management

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### **Cautions:**

Care should be taken when performing a Re-Qualification using a manual CMM. The qualification process relies on the XYZ offset from the CMM Home position for location of the reference sphere. That position is assigned to stylus number 1.

When you qualify the first stylus, Geomet Junior retains the location based on the center of the reference sphere in the Machine Coordinate System (MCS). The MCS has an origin point (X=0.0, Y=0.0, Z=0.0) that has been established either with the power on position for manual CMMs or the Home position for DCC CMMs. It is possible to have an established Home position on some manual CMMs that have the Home option installed.

Additionally, Re-Qualification assumes the reference sphere has not been moved. If the reference sphere has been moved, the Geomet Junior function [Recover→Ref Sphere] should be done.

### **Re-Qualify Example**

On the Geomet web site, you can find an example of a Re-Qualify program for use on DCC style coordinate measuring machines. This help can be found at:

<http://www.geomet-cmm-software.com/KB/Chapter4/KB10043.htm>

## Chapter 3 – Stylus Management

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# Chapter 4 – Feature Measurement

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## Chapter 4 – Feature Measurement

### Basic Features

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# Chapter 4 – Feature Measurement

## Point

Points are dimensionless locations in 3D space. Points have no size. The location of a point is specified by its X, Y, and Z coordinates in a defined coordinate system. There are many point types that Geomet Junior supports. These include 1D, 2D and 3D points.

Measured points consist of 1D, 2D and 3D style geometric elements. Keyboard access to these points is done through the number keypad, *see table below*.

Keystroke	1D Point	2D Point	3D Point
1	-Z		
2	-Y		
3 + 2		XY IR	
3 + 4		ZX IR	
3 + 6		YZ IR	
3 + 9			3D IR
4	-X		
5 + 2		XY	
5 + 4		ZX	
5 + 6		YZ	
5 + 9			3D
6	+X		
7 + 2		XY OR	
7 + 4		ZX OR	
7 + 6		YZ OR	
7 + 9			3D OR
8	+Z		
9	+Y		
IR = Inside Radius / OR = Outside Radius			
<i>Table 1, Keyboard Access</i>			

# Chapter 4 – Feature Measurement

## 1D Point

1D Points report 1D locations. There are six 1D point routines, designated  $\pm X$ ,  $\pm Y$  and  $\pm Z$  PCS directions. Pressing one of assigned keys, *see previous table*, prepares Geomet Junior to measure a single point on a planar surface. The report consists of the location of the center of the stylus corrected by the stylus radius in the PCS probing direction. Problems arise if the planar surface is not parallel to a PCS base plane.



The illustrations above demonstrate a 1D-point measurement using the same planar surface on the GeoWidget using two alignments. One based upon the MCS and then referencing PCS 2. Although the stylus center is at the same XYZ location in both cases, the calculated points P1 and P2 are quite different. P1 was measured as a +X 1D Point and is calculated based on the probe radius correction parallel to the X-axis of the MCS. P2 resulted from a probe radius correction parallel to the Y-axis of PCS 2. This illustrates how measurements of a surface in an unaligned PCS can produce erroneous results.

Single 1D Point measurements can only be used to determine the locations of planar surfaces, which are **parallel** to the PCS base planes. Pairs of 1D Point measurements on planar surfaces that are parallel to PCS base planes may serve to determine the Distance between the surfaces or the location of the Bisector of surfaces. Pairs of 1D Point measurements on simply skewed planar surfaces, meaningless in themselves, may be used to define a Line on a surface or to Align the current PCS to be parallel to the surface.

To measure a 1D Point, press the corresponding Point direction key and gather a data point on your work piece. If you have Auto-Direction enabled, you will be prompted "Measure Auto-Dir Point" and your approach vector to the work piece will identify the probing direction.

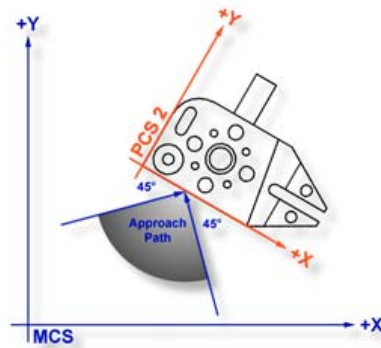
Tolerancing of 1D Points is limited to Cartesian / Linear.

1D Points are available for use in building Part Coordinate Systems. Single 1D points can establish the origin for a single PCS axis. For example: a +X Point can establish the X axis origin. Two coplanar 1D Points can establish an alignment.

## Chapter 4 – Feature Measurement

### Auto Direction Sensing and 1D Points

Using auto direction on 1D Points can lead to erroneous reported values if used incorrectly. Auto direction relies on a smooth approach, from you the operator, in capturing of a data point. The process of determining the approach vector involves the CMM interface card (ProCounter, Tech 80 or PMAC) to maintain a rolling IJK vector based on the last five reported values. These interface cards update the current position in the MCS on a programmable time interval from 20 to 200 milliseconds.



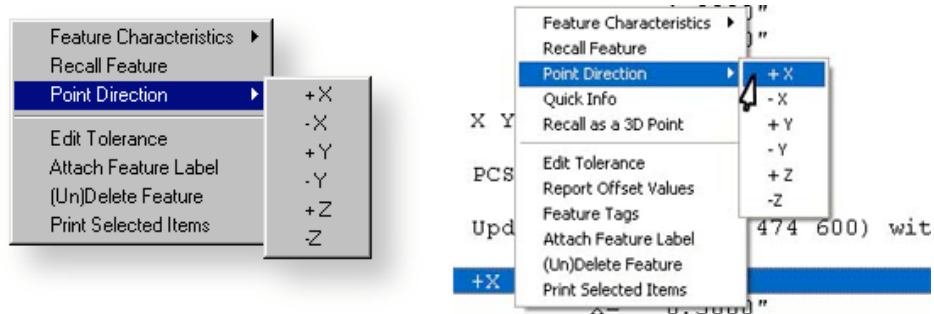
Auto Direction Approach Vector

When you are approaching your work piece, it is required that you make contact while remaining in a  $\pm 45^\circ$  approach, *see figure above*. In this example, if we remained in the approach zone we will capture a data point that will be reported as a +Y point. If the operator did not remain in the approach zone the 1D Point might report a + or - X Point from which we will have to correct the probe compensation error. Most common occurrence of a erroneous data point comes from operators who approach the surface, and then pause during the approach and attempt to make contact under extremely slow speeds, which while approaching causes variations in the path toward the surface.

To correct the reported direction of a 1D Point, highlight the feature by left clicking on it, then right-click to bring up the feature menu, as shown in the figure on the next page. Select [Point Direction], which will offer a sub-menu with all six probing directions available. Choose the correct 1D Point direction and your part inspection will update with the correct 1D Point.

*Note: Once a feature has been referenced it can not be changed or edited. For example, if a feature was used in the construction of a PCS, it will be locked from changes. This is identified by the inclusion of a ' next to the feature number, example " 12' ".*

# Chapter 4 – Feature Measurement



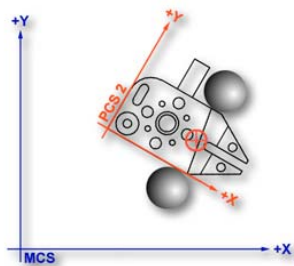
1D Point Correction Sub-menu (both styles shown)

Using Auto-Direction with multi-point features such as circle, lines and planes can also incorrectly report feature characteristics. This occurs when capturing data points in an inconsistent method or by capturing data points at a high rate. As previously mentioned, the calculation of the direction vector for the probe works off the speed of the interface and should that rate of point capture be too high, the changes in direction going toward, then backing off the data point will create a poor direction vector.

Since touch probes can be effected by speed and our auto-direction tool is also adversely effected by speed, we suggest the use of a smooth consistent approach speed and rate when capturing data points.

## 2D Point

The 2D Point function is normally used in conjunction with a hard taper probe for simple contact determination of the location of bores whose axes are parallel to the PCS Z axis. It can also be used with hard ball stylus for single contact determination of the location of bores whose axes are parallel to any PCS axis. In these applications the 2D Point feature is referred to as the self-centering routine.



2D Bisect Point Application

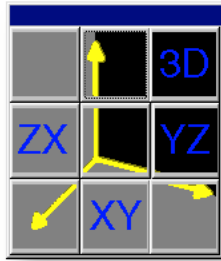
The 2D Point feature can also be used with hard or electronic trigger ball stylus to create 2D Bisector Point features in slots or a web for Aligning purposes as shown in PCS Example #6. All 2D Points are automatically projected into the requested PCS base planes. The example shown in figure, demonstrates the use of 2 - 2D Points on the outside of the GeoWidget bisected to obtain a 2D Point on the centerline of the body.

## Chapter 4 – Feature Measurement

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Measured features that create a 2D point entity include the 4 Point Intersect, Slot / Web and Oval Slot Macro Features.

To measure a 2D Point press the 2D Point key, < 5 > from the number pad. Geomet Junior will prompt you for a PCS base plane the 2D Point will project into, *see figure below*. Choose XY, YZ or ZX and begin your measurement.



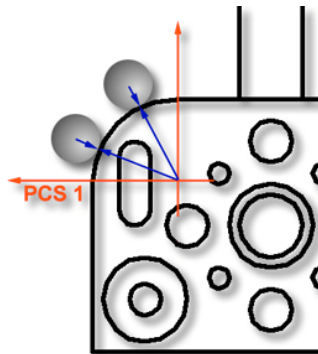
*2D Point Projection Plane Selector*

Tolerancing of 2D Points is available in Cartesian, Polar or RFS Positional Tolerance formats.

### **Inside Radial / Outside Radial 2D Points**

---

The IR (Inside Radial) and OR (Outside Radial) Point features allow 2D ball radius compensated probing of cylindrical surfaces. The probe vector is determined as a vector from the current PCS origin through the ball center of the stylus. Adding one radius along this vector compensates inside Radial features. Outside Radial subtracts one probe radius.



*Outside Radial 2D Point*

An IR / OR measurement is ideal for measuring extremely large radial surfaces that only offer a small segment to capture data points on. Translate your PCS origin to the center of the radial feature and capture radial points along the surface.

# Chapter 4 – Feature Measurement

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## 3D Points

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The 3D Point feature reports the current PCS location of the center of the ball stylus used in the measurement. It is useful in conjunction with a hard ball stylus to establish a point on the axis of an ID cone. An example is to establish the centerline of a turned part using two 3D Points, one at each end in the conical shaped turned datum used by the head and tail stock made with a center drill.

To measure 3D Point Features, press the 3D Point key, < 5 > + <9> from the number pad and begin your measurement.

## Inside Radial / Outside Radial 3D Points

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The IR (Inside Radial) and OR (Outside Radial) Point feature allow 3D ball radius compensated probing of spherical surfaces. The probe vector is determined as a vector from the current PCS origin through the ball center of the stylus. Adding one radius along this vector compensates inside Radial features. Outside Radial subtracts one probe radius.

These features are ideal for measuring extremely large spherical surfaces that only offer a small segment to capture data points on. Translate your PCS origin to the centroid of the feature and capture radial points along the surface.

Tolerancing of 3D Points is available in Cartesian, Polar or RFS Positional Tolerance formats.

# Chapter 4 – Feature Measurement







## Multi-Point Features in Geomet Junior

All multi-point features in Geomet Junior can be measured or constructed with more than the default number of data points. Those defaults can be set in:

*[System ⇒ System Options ⇒ Feature Characteristics]*

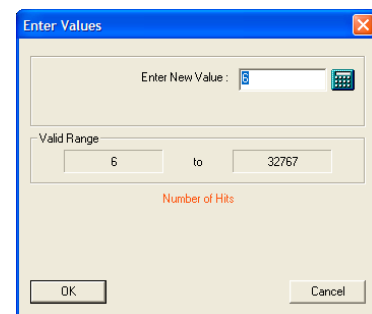
The defaults set by Geomet Junior are only minimum suggestions to solve the requested feature. To obtain additional information, such as form, always add additional data points.

The table below shows the corresponding keystroke, icon and menu access for each feature.

Feature Type	Icon	Keyboard	Menu	Suggested Minimum Data Points
Line		m	<i>[Measure ⇒ Line]</i>	2
Circle		z	<i>[Measure ⇒ Circle]</i>	4
Plane		b	<i>[Measure ⇒ Plane]</i>	4
Cylinder		c	<i>[Measure ⇒ Cylinder]</i>	6
Cone		n	<i>[Measure ⇒ Cone]</i>	7
Sphere		v	<i>[Measure ⇒ Sphere]</i>	5

To request additional data points during the inspection, press the <shift> key when selecting your feature. For a circle use <shift + Z> and you will be prompted to enter the data point count required.

You can also increase the data point count by pressing the feature key repeatedly. For example if you are measuring a Circle and would like to add two more data points, just press the <z> key twice and the required count will increase. This can be done even when data points have already been captured. To terminate and solve a feature before capturing all data points, press the Terminate key, <F5>.



# Chapter 4 – Feature Measurement

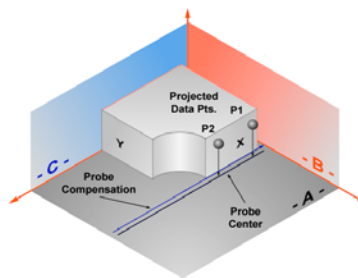
## Line

Keyboard: m

Menu: Measure ⇒ Line

A line is the trail left by a point that moves in a constant direction. Lines are infinitely long and have no width. A point somewhere along its length and a direction characterizes a line. In Geomet Junior a line is reported as a pierce point with a PCS base plane and two or three base plane projection angles. A 2D Line is reported as the point where it intersects with a PCS axis. A 3D Line is reported as the 2D Intersection with a PCS base plane.

The Line feature provides you with the means to measure multi-point 2D Lines. 2D lines are projected into a PCS base plane and report the angular deviation in the current PCS base plane and a 1D pierce value of a PCS base axes, *see figure below*. The line feature is multi-point consisting of 2 - 32767 data points.



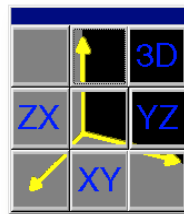
Line projected into the PCS

### Measure a Line

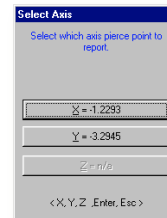
When starting the line tool <m>, you will be presented with a direction selector dialog if Auto-Direction is turned off. The direction selection allows you to choose the probing direction suited for the line to be measured.



Direction Selector



Projection Plane



Pierce Axis

After you select the probing direction, Geomet Junior will prompt you to "Measure an -X Line", for example. Should Auto-Direction be turned on, Geomet Junior will display "Measure a Auto-Line". Proceed to capture the required number of data points.



## Chapter 4 – Feature Measurement

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The determination of the PCS base plane is supplied by the operator after the capturing of the data points. Depending on the angle of the line, Geomet Junior will prompt for the selection of a PCS axis to report. Geomet Junior uses an angle of  $\pm 10^\circ$  between the line normal to a PCS axis to determine if the operator should be prompted to select the pierce axis.

For example, if a line being measured crosses the PCS X axis at 1.000" and has a reported angle of  $85^\circ$ , the operator will not be prompted to select a PCS axis. Should the same line have a reported angle of  $75^\circ$ , then Geomet Junior would prompt the operator to select the pierce axis showing the solutions of both values as shown in Pierce Axis figure on the previous page.

After completing the first measured line, Geomet Junior auto-cycles preparing to measure another line. Note: after the first measure line is completed, Geomet Junior will not prompt you for a projection plane. It is assumed that you will continue measuring lines in the original selected plane. Should you require a new projection plane, press <Esc> and select the line tool again.

The direction of the line is determined by the direction of the data points, from the first data point to the second. In our example, the order the data points were captured created a reported angle of  $-90^\circ$  whereas should the order have been reversed, the reported angle would be  $+90^\circ$ . NOTE: see Switching the Reported Angle Directions below. This is important when applying a tolerance value to the angular component.

During the capturing of the data points, should you want to change the requested number of data points you can press the line key repeatedly and the count will increase by one with every depress without losing data points already captured.

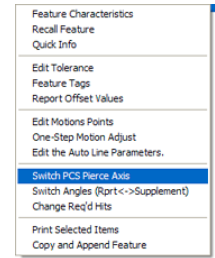
If you have already captured sufficient data points to satisfy the line press <f5>, Terminate, to solve the line without having to capture the remaining prompted data points.

Tolerancing of Lines is available in Cartesian / Linear format.

# Chapter 4 – Feature Measurement

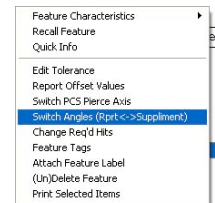
## Switching of the Reported Pierce Axis

To switch the reported pierce axis of an already measured or constructed line, highlight the line in the report area and right-click. A sub menu will appear where you can choose *[Switch PCS Pierce Axis]*. The option is available only when the line has not been used as a PCS component and does not have a reference lock attached to it.



## Switching the Reported Angle Directions

As mentioned previously, the order the data points were taken in will configure which angle will be reported. If you want to switch the supplement angle with the normal reported angle, there exists an option flag that can be set.



To switch the angles, highlight the line feature in the report section by left clicking on it. Once the feature is highlighted, right-click to bring up the sub-menu. Choose *[Switch Angles....]*. The report will update and reflect the switch has been applied. To change it back, toggle the switch again by selecting *[Switch Angles....]* again.

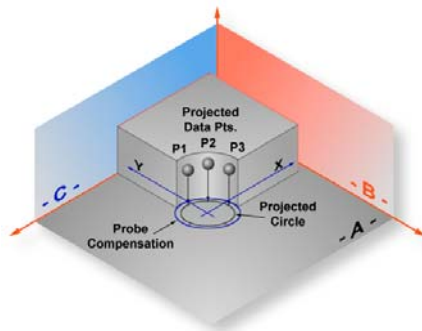
# Chapter 4 – Feature Measurement

## Circle

Keyboard: z

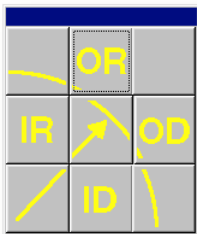
Menu: Measure ⇒ Circle

The Circle feature reports the center location and diameter or radius of bores and bosses whose axes are parallel to a PCS axis. The circle feature will give erroneous results on skewed bores and bosses. Circle center locations are projected into a PCS base plane and are 2D in nature.

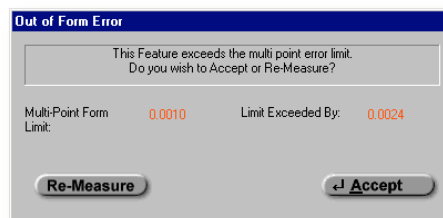


Circle projected into the PCS

To measure bores or bosses, press the Circle key < z > for the default number of data points as set in System Options. Geomet Junior will then prompt you for the type of feature being measured, ID, OD, IR or OR. If you have Auto Direction enabled, this prompt will not appear.



Inside/Outside Selector



Out-of-Form Warning

If you required additional data points, you can repeatedly press the Circle key which increments the required number by one, or press < shift > + < Z > and you will be prompted to enter the required number.

Geomet Junior performs a form validation on your captured data points. This function is called the Multi-Point Error Limit and is controlled by a setting in System Options. In the event your circle exceeds this limit, Geomet Junior will prompt you to accept or re-measure the feature. If you elect < Re-Measure >, you will be prompted to capture new data points for the same feature. Note: *The*

# Chapter 4 – Feature Measurement

*Multi-Point Error Limit test is only performed in the self-teach mode, not during a part program run.*

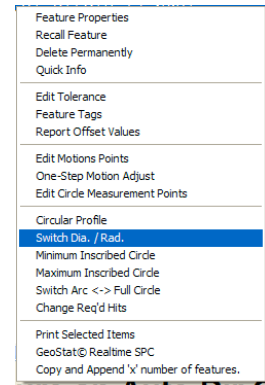
Data points used to calculate a circle if not spread around the circle can cause erroneous results. In the table below, we will use a 3 point circle with one point .00014" off the nominal value for a 1.00" radius. The results are calculated to show the error that is part of the reported values.

Arc(Degrees)	Center Error	Radius Error
180	0.00014	0.00000
120	0.00028	0.00014
90	0.00048	0.00034
60	0.00104	0.00090
30	0.00409	0.00395
20	0.00914	0.00899
10	0.03549	0.03535
5	0.12823	0.12810
<i>Circle Deviations</i>		

Tolerancing of Circles is available in Cartesian, Polar or RFS, MMC and LMC Positional Tolerance formats.

## Switching between Radius and Diameter

Changing the reported characteristics of a previously measured or constructed feature can be done directly on the report. Select the circle feature in the report area and right click to activate the feature sub menu. From the available commands select [*Switch Dia. / Rad.*].



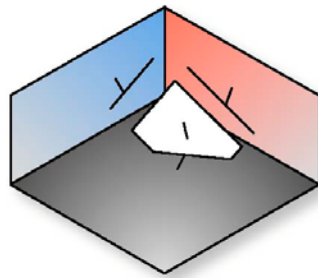
# Chapter 4 – Feature Measurement

## Plane

Keyboard: b

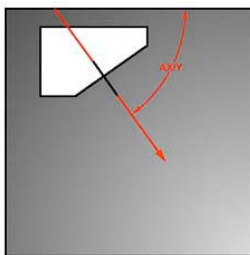
Menu: Measure ⇒ Plane

Planes have locations, attitudes and directions. The location of a plane is defined as the point at which it is pierced by a PCS axis. The attitude of a plane is defined by the projection angle  $AX/Y$ ,  $AY/Z$  and  $AZ/X$  of the plane normal in each of the three PCS base planes, with range values from  $0^\circ$  to  $\pm 180^\circ$ .

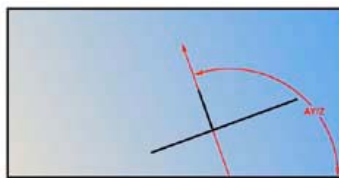


*Plane represented in the current PCS*

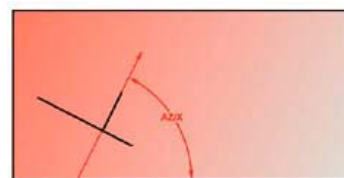
The Plane feature may be used to measure non-skewed planes. The printed pierce point of a measured plane is determined by the PCS axis that is most parallel to the normal of the measured plane. Planes which are essentially parallel to PCS base planes have only two attitude angles which are meaningful, the third is printed in lower case, as for example "ax/y" to indicate its reduced significance.



*AX/Y Projection*



*AY/Z Projection*



*AZ/X Projection*

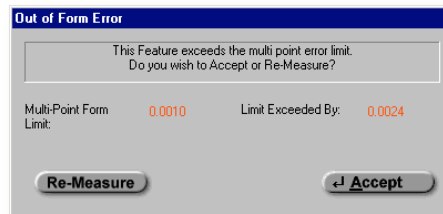
The vector normal defines the direction of a plane. The first figure above shows a plane with its projection into each PCS base plane. The normal, when projected into each PCS base plane provides the attitude in angles, *see example above*.

## Chapter 4 – Feature Measurement

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*Probe Direction Selector*



*Out-of-Form Warning*

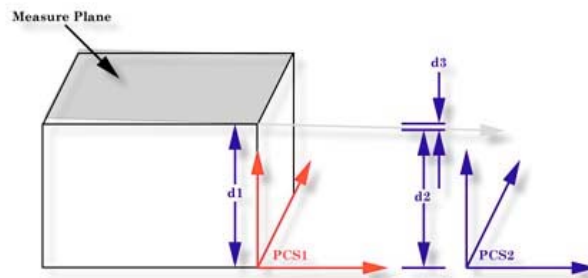
To measure Planes press the Plane key <b> for the default number of hits as established in System Options, or < shift> + < B > for a multi-point plane. If you required additional data points even during point capture, you can repeatedly press the Plane key which increments the required number by one. If auto-direction is not enabled, you will be prompted to enter the probing direction. Upon completion of gathering your required number of data points, Geomet Junior will test the form error of the newly calculated plane. If the form error exceeds the default setting, you will be prompted to < Accept > or < Re-Measure > the plane.

# Chapter 4 – Feature Measurement

## Pierce Point Reporting

It is important that your PCS be established close to the desired location where the distance should be taken. As shown in figure below, should the PCS be outside the effective location the distance is expected, the reported result will not represent the actual distance.

Referring to figure below, we have two established Part Coordinate Systems. PCS 1, established on the base of the 2.000" gage block. PCS 2 is located 4.000" inches in the X direction from the right side of the gage block.



Two planes were measured, one representing the lower base and one on top of the gage block, The lower base plane was used to establish the XY PCS Base Plane for both PCS 1 and 2. The top plane had an AZ/X of 89.9943° and the AY/Z was 90.0000°. The intersection of the pierce point with the PCS1 Z-Axis, **d1**, is reported at 1.9999". The reported pierce point on the Z-axis of PCS2, **d2** is 1.9995". By not having PCS localized to the actual measured surfaces we introduced 0.0004", **d3**, error!

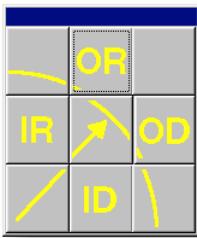
# Chapter 4 – Feature Measurement

## Sphere

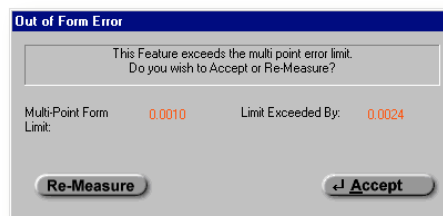
Keyboard: v

Menu: Measure ⇒ Sphere

A sphere is the trail left by a point traveling in every conceivable direction at a constant distance from another point called its center. A sphere is also the surface generated by a rotating circle about a coplanar axis through its center. The sphere is characterized by its size as a Radius or Diameter and a three dimensional center location.



*Inside/Outside Selector*



*Out-of-Form Warning*

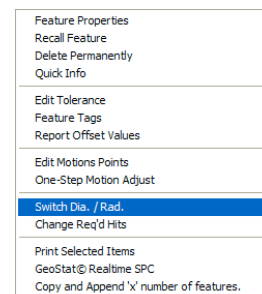
To measure a sphere, press the < v > key for the default number of data points as established in System Options, or < shift > + < V > for a multi-point sphere.

If auto-direction is not enabled, Geomet Junior will prompt you for the characteristic of the sphere, ID, OD, IR or OR. After the data points have been captured, Geomet Junior will test the form error and if exceed, will prompt you to < Accept > or < Re-Meas >.

Tolerancing of Spheres is available in Cartesian / Linear format.

### Switching between Radius and Diameter

Changing the reported characteristics of a previously measured or constructed feature can be done directly on the report. Select the sphere feature in the report area and right click to activate the feature sub menu. From the available commands select [*Switch Dia. / Rad.*].





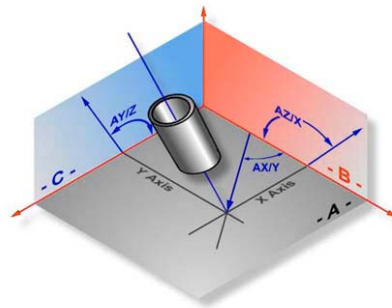
# Chapter 4 – Feature Measurement

## Cylinder

Keyboard: c, Shift + C

Menu: Measure ⇒ Cylinder

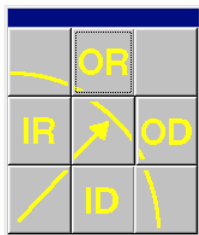
A cylinder is the trail left by a line, which revolves around and at a constant distance away from a parallel line called its axis. A cylinder is characterized by a point and direction of its axis and by its diameter or radius.



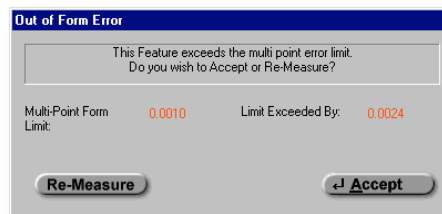
*Cylinder Projection in the current PCS*

The cylinder feature determines the size, PCS pierce point and attitude of the axis of bores and shafts. The attitude of a cylinder axis is expressed like the attitude of the normal of a plane, using the characteristic identifiers AX/Y, AY/Z and AZ/X. These angles can vary between  $0^\circ$  and  $\pm 180^\circ$ . The axis of a cylinder has a direction as well as an attitude: its direction is from a group of points measured near its bottom toward a group of points measured near its top.

The reporting of the position in the PCS is the point where the axis of the cylinder intersects a PCS base plane, called its pierce point. Geomet Junior determines which PCS base plane to report by determining which PCS base plane the axis of the cylinder is most normal to.



*Inside/Outside Selector*



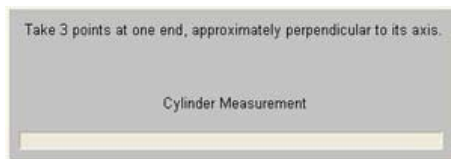
*Out-of-Form Warning*

To measure bores or bosses press the Cylinder key <c> for the default number of data points as established in System Options, or <shift> + < C > for a multi-point cylinder.

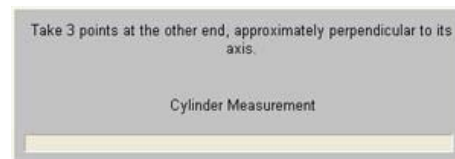
# Chapter 4 – Feature Measurement

If auto-direction is not enabled, Geomet Junior will prompt you for the type of cylinder, ID, OD IR or OR.

Collect the first 3 data points at or near the "bottom" of the bore or boss. Collect the last 3 data points at or near the "top". Should you require more than 6 data points, the data points captured after first 3 and before the last 3 can be captured anywhere on the bore or boss.



*Collect the First 3 Data Points*



*Collect the Last 3 Data Points*

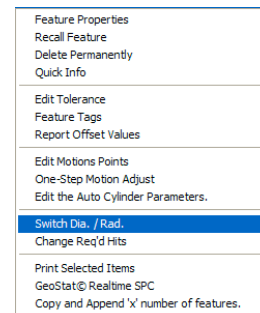
The order in which these two 3 point end groups are collected determines the direction of the axis of the cylinder. After the data points have been captured, Geomet Junior will test the form error and if exceeded, will prompt you to < Accept > or < Re-Meas >.

The order in which these two 3 point end groups are collected determines the direction of the axis of the cylinder. After the data points have been captured, Geomet Junior will test the form error and if exceeded, will prompt you to < Accept > or < Re-Meas >.

Tolerancing of Cylinders is available in Cartesian, Polar or RFS, MMC and LMC Positional Tolerance formats.

## Switching between Radius and Diameter

Changing the reported characteristics of a previously measured or constructed feature can be done directly on the report. Select the cylinder feature in the report area and right click to activate the feature sub menu. From the available commands select [*Switch Dia. / Rad.*].



# Chapter 4 – Feature Measurement

## Cone

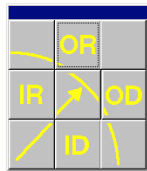
Keyboard: n, Shift + N

Menu: Measure ⇒ Cone

A cone is the trail left by a line which rotates about another non-parallel and non-perpendicular, intersecting line called its axis. The intersection of the two lines is called the apex. The cone is characterized by a point on its axis (PCS base plane pierce point), the direction of its axis, its apex, its included angle and its radius at the pierce point.

The attitude of a cone axis is expressed like the attitude of the normal of a plane, using the characteristic identifiers AX/Y, AY/Z and AZ/X. These angles can vary between  $0^\circ$  and  $\pm 180^\circ$ . The axis of a cone has a direction as well as an attitude: its direction is from a group of points measured near its bottom toward a group of points measured near its top.

To measure a Cone, press the < n > key for the default number of data points as established in System Options, or < shift > + < N > for a multi-point cone. If auto-direction is not enabled, Geomet Junior will prompt you for the type of cone as either a ID, OD IR or OR.

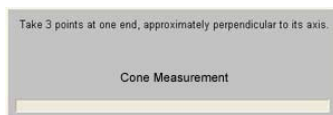


*Inside/Outside Selector*

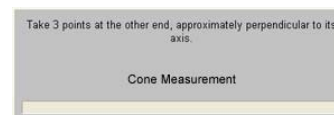


*Out-of-Form Warning*

Collect the first 3 data points at or near the "bottom" of the cone. Collect the last 3 data points at or near the "top". Should you require more than 7 data points, the data points captured after first 3 and before the last 3 can be captured anywhere on the cone.



*Collect the First 3 Data Points*



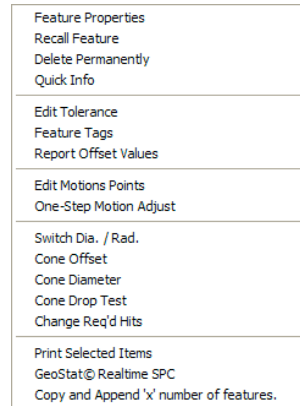
*Collect the Last 3 Data Points*

The axis of a cone has a direction as well as an attitude: its direction is from the group of points measured near its bottom toward the group of points measured near its top. After the data points have been captured, Geomet Junior will test the form error and if exceeded, will prompt you to < Accept > or < Re-Meas >.

# Chapter 4 – Feature Measurement

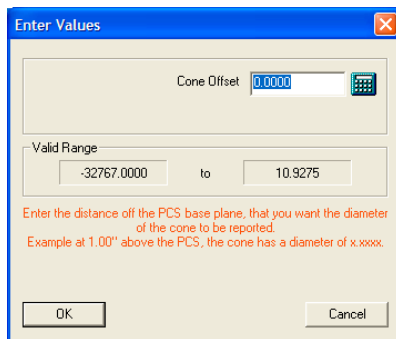
## Switching between Radius and Diameter

Changing the reported characteristics of a previously measured or constructed feature can be done directly on the report. Select the cone feature in the report area and right click to activate the feature sub menu. From the available commands select [*Switch Dia. / Rad.*].



## Cone Offset

The Cone Offset command produces a reported diameter at a specified distance from the PCS Base Plane. For example, what would the diameter on the cone at  $-0.250''$  below the PCS? To obtain the value, highlight the cone in the report and right click to activate the sub menu, choose [*Cone Offset*].



*Cone Offset Setup Tool*

Enter  $-0.250$  in the Cone Offset Setup Tool and select <Ok>. The Offset Tool will provide a range of available values. This starts at the apex of the cone. The reported cone diameter is the solution of a parallel plane intersecting the cone at the specified offset.

```
25: ID XY Cone [7 pts]
    ID= 1.1417"
    Incl Ang= 89.9971
    Cone Taper= 11.9994" IN / FT
    Pierce Point
        X= 0.0000"
        Y= -0.0003"
    Attitude
    Ax/y Angle = -41.6512
    AY/Z Angle = -90.0040
    AZ/X Angle = -89.9956

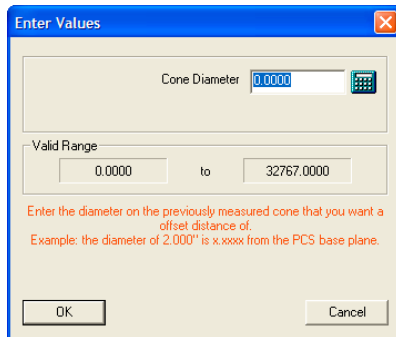
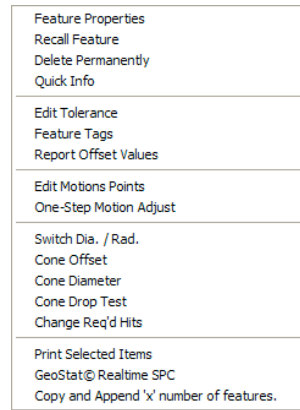
26 ID XY Cone (RCL 25) [7 pts]
    ID= 0.6417"
    @ Offset= -0.2500
```

*Reported results from a Cone Offset*

# Chapter 4 – Feature Measurement

## Cone Diameter

Another very powerful feature of the available Cone analysis tools is the ability to locate the height off the PCS Base Plane that a specified diameter exists at. For example if measuring a cone that defines the seating surface of a valve and the dimensional requirement is to measure the height where the cone has a diameter of 3.500". First we measure the cone the right click on the cone to activate the sub menu. From the commands, choose [*Cone Diameter*]. Enter 3.500 in the Cone Diameter Setup Tool and press <Ok>.



*Cone Diameter Setup Tool*

In the graphics, a circle appears at the specified height. The reported value will be shown in the report.

```
251 ID XY Cone [7 pts]
      ID= 1.1417"
      Incl Ang= 89.9971
      Cone Taper= 11.9994" IN / FT
      Pierce Point
        X= 0.0000"
        Y= -0.0003"
      Attitude
      Ax/y Angle = -41.6512
      AY/Z Angle = -90.0040
      Az/X Angle = -89.9956

26 ID XY Cone (RCL 25) [7 pts]
   Eff. Depth= 1.1792"
   @ Diameter= 3.5000
```

*Reported results from a Cone Offset*

In this example the measured height is called the Effective Depth and has a value of 1.1792".

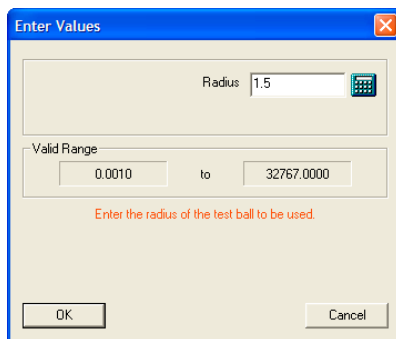
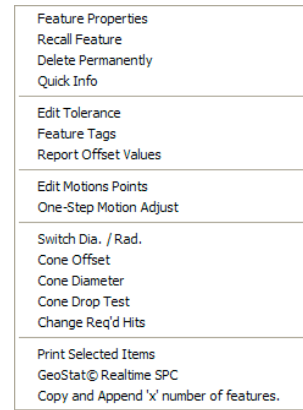
# Chapter 4 – Feature Measurement

## Cone Drop Ball Test

The Cone Drop Ball Test is used to place a test ball in a cone and calculate the diameter and position where the ball intersects with the cone.

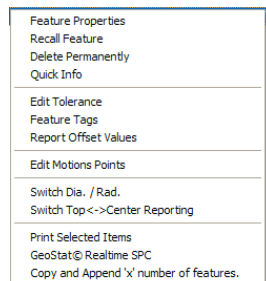
To use this test, right click on the cone in the report and choose [*Cone Drop Test*] from the sub menu.

Enter the radius of the ball that will be dropped into the open end of the cone.



*Cone Drop Test Setup Tool*

By default the results of the calculation is the XYZ position of the center point of the ball and its diameter on the cone where it makes contact. The reported position can be switched to the top of the ball by right clicking on the Drop Test record and from the sub menu choose [*Switch Top <-> Center Reporting*].



*Cone Drop Test Sub Menu*

```
25: ID XY Cone [7 pts]
    ID= 1.1417"
    Incl Ang= 89.9971
    Cone Taper= 11.9994" IN / FT
    Pierce Point
      X= 0.0000"
      Y= -0.0003"
    Attitude
    Ax/y Angle = -41.6512
    Az/Z Angle = -90.0040
    Az/X Angle = -89.9956

26 Cone Ball Drop Test (1.5000 Rad.) Center Position (RCL 25)
    Tan. Radius= 1.0607"
      X= -0.0001"
      Y= -0.0002"
      Z= 1.5505"
```

*Ball Drop Results*

# Chapter 4 – Feature Measurement

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## Ball Bar Macro

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One method to accurately evaluate axis to axis relationships is found in the [B89.4.1](#), Methods for Performance Evaluation of Coordinate Measuring Machines published by [ASME International](#). This Standard establishes requirements and methods for specifying and testing the performance of coordinate measuring machines (CMMs) having three linear axes perpendicular to each other and up to one rotary axis positioned arbitrarily with respect to these linear axes. In addition to clarifying the performance evaluation of CMMs, this Standard seeks to facilitate performance comparisons among machines by unifying terminology, general machine classification, and the treatment of environmental effects.

The Ball Bar consists of a temperature-stabilized bar with two high precision spheres mounted at each end, *see figures below*. The length between the spheres is not necessary to be known. The Ball Bar is positioned within the measuring area of the CMM in 28 different positions as described in ASME B89.4.1.



To assist in the gathering of the distance between spheres, the Ball Bar Macro is used.

### Using the Ball Bar Macro

Activate the macro using the drop down menus:

Measure ⇒ Ball Bar Macro

You will be prompted the required number of data points and the sphere to capture them on. The reported value is the distance between the Spheres.

For a more detailed use of the Ball Bar routine, visit the Geomet web site:

<http://www.geomet-cmm-software.com/tn-002.htm>

# Chapter 4 – Feature Measurement

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# Chapter 5 – Coordinate Systems

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## Chapter 5 – Coordinate Systems

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# Chapter 5 – Coordinate Systems

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# Chapter 5 – Coordinate Systems

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## Understanding Coordinate Systems

### Supported Geomet Junior Coordinate Systems:

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- MCS - Machine Coordinate System
- PCS - Part Coordinate System
- ICS - Interim Coordinate System

### PCS Differences between Geomet Junior and Geomet Junior Plus

Geomet Junior provides access to one PCS that can be redefined during the inspection process. Geomet Junior Plus has expanded PCS capabilities offering multiple PCS support. During the inspection process you can establish several PCSs as required to perform the inspection. Since Geomet Junior is a on-demand inspection tool and does not cycle inspection programs, there are limits placed upon it.

### MCS - Machine Coordinate System

The MCS is the XYZ position on the CMM with respect to the Home Position. The MCS axes are mutually parallel with the movement of the CMM.

Most manual CMMs do not have a home position; therefore the home position is the location of the CMM at the point of starting the system. Some manual CMMs do offer a home position that requires the operator to manually move the CMM over reference marks one axis at a time.

On a Direct Computer Control (DCC) system, the start-up procedure requires that you "Home" the CMM. This process will drive the CMM one axis at a time, to the designated home location and establish a repeatable XYZ zero point.

An MCS is therefore not a valid coordinate system to obtain reliable measured values for your part inspection, unless the part is carefully aligned with the machine axes.

# Chapter 5 – Coordinate Systems

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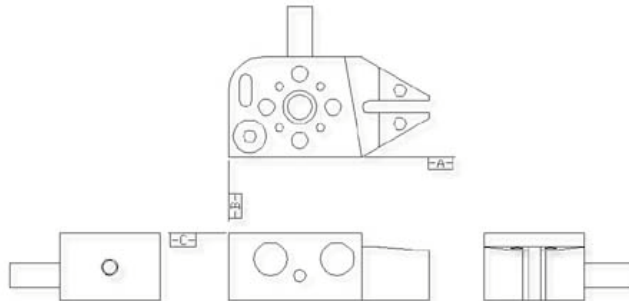
## PCS - Part Coordinate System

The PCS is the foundation that establishes the Orientation, Alignment and Origin of your part inspection. PCSs are simply the frames of reference in which part feature locations are defined.

Traditional drawings were made using 2D projections to represent 3D objects. Each 2D view shared a common reference point and common axis of alignment allowing the building of 3D features. In fact, a 3D dimensional PCS is implied.

Today, it is common to create machined parts using a 3D model created by many popular CAD tools. These models may contain all necessary information for the machinist to create the part and for the inspector to validate the final production. However, the PCS is still implied using the same procedures as if measured from a 2D drawing.

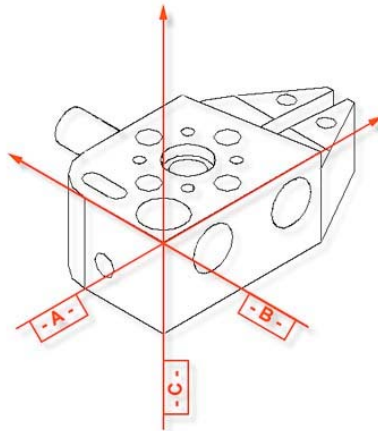
The established method for creating and using a datum frame reference can be found in the ASME Y14.5M - Dimensioning and Tolerancing manual. Geomet Junior uses these accepted practices in the application of PCS. To better understand this let us consider the multi-projection part shown below:



In order to measure this part on a coordinate measuring machine we shall need to contact it with probes on all sides. In planning to do this it is helpful to visualize the 3D coordinate system of the part. Let us do this by making a perspective drawing from one possible direction and then overlaying a 3D PCS. The figure below is one possible view of the 3D dimensional PCS applied to the GeoWidget.

## Chapter 5 – Coordinate Systems

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The way in which the PCS is overlaid on the part is determined by the datums defined in the drawing. Notice that each datum can be represented by a standard measured feature; The datum -A- is the ZX plane, datum - B - is the YZ plane and datum - C - is the XY plane. The XY, YZ and ZX planes are orthogonal to one another.

The important point to remember is that the two dimensional drawings we deal with represent three dimensional concepts, and in order to effectively measure a 3D part with a coordinate measuring machine we must "see" the 3D PCS associated with the part. This is made easier by looking at the actual part, referring to the drawing and making a habit of imagining the datums as we view the part.

### PCS Base Planes

PCS Base Planes are the extracted XY, YZ or ZX datum planes of an established Part Coordinate System. When extracted through the Recall Component tool, they become constructed planes and are given a feature number in the inspection report.

### PCS versus MCS

Since features of machine parts are defined in terms of their datum references, we must create Part Coordinate Systems reflecting those datums before the features can be measured. Since coordinate measuring machines have their own coordinate system, namely a system of mutually orthogonal axes of motion referred to as the Machine Coordinate System (MCS), the first problem we face is to create the PCS within the MCS. This is not trivial.

One way to create a PCS within a coordinate measuring machine is to make the PCS coincide with the MCS. The procedure consists of physically aligning the datum surfaces of the part parallel to the axes of motion of the machine and setting the X, Y and Z readout display to the datum of the part. Once the MCS

## Chapter 5 – Coordinate Systems

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and the PCS have been made to coincide, all dimensions found on the display of the coordinate measuring machine are also feature locations on the part.

Making the PCS and MCS coincide physically can be extremely time consuming, and sometimes impossible. We can eliminate the problem by using Geomet Junior to create and store a skewed PCS. Once a PCS has been established, the computer converts raw data collected in the machine coordinates into measurement results in part coordinates. Once the PCS has been established, you will see a part coordinate system with X, Y and Z axes nested inside a machine coordinate system with its own X, Y and Z axes.

The MCS and the PCS are totally skewed relative to each other. With the help of Geomet Junior any point in the MCS can be expressed in the PCS.

As Geomet Junior can manage the link between an MCS and a totally skewed PCS we no longer need to physically align the parts to the machine. BUT...we need to create the skewed PCS in Geomet Junior before it can manage the link. The job of creating the PCS will be simple once we understand a few fundamental principles.

### **ICS - Interim Coordinate System**

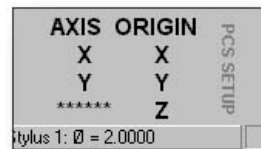
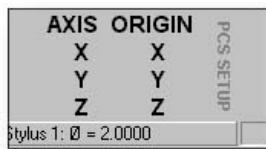
The ICS is a coordinate system that has not been completed to the status of a PCS. For example, when Geomet Junior begins a part inspection, the only coordinate system available is the MCS. Should the part to be inspected have the orient applied to it, Geomet Junior creates an ICS based on the orient vector data and brings forward the alignment and origin data from the MCS.

During the inspection process, reported results on features are hidden until the PCS is completed. Only then will the reported data be meaningful.

# Chapter 5 – Coordinate Systems

## Part Coordinate System Setup Guide

In order to ensure that a complete PCS has been established Geomet Junior provides a visual PCS Setup Guide to remind you of the missing components of the current PCS under construction. In the sample below, we show the setup guide with all axis and origins still requiring definition.



When you establish one of the PCS components, such as the Z primary axis derived from the Orient function on a measured or recalled qualifying feature, the setup guide will reflect the completion by "signing-off" that component with a series of "\*\*\*\*\*" as shown above. During the building of a PCS, Geomet Junior maintains an Interim Coordinate System, ICS, which contains the resolved transformations and carries forward the missing components from the MCS.

During the inspection process, additional PCSs may be required. Should you want to create another PCS by starting with the Orient function, the PCS Setup Guide will reappear and further results will be suppressed until the ICS is resolved into a completed PCS. The setup guide will not reappear with basic transformations on a current, completed PCS that results in a new PCS. These commands are:

- Alignment
- Origin
- Translate
- Rotate

Each of these commands when applied to a complete PCS results in the creation of a new PCS.

It should be noted that as long as a PCS is under construction, no results are displayed with each measured feature. When the PCS is completed, the PCS Guide Box will disappear from view and the suppression of results is removed.

# Chapter 5 – Coordinate Systems

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## Coordinate System Commands

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### ICS $\Rightarrow$ PCS, Interim Coordinate System

The ICS is a coordinate system that has not been completed to the status of a PCS. For example, when Geomet Junior begins a part inspection, the only coordinate system available is the MCS. Should the part to be inspected have the orient applied to it, Geomet Junior creates an ICS based on the orient vector data and brings forward the alignment and origin data from the MCS. During the inspection process, reported results on features are hidden until the PCS is completed. Only then will the reported data be meaningful.

The ICS  $\Rightarrow$  PCS Command is activated by:

Keyboard: shift + “

Menu: PCS  $\Rightarrow$  “ICS  $\Rightarrow$  PCS”

The ICS  $\Rightarrow$  PCS routine converts the status of an interim coordinate system from interim to complete. The effect of this routine is to permit the user to obtain printed results from what would normally be suppressed data.

For example ICS  $\Rightarrow$  PCS might be used when establishing the first coordinate system on a sample part such as shown in figure 1. In this example, we have the GeoWidget laying on the surface plate of the CMM with the OD cylinder pointing in the -X direction. The required dimension to inspect is the distance between the two bores as shown in figure 1.

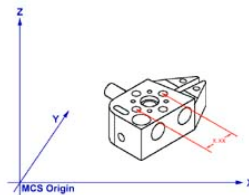


figure 1



# Chapter 5 – Coordinate Systems

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## Step 1

Our first operation would be to measure the circle designated A/4 using an ID Circle, see figure 2.

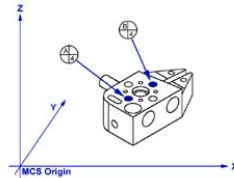


figure 2

## Step 2

Select Origin, Geomet Junior will prompt you to establish the X and Y origins, which you answer <Yes>, to both. This will create an ICS with the X and Y origin in the center of A/4.

## Step 3

Select the ICS  $\Rightarrow$  PCS command. This will bring forward the Orient, Alignment and the Z origin from the ICS. A completed part coordinate system will be established as shown in figure 3.

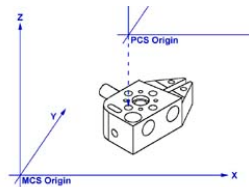


figure 3

## Step 4

Switch Geomet Junior to Polar reporting mode if it is not already there. Press the key <e> to toggle between Cartesian and Polar modes.

## Step 5

Measure circle B/4 using the circle command. The reported values will be straight-line values satisfying the requirements as shown in figure 1.

# Chapter 5 – Coordinate Systems

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## Orient

---

Keyboard:    j

Menu:         PCS ⇒ Orient

Orient establishes the direction of the primary PCS axis, with the selection of X, Y or Z determined by the MCS X, Y or Z-axis to which the directed feature axis is most parallel. Orient acts on the last measured or recalled 3D directed feature or pair of non-directional features, which could serve to create a 3D, directed feature. Orient sees through transparent operations such as other PCS formation commands, distance and angles, etc. Orient will be disabled for feature(s) that are not validated as having the required components to establish a primary datum.

The Orient command destroys the axis and origin references of the previous PCS and, if not already visible, invokes the PCS Setup Guide. For proper function, the Orient must be followed by the Align command with one exception, after performing the orient command; you can establish the origin on the characteristics of the feature. An example might be the measuring of an XY plane, which is used to establish the primary datum through the orient command along the Z-axis. Once the orient has been completed, you can establish the Z origin on that plane. Another example might be establishing the primary axis through two spheres.

When the Orient command is activated, Geomet Junior will look at the last feature in the inspection report to determine whether it has the necessary information to form the Primary datum. Should Geomet Junior determine that the last feature requires a second feature to solve for a primary datum, then it will continue to look back in the inspection report until the next feature is found. If the validation tests fail, Geomet Junior will then inform the operator that the orient command has failed and will abort the operation.

## Chapter 5 – Coordinate Systems

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### Align

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Keyboard: k

Menu: PCS ⇒ Align

Align establishes the directions of the secondary and tertiary PCS axes, with the selection of X, Y and Z determined by the MCS X, Y or Z axis to which the directed feature axis is most parallel. Align acts on the last measured or recalled 3D or 2D directed feature or pair of non-directed features which could serve to create a 2D or a 3D directed feature. For example, a pair of 1D co-directional points, pairs of coplanar 2D points, or pairs of 3D points. The Align command will see through transparent operations such as other PCS formation commands, distance, angle commands, etc. Geomet Junior will validate the last feature(s) to determine whether they are capable of providing a secondary datum.

Align, when executed in an ICS directly after the orient has been established makes an automatic choice for the alignment axis. For example, if the orient command resulted in establishing the Z-axis, then the Align command will rotate about the Z to establish the secondary datum.

When the Align command is executed in an established PCS, the resulting operation creates a new PCS by aligning to the requested feature. The Align command will determine the alignment axis when a pair of co-directional 1D points or coplanar 2D features is used. When using a pair of 3D features or a 3D axial feature, Geomet Junior will prompt for the PCS base plane to align in.

# Chapter 5 – Coordinate Systems

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## Origin

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Keyboard:    l (lower case L)

Menu:        PCS ⇒ Origin

The Origin command builds the tertiary datum on the location of the last measured or recalled feature. In the case of features with 1D locations such as 1D points and planes the origin is established for the reported direction of the feature.

Using a +X 1D Point, the Origin command will set the reported position along the X-axis as the new X-axis origin leaving Y and Z untouched. For a -Z Plane, the Z-axis Origin is set where the plane crosses the existing Z-axis.

For 2D and 3D features, the Origin command will prompt you to choose which axis to set. On a 2D XY Circle, you may elect to set the X-axis and not the Y-axis.

# Chapter 5 – Coordinate Systems

## Rotate

Keyboard: shift + :

Menu: PCS ⇒ Rotate

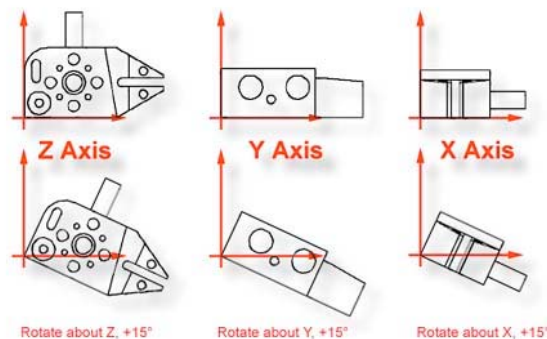
Rotate permits an existing PCS to be rotated in space about one of its own axes. A PCS can only be rotated about one axis at a time. Compound rotations must be done in two or more successive steps. It is important to note the following rotation conventions:

**Rotate about the X-Axis** - a positive angle produces a counter-clockwise rotation when looking in the -X direction.

**Rotate about the Y-Axis** - a positive angle produces a counter-clockwise rotation when looking in the +Y direction.

**Rotate about the Z-Axis** - a positive angle produces a counter-clockwise rotation when looking in the -Z direction.

In the Rotate PCS Dialog, see figure below, we show a request to rotate the current PCS 25° around the X-axis. To ensure only one axis of rotation, any entry in Y or Z, would result in clearing the entered value in X. In the examples shown below, a rotation is applied to each axis with its corresponding change in relationship to the sample part.



Note that the sense of directional measurements made by specifying a direction using directional keys; +X, -Y, etc. rotates with a PCS rotation. After rotating a PCS whose axes are essentially aligned with the MCS axes by 90° about the PCS Y axis, a +X measurement is understood to be directed upward instead of to the right, since that is now the direction of the +X axis.

# Chapter 5 – Coordinate Systems

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## **Edit an Existing Rotation Value**

A Rotate PCS feature once applied creates a new Part Coordinate System. You may edit the existing rotation value when there are features using the rotated PCS, but a warning is provided to rebuild all coordinate systems by running the program from the beginning.

To edit the existing rotation feature, highlight that feature and bring up the right-click sub menu. From the sub menu, select Edit Rotate Values. NOTE: The ability to edit a translated feature is only available when the translate feature has absolute entered values, not values derived from the last feature option.

Enter the new rotate value in the space provided and press the <Ok> button. Geomet Junior will display a warning that the features will no longer have valid positional data after the edit of the rotation values is completed. At this time, save the part inspection file and run the file to rebuild the Part Coordinate Changes.

# Chapter 5 – Coordinate Systems

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## Translate

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Keyboard: ;

Menu: PCS ⇒ Translate

Translate permits an existing PCS origin to be shifted by nominal amounts in all three directions. Translation creates a new complete PCS whose axes are parallel to those of the preceding PCS but shifted by the input values.

To perform a Translate, activate the Translate tool using the keyboard “;” or [*PCS ⇒ Translate*] from the drop down menus. Geomet Junior offers two methods to perform a PCS Origin Translation. The first method uses XYZ incremental values to translate the current origin, which are entered by the operator. To use this method, place a bullet next to the "Enter Values" entry in the Translation Source group box.

To translate absolute values, enter the required absolute values in the X, Y and Z edit controls provided. You can translate 1, 2 or 3 axis with one translate command. Upon completion, a new PCS is established using the next available PCS ID number.

In the “Use Last Feature” method, we can obtain a feature specific value such as the radius of the previously measured circle. Qualifying features include Circle, Cylinder, Cone and Sphere. When you place a bullet next to "Use Last Feature", Geomet Junior will show the radius value in the Translation Source box under "Use Last Feature".

The ( - ) and ( + ) column will become active next to the data fields. You can then check the appropriate directions you wish to translate in. Should you not want to translate in any axis, leave the check marks unchecked.

An example would be when the origin is called out on a tangent point of a circle. After you have established the Orient and Align Axis, measure the circle and place the origin in the center. Then perform a PCS Translate using the last feature option. Select the appropriate direction under the ( - ) and ( + ) columns. After accepting the translation, the new origin will be on the tangent point of the circle.

Both methods will create a new PCS. To summarize the methods, when "Enter Values" is selected, the values entered by the operator are considered absolute and will carry forward with each successive inspection run. Selecting "Use Last Feature" the translation values will recalculate with each inspection run and are considered dynamic to the current inspection run.

# Chapter 5 – Coordinate Systems

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## **Edit an Existing Translation Value**

A Translate feature once applied creates a new Part Coordinate System. You may edit the existing translation values when there are features using the translated PCS, but a warning is provided to rebuild all coordinate systems by running the program from the beginning.

To edit the existing translation feature, highlight that feature and bring up the right-click sub menu. NOTE: The ability to edit a translated feature is only available when the translate feature has absolute entered values, not values derived from the last feature option.

Enter the new translation values in the space provided and press the <Ok> button. Geomet Junior will display a warning that the features will no longer have valid positional data after the editing of translation values has been completed. At this time, save the part inspection file and run the file to rebuild the Part Coordinate Changes.



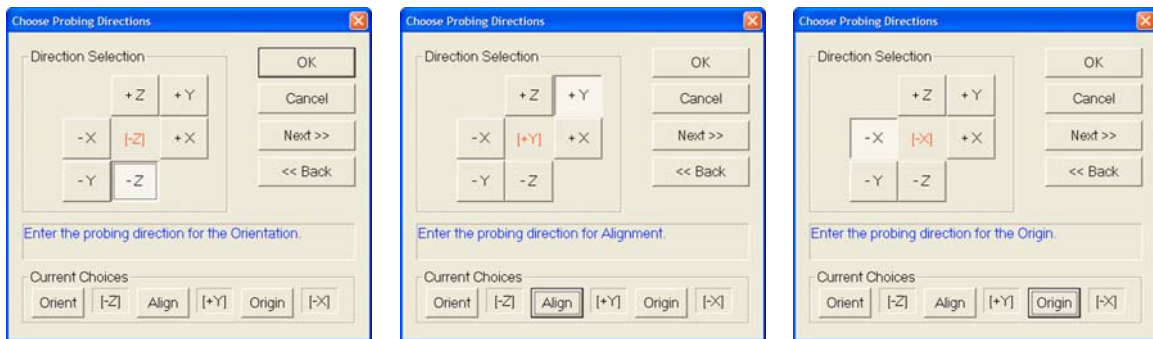
# Chapter 5 – Coordinate Systems

## One-Step PCS Generator

The One-Step PCS function is a macro to assist in establishing a basic PCS. It generates a PCS from a plane, line and point commonly used to build a PCS. The Plane is created from 3 data points. The Line is build from 2 data points and the final Point is a 1D directional point. The result is commonly known as a 3-2-1 coordinate system.

To activate the One-Step tool, select [PCS ⇒ One-Step PCS] from the main drop down menus. The setup dialog will appear with the last known settings.

Through this setup dialog you will establish the probing directions for each measured featured. By default it opens in the Orient mode which is the setting used for the Plane. To move to the Align component, click the <Next > or <Align> button. Similarly to move to the Origin click the <Next> or <Origin> button.



*Orient Probe Directions*

*Align Probe Directions*

*Origin Probe Directions*

When you have chosen all directions, press the <Ok> button and Geomet Junior will prompt you to: **Capture Orient -Z Data Point (0/3)**.

When you have captured the three data points, the prompt will display the requirements for the alignment: **Capture Align +Y Data Points (0/2)**.

Upon completion of the two alignment data points Geomet Junior will prompt for the final Origin Point: **Capture Origin -X Point 1**.

If you should capture an errant data point, you can remove that data point by pressing the <f2> Abort Point tool.

When all six data points have been captured, Geomet Junior will calculate the new Coordinate System.

# Chapter 5 – Coordinate Systems

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## PCS Program Examples

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Here you will find 10 Part Coordinate Examples to assist your learning of the processes used for measuring features and applying them to the building of a Part Coordinate System. On the Geomet web site, these examples can be downloaded to view the end results on your system.

Try each example and compare your final results with that of our supplied examples.

### PCS Program Examples

- #1, Basic Alignment
- #2, Plane-Line-Point
- #3, Quick PCS
- #4, Plane-Circle-Circle
- #5, Plane-Cylinder-Circle
- #6, Plane-Bisect Points-Circle
- #7, Cylinder-Circle-Point
- #8, Plane-Intersect Lines-Bisect Points-Circle
- #11, Translate
- #12, Rotate

NOTE: Pcs Examples #9 and #10 are removed from the Geomet Junior manual as they illustrate creating a PCS using Pivot Align and Offset Align which are features unique to Geomet 101 and above.

For more information regarding advance PCS features, please review the Geomet web site at:

<http://www.geomet-cmm-software.com/KbIndex3.htm>

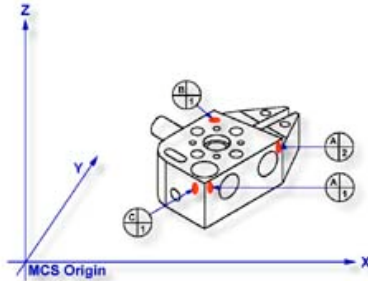
# Chapter 5 – Coordinate Systems

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## PCS Building Example #1: Basic Alignment

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Most CMMs offer a machine coordinate system that is true to the working surface. This allows the operator to establish simple, and fast, part coordinate system by eliminating steps normally required to ensure accurate alignments. The following example assumes the part orient in the Z axis is parallel to the Z axis of the CMM and the cylinder of the Widget is pointing in the -X direction.



### Step 1

Request a -X Point <4>, You will then be prompted to "Measure -X Point". Capture points A-1 and A-2; refer to the figure above. Note: if your system is active for auto-direction sensing then your prompt will display "Measure Auto-Dir Point". See System Options for controlling Auto-Direction Sensing.

### Step 2

Select Align <j>. Note: when you elect to perform an alignment without first establishing the orient, Geomet Junior will assume the orient axis is parallel to the machine coordinate system. For example, aligning in the XY plane will force the Z-axis of the MCS to establish the Z-axis of the ICS.

### Step 3

Select Origin <l>. This will establish the X origin as defined by the selected direction of the -X Point features. Note: always perform the alignment prior to origin, as the alignment will effect the probe compensation on features such as 1D Points.

### Step 4

Request a -Z Point <2>, You will then be prompted to "Measure -Z Point". Capture point B-1.

# Chapter 5 – Coordinate Systems

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## Step 5

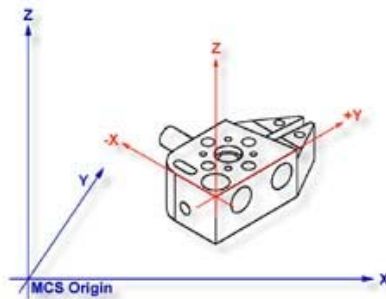
Select Origin <1>. This will establish the Z origin and your PCS Setup Guide will now reflect that only the Y origin is still required.

## Step 6

Request a +Y Point <9>, You will then be prompted to "Measure +Y Point". Capture point C-1.

## Step 7

Select Origin <1>. This will establish the Y origin and complete the ICS to a full part coordinate system. The PCS Setup Guide will disappear and you are now ready to take feature measurements.



## Summary

With a minimum of four data points and four command requests administered in the proper sequence you have completed a full part coordinate system, see figure above. This method of establishing a PCS is not meant to work with all production parts, but it does work with parts that have a surface that is capable of providing the orientation, or primary datum, and can lay flat on your CMM.

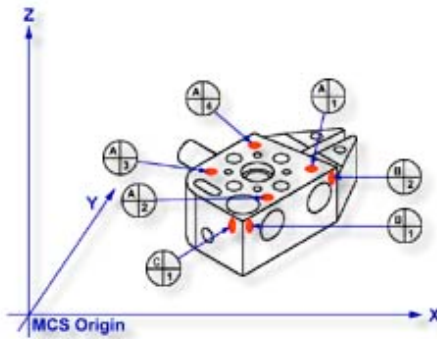
# Chapter 5 – Coordinate Systems

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## PCS Building Example #2: Basic PCS Plane - Line - Point

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In this exercise, we will create a basic part coordinate system utilizing a plane, line and point for establishing the axes and origins. The following example assumes the part is placed on your CMM where the cylinder of the Widget is pointing in the -X direction.



### Step 1

Request a -Z plane <b>, if auto-direction is not activated, you will be prompted for the probing direction which you should select as -Z. You will then be prompted to "Measure -Z Plane", (if auto-direction is active "Measure Auto-Dir Plane"). Capture points A-1, A-2, A-3 and A-4 as shown in the figure above.

### Step 2

Select Orient <j>. The orient command will create the primary datum on the axis that is most normal to the machine coordinate system. For example, if the plane used by orient was determined to be a XY plane then the normal will most closely align with the Z-axis. In your PCS Setup Guide, the Z-Axis will be signed off.

### Step 3

Select Origin <l>. This will establish the Z origin that is determined by the normal direction of the -Z plane.

### Step 4

Request a Line <m>, You will then be prompted to select the probing direction, enter -X (if auto-direction is not active). The prompt will update to display "Measure -X Line" (or "Measure Auto-Dir Line"). Capture points B-1 and B-2. When the points have been captured, you will be asked which projection plane to use, select XY. A secondary request may be made to determine the pierce axis, select X, see Measured Features - Line for explanations.

# Chapter 5 – Coordinate Systems

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## Step 5

Select Align <k>. Your ICS will update to include the secondary datum that is derived from the XY line feature.

## Step 6

Select Origin <l>. This will establish the X origin that is determined by the reported direction of the XY Line.

## Step 7

Request a +Y Point <9>, You will then be prompted to "Measure +Y Point". Capture point C-1.

## Step 8

Select Origin <l>. This will establish the Y origin and complete the ICS to a full part coordinate system. The PCS Setup Guide will disappear and you are now ready to take feature measurements.

## Summary

The Plane-Line-Point combinations of features are commonly used for most machined parts to set the part coordinate system. It is important to remember that the features in these exercises are utilizing minimum data points to achieve a complete PCS. There are several factors that can negatively effect the quality of your data points. These include probing speed and distance between data points just to name two.

In the case of the alignment, we used two points to calculate the line. The repeatability of the electronic trigger probe can be as much as .00014" with a standard 20 mm extension. If the two points for the line were taken 0.500" apart, the possibility exists of .00028" error per inch, when applied to the PCS effects all features being measured. It is therefore important that you select the most stable features to establish your PCS and balance the number of data points to help reduce inherent CMM and operator errors. When possible, use more data points to help define the feature, especially when these features are used for establishing datum features.

# Chapter 5 – Coordinate Systems

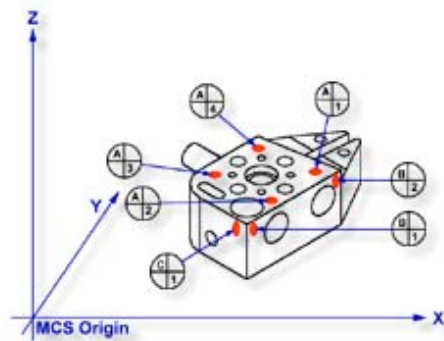
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## PCS Building Example #3: Quick PCS

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In this exercise, you will utilize Geomet Junior's automatic part coordinate system tool, known as the Quick PCS. Quick PCS requires that you have auto-direction capabilities and that it is active through [*System Options*⇒*Enhanced Features*].

The premise of Quick PCS is to perform the basic Plane and 3 - 1D Point setup to create a PCS without the operator commanding any feature requests. When you start Geomet Junior and establish the working stylus, Geomet Junior is waiting for a data point. If it acknowledges an incoming data point and is not currently setup for a feature, it assumes you are invoking the Quick PCS option.



### Step 1

Using the datum targets as shown in the figure above, gather data points A-1 through A-4. Geomet Junior will automatically establish a plane, orient and origin after the fourth point has been captured.

### Step 2

Gather data points B-1 and B-2 making sure you follow the rules on probing 1D points using auto-direction, see Measured Features - Points. Once these two points are captured, Geomet Junior will establish the alignment and origin based on the point directions.

Should the points be captured in such a way as to misidentify the direction, the Quick PCS tool will abort the auto sequence and return you to normal inspections. If this occurs, correct the point direction (see Measured Features - Points) and continue with the setup as described in exercise 2, steps 5 - 8.

### Step 3

Capture the final data point, C-1 and Geomet Junior will complete the final origin and establish PCS 1.

# Chapter 5 – Coordinate Systems

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## Summary

With the Quick PCS feature of Geomet Junior, you were not required to press any feature key or in any other way instruct Geomet Junior of the next feature or action.



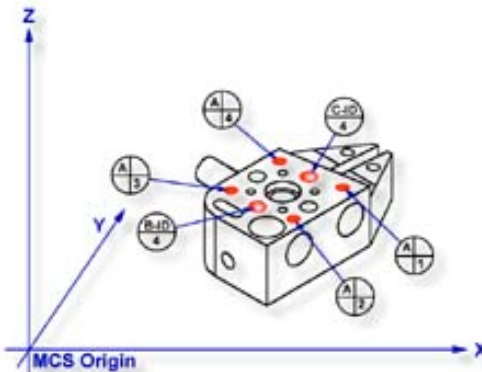
# Chapter 5 – Coordinate Systems

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## PCS Building Example #4: Plane - Circle - Circle

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In this exercise, we will create a basic part coordinate system utilizing a plane and two circles for establishing the axes and origins. The following example assumes the part is placed on your CMM where the cylinder of the Widget is pointing in the -X direction.



### Step 1

Request a -Z plane <b>. If auto-direction is not activated, you will be prompted for the probing direction which you should select as -Z. You will then be prompted to "Measure -Z Plane", (if auto-direction is active "Measure Auto-Dir Plane"). Capture points A-1, A-2, A-3 and A-4 as shown in the figure above.

### Step 2

Select Orient <j>. The orient command will create the primary datum on the axis that is most normal to the machine coordinate system. For example, if the plane used by orient was determined to be a XY plane then the normal will most closely align with the Z-axis. In your PCS Setup Guide, the Z-Axis will be signed off.

### Step 3

Select Origin <l>. This will establish the Z origin that is determined by the normal direction of the -Z plane.

### Step 4

Select Circle <z>, if auto-direction is not activated, you will be prompted for the Circle types, ID OD IR OR, choose ID. Capture the four data points identified as B-ID/4. Continue with the data points for the next circle, C-ID/4.

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## Step 5

Select Align <k>. Your ICS will update to include the secondary datum that is derived from the two XY circles. The alignment takes place through the reported XY position of the circles, which are projected, into the orient plane.

## Step 6

Select Origin <l>. Circles, which are 2D, provide two directions when establishing an origin. In our example, the circle can be used for the X and/or the Y directions. The origin command will prompt you whether to use the X and then the Y. For our example you should answer Yes to both requests. Upon completion, you will have established PCS 1.

## Summary

In this exercise, we utilized two coplanar XY features for the alignment and subsequent origin. As with many feature characteristics, the circles could have been replaced with any feature that reports a 2D solution. These include 2D points, cylinder and cone pierce points, etc. Through the proper selection of features, you can establish a part coordinate on nearly any type of manufactured part.

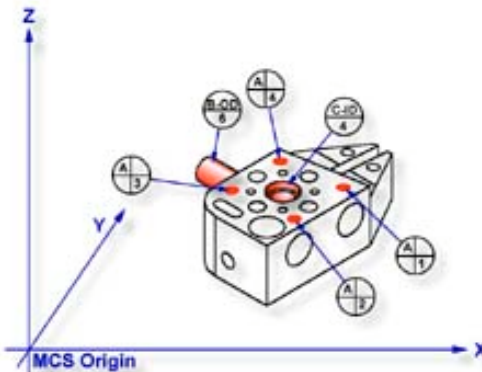
# Chapter 5 – Coordinate Systems

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## PCS Building Example #5: Plane - Cylinder - Circle

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In this exercise, we will create a part coordinate system utilizing a plane for the orient and origin, a cylinder for the alignment followed by a circle for the last components of the origin. The following example assumes the part is placed on your CMM where the cylinder of the Widget is pointing in the -X direction.



### Step 1

Request a -Z plane <b>, if auto-direction is not activated, you will be prompted for the probing direction which you should select as -Z. You will then be prompted to "Measure -Z Plane", (if auto-direction is active "Measure Auto-Dir Plane"). Capture points A-1, A-2, A-3 and A-4 as shown in the figure above.

### Step 2

Select Orient <j>. The orient command will create the primary datum on the axis that is most normal to the machine coordinate system. In your PCS Setup Guide, the Z-Axis will be signed off.

### Step 3

Select Origin <l>. This will establish the Z origin that is determined by the normal direction of the -Z plane.

### Step 4

Select Cylinder <c>, if auto-direction is not activated, you will be prompted for the cylinder type: ID OD IR OR, choose OD. Capture the six data points identified as B-OD/6.

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## Step 5

Select Align <k>. A cylinder offers the possibility of more than one alignment solution. In our example, you have solved the Z-axis orient by utilizing the previous plane; therefore you are attempting to align the remaining axis, or XY. Select the XY button from the Select Axis dialog that is displayed during the Alignment process.

Your ICS will now update to include the secondary datum that is derived from the longitudinal axis of the cylinder. In this example, the cylinder was reported as piercing the YZ ICS base plane, therefore the normal to that plane is X with a direction of -X. The PCS Setup Guide will update to reflect the XY Axis have been solved.

## Step 6

Select Circle, if auto-direction is not activated, you will be prompted for the Circle type: ID OD IR OR, choose ID. Capture the four data points identified as C-ID/4.

## Step 7

Select Origin. The Circle, which is 2D, provides two directions when establishing an origin. In our example, the circle can be used for the X and/or the Y direction. The origin command will prompt you whether to use the X and then the Y. For our example you should answer Yes to both requests. Upon completion, you will have established PCS 1.

## Summary

There are times when you are required to utilize more than one 3D feature to solve for the part coordinate system. In this example we used a 3D feature, a cylinder, from which the alignment is derived, therefore you are prompted to solve which part coordinate system component to solve.

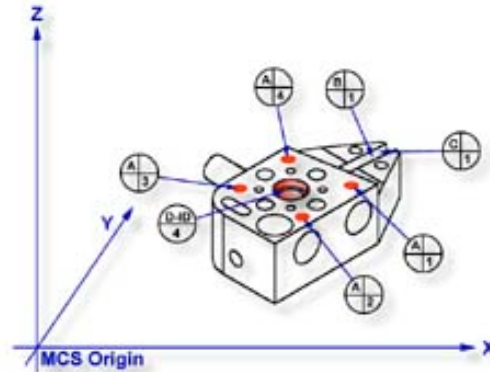
From this example you should note that the data point spread on the cylinder is approximately 1.25" in the X-axis and the width of the part is 4.50". This can be a cause of concern as it is poor inspection practice to have your data point spread ratio to the width of the part less than 50%, in this case only 28%. The possibility of skewing your part coordinate system increases dramatically as your ratio is reduced.

However, conditions do arise that do not allow for proper setup and as the inspector, you are challenged to determine the best data point spreads with the features available that will produce a sound part coordinate system.

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## PCS Building Example #6: Plane - Bisect Points - Circle

In this exercise, we will create a part coordinate system utilizing a plane for the orient and origin, two 2D points from which we will obtain a constructed 2D point through the bisect command then followed by a circle for alignment and origin. The following example assumes the part is placed on your CMM where the cylinder of the Widget is pointing in the -X direction.



### Step 1

Request a -Z plane <b>, if auto-direction is not activated, you will be asked for the probing direction which you should select as -Z. You will then be prompted to "Measure -Z Plane", (if auto-direction is active "Measure Auto-Dir Plane"). Capture points A-1, A-2, A-3 and A-4 as shown in the figure above.

### Step 2

Select Orient <j>. The orient command will create the primary datum on the axis that is most normal to the machine coordinate system. In your PCS Setup Guide, the Z-Axis will be signed off.

### Step 3

Select Origin <l>. This will establish the Z origin that is determined by the normal direction of the -Z plane.

### Step 4

Select a 2D XY Point <5> + <2>. The selection of a 2D point requires two commands. The first command is activated by pressing the < 5 > key, which will display the 2D and 3D point selection tool, next select the PCS base plane you would like to point to be projected into. After the selection has been completed, Geomet Junior will prompt you to "Measure XY Point". Capture points B-1 and C-1.

# Chapter 5 – Coordinate Systems

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## Step 5

Select the Bisect command <a>. This command will take the two projected XY points and solve for the 2D XY bisect point.

## Step 6

Select Circle <z>, if auto-direction is not activated, you will be prompted for the Circle type: ID, OD, IR, or OR, choose ID. Capture the four data points identified as D-ID/4.

## Step 7

Select Align <k>. This will take the just measured circle center and the previous 2D point created by the bisect routine and perform an alignment. Your ICS will update to include the secondary datum.

## Step 8

Select Origin <l>, the Circle, which is 2D, provide two directions when establishing an origin. In our example, the circle can be used for the X and/or the Y direction. The origin command will prompt you whether to use the X and then the Y. For our example you should answer <Yes> to both requests. Upon completion, you will have established PCS #1.

## Summary

In this exercise, we used a constructed feature, an XY point, as part of the alignment solution. It is important that you choose the correct features to be used for alignment based on the completeness of the ICS. The XY points for B-1 and C-1 were chosen as the ICS lacked an alignment. If two 1D points were chosen, then there would exist an error caused by the part skewed to the MCS base axis, *see Chapter 4 Measurement Features ⇒ Points*.

This does not preclude conditions where 1D points could have been used. For example, if we were working in the PCS that was created in exercise 1, then we would have the correct probe compensation vector and we could select -X and +X 1D points for B-1 and C-1 respectively. The resulting bisect would create a 1D point on the centerline of the slot.

A 1D point followed by a circle can not be combined to form an alignment. Geomet Junior does not accept this as it causes potential repeatability problems when the slot is not aligned with the current PCS. Therefore you could repeat the bisect of two additional 1D points captured on the width of the part at the other end from the slot points C and D. The resulting 1D point derived from the bisect combined with the previous recalled constructed point could produce the alignment.

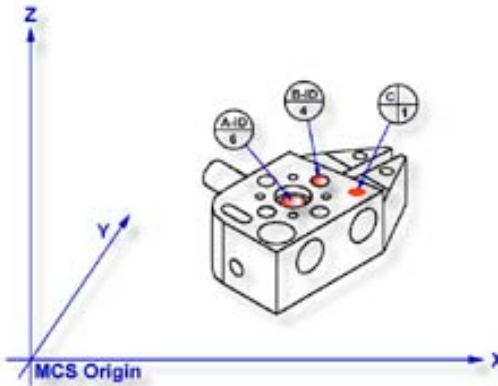
# Chapter 5 – Coordinate Systems

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## PCS Building Example #7: Cylinder - Circle - Point

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In this exercise we will utilize a cylinder to provide the primary datum and the pierce point from the cylinder as the origin. The alignment will be supplied through a circle and the previous cylinder. Finally a 1D point will complete the part coordinate system by providing the last component of the origin. The following example assumes the part is placed on your CMM where the cylinder of the Widget is pointing in the -X direction.



### Step 1

Select Cylinder <c>, if auto-direction is not activated, you will be prompted for the cylinder type ID, OD, IR, or OR, choose ID. Capture the six data points identified as A-ID/6, see the figure above.

### Step 2

Select Orient <j>. The orient command will create the primary datum on the axis of the cylinder that is most parallel to the machine coordinate system. In your PCS Setup Guide, the Z-Axis will be signed off.

### Step 3

Select Origin <l>. This will establish the origin reported as the pierce point of the cylinder. In this example, the cylinder pierces the XY base plane and the origin command will prompt you whether or not to set the origin on the X and/or the Y. Answer yes to establish the XY origin.

### Step 4

Select Circle <z>, if auto-direction is not activated, you will be prompted for the Circle type: ID, OD, IR, or OR, choose ID. Capture the four data points identified as B-ID/4.

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### Step 5

Select Align <k>. Your ICS will update to include the secondary datum which is derived from the XY circle and the previous XY pierce point from the cylinder.

### Step 6

Select -Z Point <2>. The final component missing for your complete PCS is the Z origin. You will then be prompted to "Measure -Z Point". Capture point C-1.

### Step 7

Select Origin <1>. This will solve the Z-axis Origin and complete PCS #1.

### Summary

When using a through bore as the primary datum, we must be careful that the data point spread is sufficient to allow for a stable feature. In this example we would place an extension on the stylus to allow for a greater reach into the cylinder.



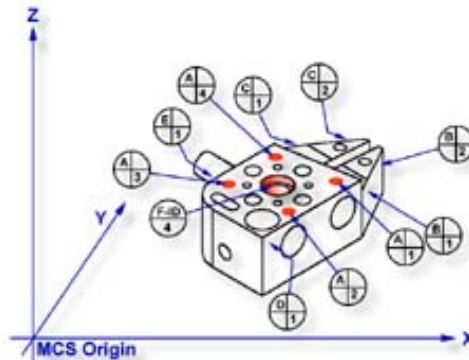
# Chapter 5 – Coordinate Systems

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## PCS Building Example #8: Plane - Intersect Lines - Bisect Points - Circle

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In this exercise we will combine two constructed features to create the secondary datum. These constructed features are derived from two lines intersected and two 2D points bisected. The following example assumes the part is placed on your CMM where the cylinder of the GeoWidget is pointing in the -X direction.



### Step 1

Request a -Z plane <b>. If auto-direction is not activated, you will be prompted for the probing direction which you should select as -Z. You will then be prompted to "Measure -Z Plane", (if auto-direction is active "Measure Auto-Dir Plane"). Capture points A-1, A-2, A-3 and A-4 as shown in the figure above.

### Step 2

Select Orient <j>. The orient command will create the primary datum on the axis that is most normal to the machine coordinate system. In your PCS Setup Guide, the Z-Axis will be signed off.

### Step 3

Select Origin <l>. This will establish the Z origin that is determined by the normal direction of the -Z plane.

### Step 4

Request a Line <m>, You will then be prompted to select the probing direction, enter -X (if auto-direction is not active). The prompt will update to display "Measure -X Line" (or "Measure Auto-Dir Line"). Capture points B-1 and B-2. When the points have been captured, you will be asked which projection plane to use, select XY. A secondary request may be made to determine the pierce axis, select X, refer to *Chapter 4 Measured Features* ⇒ *Line for more information*.

# Chapter 5 – Coordinate Systems

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## Step 5

Clear the current mode by pressing the < Esc > key. Request a Line feature <m>, You will then be prompted to select the probing direction, enter +X (if auto-direction is not active). The prompt will update to display "Measure +X Line" (or "Measure Auto-Dir Line"). Capture points C-1 and C-2. When the points have been captured, you will be asked which projection plane to use, select XY.

## Step 6

Select the Intersect <d> command. This command will take the two projected lines and solve for the intersection between them. The result will be a 2D XY point.

## Step 7

Select a 2D XY Point <5> + <2>. The selection of a 2D point requires two commands. The first command is activated by pressing the < 5 > key, 2D and 3D point selection, which will then prompt which current base plane you will project into. After the selection has been completed, Geomet Junior will prompt you to "Measure XY Point". Capture points D-1 and E-1.

## Step 8

Select the Bisect <a> command. This command will take the two projected XY points and solve for the bisect between them resulting in a 2D XY point.

## Step 9

Select in the report display feature number 7 by left clicking on it (2D point formed by the intersect command). Right-click your mouse and select from the popup sub menu, <Recall Feature>. This will recall the feature and create new feature number 11.

Alternatively you can recall a feature by pressing the Recall Feature <h> command from the keyboard. In the control labeled "<- Enter Feature No. to Recall, enter 7 and press the <Ok> button or the <Enter> key on the keyboard.

## Step 10

Select Align <k>. Your ICS will update to include the secondary datum which is derived from the recalled 2D XY point and the previous 2D XY point created from the bisect command.

# Chapter 5 – Coordinate Systems

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## Step 11

Select Circle <z>, if auto-direction is not activated, you will be prompted for the Circle type: ID, OD, IR, or OR, choose ID. Capture the four data points identified as F-ID/4.

## Step 12

Select Origin <l>, the Circle, which is 2D, provides two directions when establishing an origin. In our example, the circle can be used for the X and/or the Y direction. The origin command will prompt you whether to use the X and then the Y. For our example you should answer Yes to both requests. Upon completion, you will have established PCS 1.

## Summary

In this exercise we had combined features to create constructed features which are then used to create part coordinate system components. In part production we will find numerous cases where one or more part coordinate system datums are symmetry lines or points where no features exist.

When performing constructions in an ICS, it is important to remember the established projection base planes that are valid. For example, in this exercise it would not have produced acceptable results if we established 2 ZX points, one each on the top and bottom surfaces of the widget and then perform the bisect. The resulting 2D point would be projected into the alignment of the machine coordinate system and therefore would not represent a valid point feature for the part coordinate system.

# Chapter 5 – Coordinate Systems

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## PCS Building Example #11: Translate

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In this exercise we will take an existing part coordinate system and translate it by nominal amounts in the X and Y-axis. The Translate command can be performed on X, Y and/or Z individually or any combination. As you must have a complete coordinate system defined, please setup your part described in PCS Example #2.

### Step 1

Select the Translate command <;>. When you activate this command, Geomet Junior will display a dialog where you can enter your translation values. Enter 2.125 for X and 1.500 for Y and no entry for Z. Press <Accept> to perform the translation. A new PCS will be established, or in the case of Junior, a translation of the current PCS takes place.

### Summary

In many conditions, it is required to translate the part coordinate system when you are working with a datum that is derived from points that are not defined on your part. For example you may be inspecting a cavity insert which was removed from a progressive die where the datums are a common alignment pin not available at inspection time. Another example is the focal point of an optical lens whose surface radial may be projected 2,000" from the actual part.

# Chapter 5 – Coordinate Systems

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## PCS Building Example #12: Rotate

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In this exercise we will take an existing part coordinate system and rotate it about an axis by a nominal value. The rotate command can be performed only about one PCS axis at a time. If you require performing compound rotations, the rotate command must be repeated as separate steps. As you must have a complete coordinate system defined, please setup your part described in PCS Exercise 2.

### Step 1

Select the Rotate command, press <shift> + < : >. When you select this command, the Rotate PCS Axis dialog will prompt you to enter a nominal value for an axis. Rotations can only be applied to one axis at a time; therefore this rotation tool will ensure you enter only one value prior to accepting the nominal value. For this exercise, enter -5 in the X axis control and press the < Accept > button. A new PCS will be established, or in the case of base Junior, a translation of the current PCS takes place.

### Summary

When we rotated the PCS -5° around the X-axis, our resulting PCS should be parallel to the top surface of the tapered planes located on the taper end of the GeoWidget. To verify that we performed the rotation correct, select a -Z Point <2> feature and probe the top surface of the 5° plane. We should see a -Z point value at  $.018 \pm .005$ .

# Chapter 5 – Coordinate Systems

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## Coordinate System Manager – Geomet Junior

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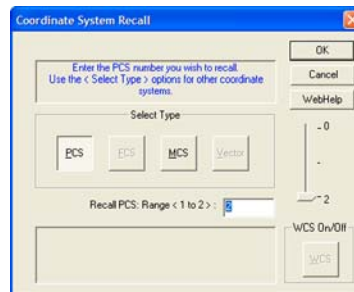
Geomet Junior only has the capacity of one Coordinate System (CS). This CS can be changed through all the CS system commands as previously defined. However, it always replaces the previously defined CS.

The Coordinate System Manager toggle between the MCS and the defined PCS. Pressing the key <'> or through the menu [PCS ⇒ Recall PCS] will toggle between the two CS.

## Coordinate System Manager – Geomet Junior Plus

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The CS Manager provides access to recall established Part Coordinate Systems and Machine Coordinate System.



### Recalling a Part Coordinate System

Each time a completed PCS is established, it is given an ascending number starting with 1. If you are requesting a PCS recall, activate the Coordinate System Manager by pressing the key <'> or through the menu [PCS ⇒ Recall PCS]. When the CS Manager appears ensure that the PCS button is pressed in the Select Type group. Any existing PCS can then be made the current PCS by entering the desired PCS number. Optionally you can utilize the slider control next to the "Select Type" group to scroll through the available PCSs. If you were to enter a 0 for the desired PCS, you are in effect recalling the machine coordinate system. Press the <Ok> button to complete the recall function.

### Recalling the Machine Coordinate System

Recalling the Machine Coordinate System can be accomplished by activating the Coordinate System Manager as described above and ensure that the MCS button is pressed in the Select Type group. Press the <Ok> button to complete the recall function.

*NOTE: You will notice two additional buttons labeled FCS and Vector. The FCS works with Fixture Coordinate Systems and Vector established drive vectors in DCC style CMMs. They are used with Geomet 101 and above.*

# Chapter 6 – Tolerance

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## Chapter 6 – Tolerance

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# Chapter 6 – Tolerance

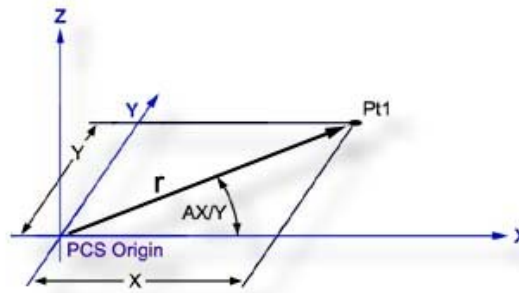
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# Chapter 6 – Tolerance

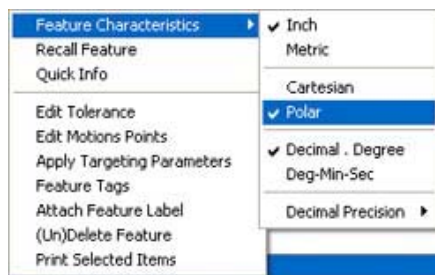
## Introduction to Tolerance

Before we discuss how Geomet Junior applies tolerance to a feature, it is useful to review the various reporting formats available. These formats include Linear or True Position tolerance reported in either Cartesian or Polar formats. All feature locations are reported against a Datum Frame Reference or PCS (Part Coordinate System). A two-dimension feature will report its location in one PCS base plane. An example would be an XY Point consisting of an X and Y-axis component relative to an origin, see example below.



The example above illustrates how the location of a point **Pt1**, (example would be a center of a bore) can be expressed in either Cartesian (X, Y) or Polar (r, AX/Y) coordinates. In the Cartesian format the coordinates **X** and **Y** are the distances between **Pt1** and the origin as measured along the X and Y-axis respectively. In the Polar format, **r** represents the straight-line distance between **Pt1** and the origin, and **AX/Y** represents the angle that the radius line makes with the X-axis.

Geomet Junior defaults to Cartesian format, which can be changed in the System Options. To change the reporting format during the teaching of a part inspection, press the <e> (Cart/Pol) key on the keyboard. To change the reporting format of a single feature, highlight the feature and activate the sub menu with a right click. Choose either Cartesian or Polar from the Feature Characteristics command.

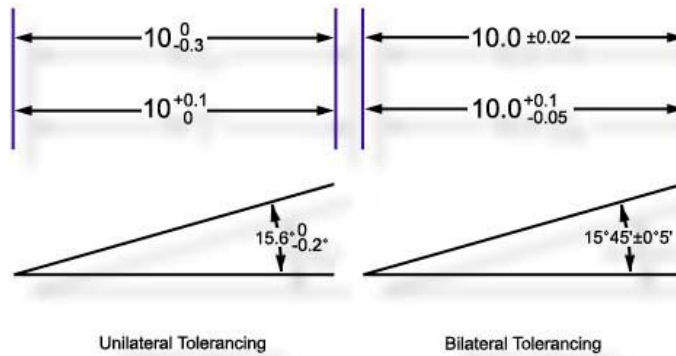


# Chapter 6 – Tolerance

## Linear Tolerance Theory

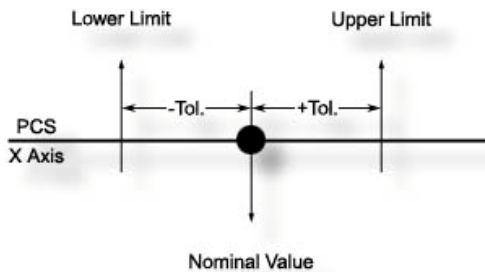
The purpose of measurement is to determine the locations and sizes of features relative to their specified upper and lower tolerance limits. The space between these limits is called the Tolerance Zone.

Linear tolerance is sometimes referred to as Unilateral or bilateral tolerance. Typical linear tolerance call outs are shown in the figure below.



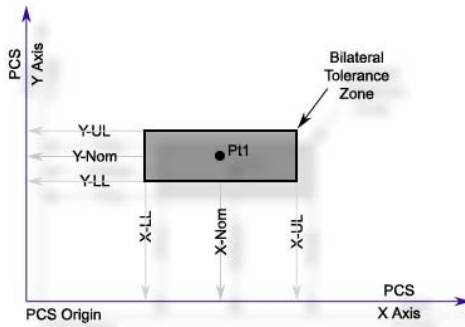
### Plus and Minus Tolerance

The shape of a linear tolerance zone depends on the dimensionality of the feature in question and on whether the reporting format is Cartesian or Polar. The figures below demonstrate a bilateral tolerance zone for a one-dimensional and two-dimensional feature reported in Cartesian format.



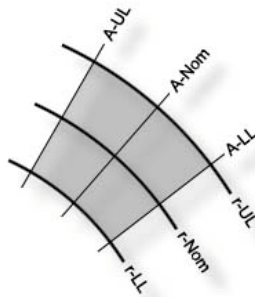
### 1D Bilateral Tolerance

# Chapter 6 – Tolerance



### 2D Bilateral Tolerance

The next figure demonstrates the tolerance zone of a 2D feature in polar format. A 3 dimensional feature will have a cubic tolerance zone surrounding the XYZ nominal point.



Bilateral Tolerance in Polar Format

# Chapter 6 – Tolerance

## True Position Tolerance Theory

Geomet Junior provides True Position tolerance support for qualifying features in RFS, MMC and LMC formats. Additionally, Datum Bonus Tolerance is available when building a Datum Frame Reference (PCS) using a bore and an origin feature.

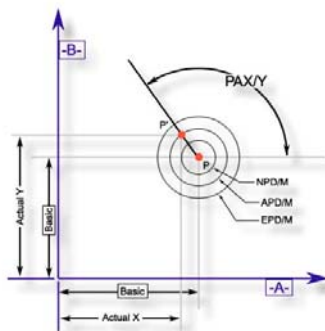
Definitions for most functions can be found in the ASME Y14.5M-xxxx specification. The manual is provided by ASME and can be found on their web site: <http://www.asme.org>

The Linear tolerance zones previously discussed were found to have widely varying shapes depending on the print-out format, Cartesian or Polar and on the 1, 2 or 3 dimensional nature of the feature. Positional Tolerance Zones are much simpler by comparison being circular, cylindrical, spherical or conical in shape.

In Geomet Junior, Positional Tolerance is limited to circular and spherical zones only and operates on the following features:

	1D Pt	2D Pt	3D Pt	Circle	Line	Plane	Sphere	Cylinder	Cone
Pos. Tol.		X	X	X			X	X <sup>(1)</sup>	X <sup>(1)</sup>
Notes:									
1 – Positional Tolerance is applied to the 2D Reported Pierce Point only.									
<i>table 1, Positional Tolerance Application Chart</i>									

A typical MMC positional tolerance zone, greatly magnified, is shown in the figure below followed by a definition of terms:



*MMC Positional Tolerance Zone Definitions*

Positional Zone	Definitions:
P	Nominal Point Location
P'	Actual Point Location
NPDM/M	Nominal Position Diameter MMC
EPDM/M	Effective Position Diameter MMC
APDM/M	Actual Position Diameter MMC
PAX/Y	Position Angle relative to the X axis

# Chapter 6 – Tolerance











Whereby the effective position diameter (EPD/M) is the sum of the nominal position diameter (NPD/M) and the tolerance bonus from the measured feature.

In this example, the feature is obviously in tolerance, because the actual position diameter (APD/M) is less than the Effective position diameter (EPD/M).

Note that the position angle (PAX/Y) records the direction in which the actual point is offset relative to the nominal point. The APD/M and the PAX/Y completely define the location of the actual point. A typical positional tolerance printout for a Circle is shown on the following examples.

No.	Feature	ACTUALS	Dev.Tol.	Dev.Nom.	NOMINALS	+TOL.	-TOL.
4*	ID XY Circle( Create ) MMC						
	ID=	2.50800" +++		0.00800	2.50000	0.01500	-0.00500
	X=	3.00220			3.00000		
	Y=	4.01280			4.00000		
	Tol=	0.025975 ++++			0.033000		
	Pos. Angle=	80.248					
5	ID XY Circle (RCL 4) MMC						
	ID=	2.50800" +++		0.00800	2.50000	0.01500	-0.00500
	Pol-R=	5.01156			5.00000		
	AX/Y=	53.198			53.130		
	Tol=	0.025984 ++++			0.033000		
	Pos. Angle=	80.283					

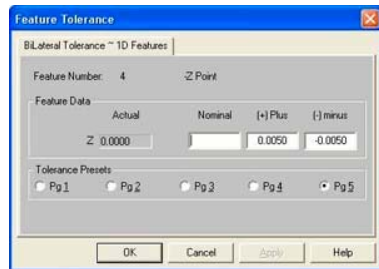
*Geomet Junior On-Screen Position Tolerance display*

No.	Feature	Actual	Dev. Tol.	Dev. Nom.	Nominal	Tol. Plus	Tol. Minus
4	ID XY Circle						
	ID	2.50800" 		0.00800	2.50000	0.01500	-0.00500
	X	3.00220" 			3.00000		
	Y	4.01280" 			4.00000		
	Pos	0.02598" 			0.03300		
	Pos-A	80.248" 			0.02000 (Nom)	0.01300 (MMC Bonus)	
5	ID XY Circle (RCL 4)						
	ID	2.50800" 		0.00800	2.50000	0.01500	-0.00500
	Pol-R	5.01156" 			5.00000		
	Pol-A	53.19778" 			53.13000		
	Pos	0.02598" 			0.03300		
	Pos-A	80.283" 			0.02000 (Nom)	0.01300 (MMC Bonus)	

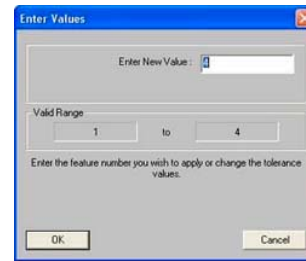
*Geomet Junior Printed Report*

# Chapter 6 – Tolerance

## Working with Geomet Junior Tolerance Windows



Tolerance 1D Points



Enter Feature Number

To activate the tolerance tool directly from the displayed report, highlight the feature by left clicking on it. Activate the feature sub menu by right clicking and select the *[Edit Tolerance]* command. To activate the tolerance tool using keyboard short keys, press <Ctrl> + <t> which activates a dialog where the feature number will be entered. In either method, the appropriate tolerance dialog will appear with the current tolerance data displayed.

To apply tolerance nominal values, start by entering the nominal value for the reported feature in the column labeled "Nominal". Next enter the Plus and Minus values for the bilateral tolerance band.

*NOTE: Geomet Junior will assist by entering the sign of the nominal automatically. This is accomplished by using the sign of the actual reported value that is added to the first number entered eliminating keystrokes.*

*Additionally, when you enter the plus tolerance band value, Geomet Junior automatically updates the minus tolerance band eliminating extra keystrokes.*

In some cases the bilateral tolerance band may not be equilateral, as with  $\pm 0.005$ . An example might be where the tolerance band is  $+0.005/-0.002$ . Enter in the Plus column "0.005" and in the Minus column "-0.002". The minus sign in the Minus column must be entered to correctly calculate the actual position within the tolerance band of  $+0.005/-0.002$ . The process of requiring the sign allows tolerance bands such as  $+0.010/+0.002$ , or  $-0.002/-0.010$ , which are still in use on assembly drawings.

To apply a Unilateral Tolerance, such as  $10.0 +0.01 / 0.0$  enter the 10.0 in the nominal column, 0.01 in the plus column and 0.0 in the minus column.

To support Limit Dimensioning where the feature has a tolerance using hard values such as  $10.0 / 10.2$ , we suggest entering either  $10.0 +0.02/0.0$  or  $10.1 \pm 0.01$ .

## Chapter 6 – Tolerance

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On every tolerance dialog, there exists radio buttons to assign a Tolerance Preset. It would only be required that the nominal value be entered followed by the selection of a tolerance preset. For further explanation on tolerance presets, please refer to System Options. To assign a tolerance preset, press the <Alt> + <2> key combination to assign tolerance preset #2 or left click with the mouse on the selection.

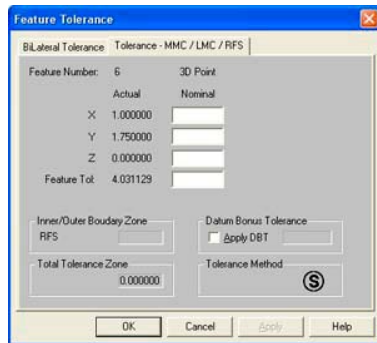
Not all data fields are required to contain data. If you are required only to tolerance the X value on a XY Point feature, enter the X nominal and leave the Y nominal blank. Geomet Junior will then report only the tolerance data on the X-axis values.

*TIP: It is more efficient to move between edit controls using the tab key or the up and down arrow keys on the keyboard. The order of movement on the tolerance dialog utilizing the tab key is Nominal ⇒ Plus ⇒ Minus with each press of the <tab> key. Should you want to reverse that order, press <Shift> + <tab>. The <Enter> key at any time solves the application of the tolerance data and closes the tolerance tool. To navigate only between the edit controls in the Nominal column, use the up and down arrow keys. It is not necessary to locate the mouse, which in this case, makes the tolerance tool very inefficient.*

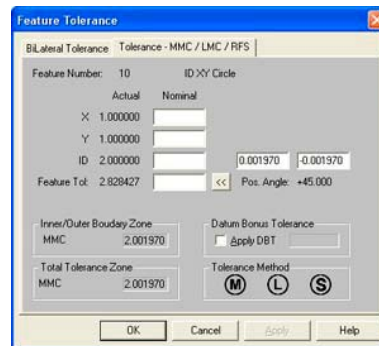
# Chapter 6 – Tolerance

## Working with True Position Tolerance Windows

On valid features, True Position Tolerance may be applied through the standard Tolerance Window. Activating the True Position Window is accomplished by selecting the tab assigned to True Position and labeled “Tolerance – MMC / LMC / RFS”.



*3D Point True Position*



*2D Circle True Position*

The example above shows the True Position Windows for a 3D Point and a 2D Circle. The Tolerance Window will show data fields specific to the feature. In some cases, such as a 3D Point where no form is provided, the MMC and LMC options will not be available.

To obtain the correct True Position reporting, it is important that all data fields are completely filled out.

To switch between MMC, LMC and RFS, left click on the appropriate symbol. If your current PCS contain a Datum Bonus Tolerance, that value will be reported to the right of the check box labeled “Apply DBT”. To use the DBT value in the final solution, place a check mark next to the “Apply DBT”



# Chapter 6 – Tolerance

## Interpreting Linear Tolerance in Geomet Junior

Using a 3D Point as an example, the figure below demonstrates what Geomet Junior reports on the computer display and the next figure the printed result. Please pay special attention to the manner in which "Dev. Tol." (Deviation from Tolerance) is expressed. Geomet Junior displays an actual deviation value when an out-of-tolerance condition exists. This number is the actual deviation from the upper or lower tolerance limit. By contrast, plus and minus symbols are used to indicate an "In tolerance" condition and simultaneously provide a measure of tolerance bandwidth utilization. In particular, each plus or minus sign represents 25% of the upper or lower tolerance bandwidth respectively.

No.	Feature	ACTUALS	Dev.Tol.	Dev.Nom.	NOMINALS	+TOL.	-TOL.
4	3D Point						
	X=	1.00000" -		-0.00100	1.00100	0.00500	-0.00500
	Y=	1.25000" -0.02000	-0.02000	-0.02500	1.27500	0.00500	-0.00500
	Z=	0.00000" ++		0.00250	-0.00250	0.00500	-0.00500

No.	Feature	Actual	Dev. Tol.	Dev. Nom.	Nominal	Tol. Plus	Tol. Minus
4	3D Point						
	X	1.00000"		-0.00100	1.00100	0.00500	-0.00500
	Y	1.25000"		-0.02500	1.27500	0.00500	-0.00500
	Z	0.00000"		0.00250	-0.00250	0.00500	-0.00500

The following table illustrates examples of the Dev. Tol. column with symbols and out-of-tolerance conditions

+	the actual lies between 0 and 25% of the plus tolerance bandwidth.
--	the actual lies between >25% and <= 50% of the minus tolerance bandwidth.
+++	the actual lies between > 50% and <= 75 % of the plus tolerance bandwidth.
0.0055	the upper tolerance limit has been exceed by 0.0055.

When Geomet Junior prints a report, the "Dev. Tol." column provides a scalable graph, which represents the location within the tolerance bandwidth, that the actual is placed.

Dev. Tol.	Dev. Nom.	Nominal
	-0.00100	1.00100
	-0.02500	1.27500
	0.00250	-0.00250

# Chapter 6 – Tolerance

When an out-of-tolerance condition exists, the "Dev. Tol" column prints a value that represents the deviation from either the plus or minus limit. The "Dev. Tol." graph is available by default on all printed reports. Should you elect to always display the deviation value, the setting can be found in System Options, Report Config page.

## Datum Bonus Tolerance

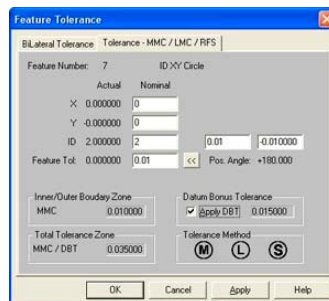
Datum Bonus Tolerance, (DBT) is available in a Part Coordinate System that has been built using a diameter as the origin. The DBT process will determine the amount of MMC or LMC available from the measurement of the diameter. This DBT value is then included when working with positional tolerance related features.

### Determining DBT

To determine the value of DBT available in Geomet Junior it is **mandatory to follow these steps**. Our example will use a 2D XY bore as the origin for our PCS being built. Measure the bore as a Circle and apply a tolerance to the size. By applying the tolerance, Geomet Junior can then determine the LMC or MMC value from the tolerance limits.

When the tolerance has been applied, press the Origin key, <I> or the menu [PCS => Origin]. Set the origin on both the X and Y directions. During the origin process, Geomet Junior will assign the DBT value to the projection plane, in our case the XY plane.

### Applying DBT



Applying Datum Bonus Tolerance

Applying DBT to a qualifying feature is accomplished during the tolerance process. In the feature tolerance dialog, the value of DBT is displayed in the group titled "Datum Bonus Tolerance". Place a check next to the "Apply DBT" and the Total Tolerance Zone will update with the new value.

# Chapter 6 – Tolerance

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## GeoTol – Form Tolerance

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Keyboard: t

Menu: Tolerances ⇒ GeoTol Form Tolerance

All GeoTol functions are combined in the single function which when activated determines the appropriate geometric element based on the feature type. The following table lists the available geometric elements for each feature type.

Geometric Element	Associated Feature Type
Angularity	Line, Plane, Cylinder, Cone
Circularity	Circle, Cylinder Cone, Sphere
Concentricity	2D Points, Circle, Cylinder, Cone, Line, PCS Origin, Related Feature
Cylindricity	Cylinder
Flatness	Plane
Parallelism	Line, Plane Cylinder, Cone, PCS Base Planes
Perpendicularity	Line, Plane, Cylinder, Cone, PCS Base Planes and Axes
Straightness	Line

The GeoTol wizard can be configured to work in the following modes:

**Current PCS:** In this mode, GeoTol references the last measured or constructed feature to the current PCS. Example; if the last feature is a circle, then GeoTol will validate the choices to Circularity and Concentricity to the PCS Origin. If the last feature was a cylinder, then GeoTol validates the choices to include Angularity, Concentricity, Cylindricity, Perpendicularity and Parallelism.

**Last Feature:** In this mode, GeoTol references the last measured or constructed feature to the previous compatible feature. For example; if the last two features in your inspection report are two XY Circles, the GeoTol tool will validate Circularity and Concentricity.

**Other Feature:** This mode is similar to Last Feature, however it allows you the choice of selecting a feature by number. For example, if your last feature is #29 and is a 2D Circle you can reference it to #12 also a 2D Circle to obtain Concentricity. It is not necessary to work exclusively on the last two features in your inspection report.

Circularity, Cylindricity and Flatness work exclusively on the last measured feature without regard to the mode selected.

## Chapter 6 – Tolerance

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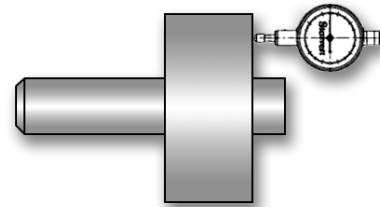
A well thought out process should be considered when using GeoTol functions to obtain results. To ensure sound results always consider using a large set of data points for defining the feature. For example taking 4 data points to define a circle may deliver acceptable results for size and location, but is insufficient to provide a circularity result. At the minimum, Geomet Junior suggests a minimum of 16 data points on smaller circles from which you want GeoTol results.

### RunOut – Cylinder / Plane

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Menu: Tolerances ⇒ RunOut ⇒ Cylinder/Plane

Not all GeoTol functions are accessed through the GeoTol wizard. Some special cases are separate functions such as the RunOut between and Plane and Cylinder. The Cylinder / Plane Runout routine is designed to calculate the runout deviation of a Cylinder that is perpendicular to a plane at a given radial distance. This calculation would be similar to placing a test indicator on the end of a cylinder whose lateral position is fixed. The indicator would be placed in a fixed position identified as the radial distance. The part would be turned slowly and the Total Indicator Reading (TIR) would be recorded, *see figure*.



### Setup for a Runout

The first requirement to making this routine successful is to measure a cylinder and plane with sufficient data points. Under these conditions the cylinder and plane should be measured with at least 30 points, more if necessary to locate a representation of the variances within the surface.

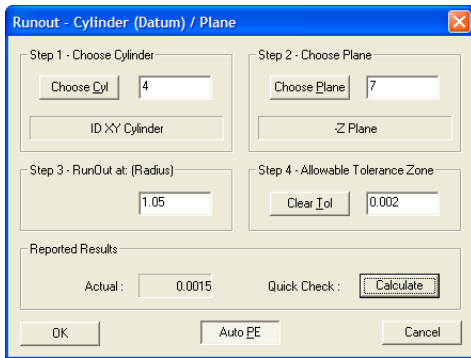
When performing the Runout test manually, as shown in the example above, you are actually capturing millions of data points while rotating the part. The indicator will show a displacement from the highest to the lowest reading. This spread will represent the Runout.

A CMM, which builds features using discrete numbers of data points will often never locate the total spread. The features are created using a best-fit algorithm. The result will contain a small uncertainty between the reported feature and the actual work piece. Therefore the higher the number of data points used, the greater the chance you will return a runout that resembles the manual method.

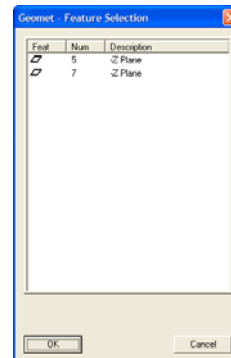
# Chapter 6 – Tolerance

## Determining the RunOut Value

Once you have completed measuring the Cylinder and Plane, activate the Runout routine, through the main drop down menus [*Tolerances* ⇒ *RunOut* ⇒ *Cylinder/Plane*]. The Runout tool will appear.



Cylinder/Plane Runout Tool



Feature Selection Tool

### Step 1 – Select Cylinder

Press the <Choose Cyl> button and the Feature Selector will appear with a filter activated to show only Cylinders in your inspection report, *see figure Feature Selection Tool*. Highlight the cylinder required for the Runout routine and press <Ok>.

### Step 2 – Select Plane

Press the <Choose Plane> button and the Feature Selector will appear with a filter activated to show only Planes. Highlight the plane required for the Runout routine and press <Ok>.

### Step 3 – Set the Radial Test Length

In this step, enter the radial distance from the axis of the cylinder you would like the runout to be calculated at. This can be explained as the location you would set the test indicator at.

### Step 4 – Allowable Tolerance Zone

This runout tolerance value is the total allowable deviation of the actual TIR value. If the calculated deviation exceeds this amount, it is considered out-of-tolerance.

# Chapter 6 – Tolerance

## <Calculate> Button

The Calculate button updates the **Actual:** data field and is an optional step before building the inspection step.

## <Auto PE> Button – Geomet Junior Plus

The <Auto PE> button is a push-on, Push-off button. When locked in the down state, as shown in example on the previous page, Geomet Junior will automatically attach a Print Exception flag on the result when it attaches the inspection step, *see Print Exceptions for additional information.*

## <Ok> Button

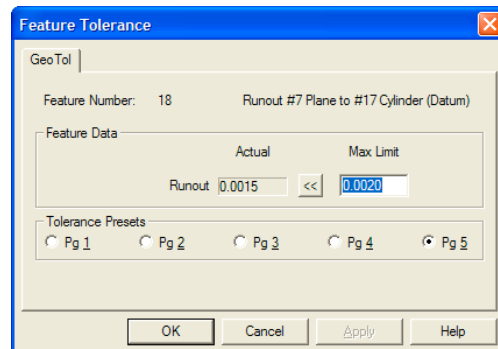
To record the results in the inspection report, press the <Ok> button. An entry will be made, *see figure below.*

9	Runout #7 Plane to #4 Cylinder (Datum)				
	• Value=	0.0015" +++	0.0015	0.0000	0.0020

*Runout Reported Results*

## Adjusting the Tolerance Limit

You can at any time adjust the maximum allowable tolerance limit. To start, highlight the feature in the inspection report area and right-click to activate the feature sub-menu. Choose Edit Tolerance from the list and the Tolerance Dialog will appear, *see figure.* After making any necessary changes, press the <Ok> button and the reported results will be updated.



# Chapter 7 – Constructions

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## Chapter 7 – Constructions

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# Chapter 7 – Constructions

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# Chapter 7 – Constructions

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## Constructions

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Geomet Junior has the capability to create new features derived from other measured or constructed entities. During the inspection process, features are often created to solve complex solutions. The constructions available include:

- Bisect
- Intersect
- Angles
- Distances

### Selecting Features for Constructions

The process of selecting compatible features from your inspection for use with a Construction command can be accomplished through three methods.

#### Method 1- Implicit Selection

This method assumes there are no highlighted features in your inspection report. The construction command will then work exclusively on the last two compatible features in your inspection report. The construction command will look through transparent features such as state changes, text and other non-geometry entries and extract two measured or constructed features for use in the construction.

#### Method 2 – Targeted Highlighting

The operator may elect to highlight two random features then invoke the construction command. The construction command will extract those highlighted features to solve for a solution. Care should be taken when selecting random features to follow the rules of compatibility. These rules vary based on the construction command being applied. Where utilizing 1D and 2D features, the selected features must share the same PCS, which is also the current PCS.

# Chapter 7 – Constructions

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## Bisect

---

The Bisector routine determines the bisecting or symmetry feature between compatible features. For example, bisecting two non-parallel planes will result in two alternative bisecting planes (90° apart). The operator may then select one.

The Bisect Command is activated by:

Keyboard:     a

Menu:           Construct ⇒ Bisect

The Bisect command requires two compatible features to create a solution. Should it determine the features do not follow the compatibility rules an error message will display and the command will abort.

	Points			Line		Circle	Plane	Cyl	Cone	Sphere
	1D	2D	3D	2D	3D					
<b>1D Pt.</b>	1D Pt.									
<b>2D Pt.</b>		2D Pt.	3D Pt.			2D Pt.		2D Pt.	2D Pt.	3D Pt.
<b>3D Pt.</b>		3D Pt.	3D Pt.			3D Pt.		3D Pt.	3D Pt.	3D Pt.
<b>2D Line</b>				2D Line	2D Line 3D Line			2D Pt. 3D Line	2D Pt. 3D Line	
<b>3D Line</b>								2D Pt. 3D Line	2D Pt. 3D Line	
<b>Circle</b>		2D Pt.	3D Pt.					2D Pt.	2D Pt.	3D Pt.
<b>Plane</b>							Plane			
<b>Cyl</b>		2D Pt.	3D Pt.	2D Pt. 3D Line	2D Pt. 3D Line	2D Pt.		2D Pt. 3D Line	2D Pt. 3D Line	3D Pt.
<b>Cone</b>		2D Pt.	3D Pt.	2D Pt. 3D Line	2D Pt. 3D Line	2D Pt.		2D Pt. 3D Line	2D Pt. 3D Line	3D Pt.
<b>Sphere</b>		3D Pt.	3D Pt.			3D Pt.		3D Pt.	3D Pt.	3D Pt.

# Chapter 7 – Constructions

## Intersect

The Intersect Command is activated by:

Keyboard: d

Menu: Construct ⇒ Intersect

The Intersect command determines the characteristics of the intersection of two compatible features. Intersection works with the following combinations:

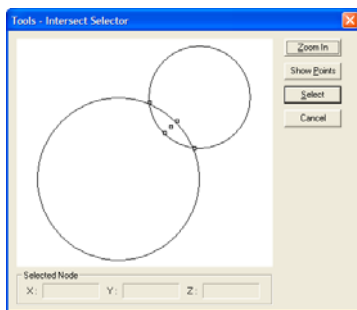
	Points			Line		Circle	Plane	Cyl	Cone	Sphere
	1D	2D	3D	2D	3D					
1D Pt.										
2D Pt.										
3D Pt.										
2D Line				2D Pt.		2D Pt.	1D Pt. 3D Pt.			3D Pt.
3D Line					3D Pt.		3D Pt.			3D Pt.
Circle				2D Pt.		2D Pt.				
Plane				1D Pt. 3D Pt.			3D Line	3D Pt.	3D Pt.	2D Circle
Cyl							3D Pt.	3D Pt.	3D Pt.	3D Pt.
Cone							3D Pt.	3D Pt.	3D Pt.	3D Pt.
Sphere							2D Circle	3D Pt.	3D Pt.	

The Intersect command requires two compatible features to create a solution. Should it determine the features do not follow the compatibility rules an error message will display and the command will abort.

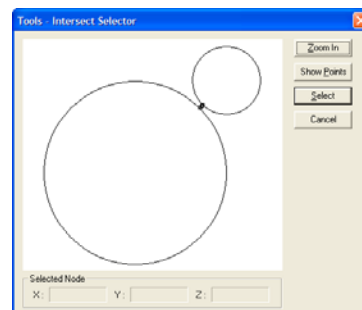
### Special Intersection Applications

#### Circle / Circle

The intersection between two Circles provides 1, 3 or 5 possible solutions. All solutions are 2D Point features in the same PCS projection plane as the circles. In left figure, we have two circles that intersect. In the right figure, we have two circles that do not intersect, but can have valid solutions.



*Intersecting Circles*



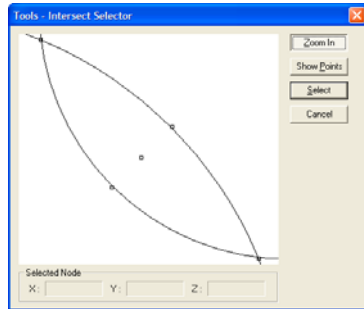
*Non-Intersection Circle*

# Chapter 7 – Constructions

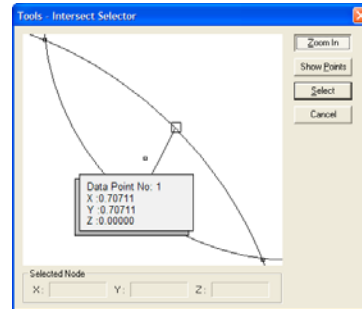
The chart below demonstrates the 2D Point assignment to the nodes shown in figures on the previous page.

	Intersecting Circles	Non-Intersecting Circle	Notes
<b>Node 1</b>	Tangent Point on Circle 1		Reported as 2D Point and a miss distance.
<b>Node 2</b>	Tangent Point on Circle 2		Reported as 2D Point and a miss distance.
<b>Node 3</b>	Mid Point between Centers, or Single contact point on the circles.		Mid Point is reported as 2D Point and a miss distance.
<b>Node 4</b>	Intersection Point 1	N/A	
<b>Node 5</b>	Intersection Point 2	N/A	

When the node selection is obscured in the graphics display, press the <Zoom In> button will redraw the graphics to encompass only the nodes for easier selection, *see figure below.*



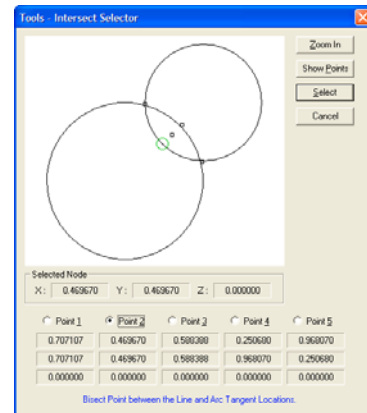
*Zoom-In Function*



*Selecting a Node*

Selecting a node can be accomplished through various means. The simplest method is to move your mouse over a node in the graphics area. When the mouse pointer touches a node, a small display is shown which will indicate the XYZ position and node ID number. Left-click on the node and it changes into a circle indicating that is the selected node. Press the <Select> button and the solution will be inserted into the inspection report.

To view all possible point solutions, press the <Show Points> button. The display will expand to show the 3 or 5 possible solutions, see figure 5. You can select a node in the list by placing a bullet next to the corresponding node ID.



# Chapter 7 – Constructions

## Circle / Circle - Single Point Solution

There exists one condition that results in one intersect solution. That is where the circles touch at only one point. When asking for the Intersection, the system will report the one solution in your inspection report. This point corresponds to node ID number 3 from the table above.

However, when capturing measured results this condition is rare. When Geomet Junior determines the two circle do not repeat the touching in only the one selected point, or may not even intersect, the solution will default to the mid point and miss distance.

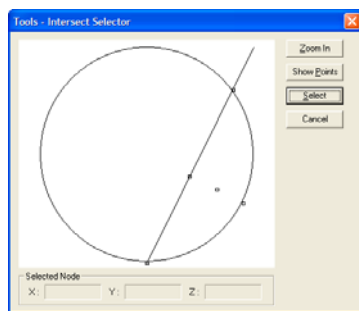
## Circle / Circle - Default Reporting

When teaching a part for auto-inspection, variances to the part during manufacturing may affect the reported intersection solution. For example, the circle may intersect resulting in 5 possible solutions during the self-teach phase, but later during the inspection routine they fail to intersect resulting in 3 possible solutions.

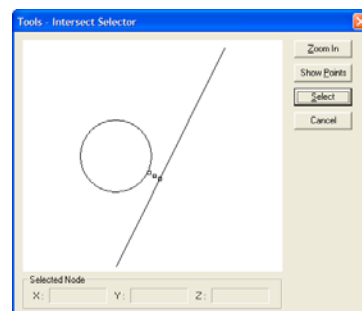
If the original solution to report was node #4 or #5 when they intersected, they will report as node #3 during inspection.

## Circle / Line

The intersection between a Circle and Line provides 1, 3 or 5 possible solutions. All solutions are 2D Point features in the same PCS projection plane as the features. In figure 6, we have two circles that intersect. In figure 7, we have two circles that do not intersect, but can have valid solutions.



*Intersecting Line/Circle*



*Non- Intersecting Line/Circle*

# Chapter 7 – Constructions

---

The behavior of the graphic intersection tool for Circle/Line is the same as described in Circle/Circle above. Please refer to that section for assistance.

	Intersecting Circle/Line	Non-Intersecting Circle/Line	Notes
<b>Node 1</b>	Tangent Point on Circle		Reported as 2D Point.
<b>Node 2</b>	Tangent Point on Line		Reported as 2D Point.
<b>Node 3</b>	Mid Point between Node 1 and 2, or Single tangent point.		Mid Point is reported as 2D Point and a miss distance.
<b>Node 4</b>	Intersection Point 1	N/A	
<b>Node 5</b>	Intersection Point 2	N/A	

## Circle / Line - Single Point Solution

There exists one condition when there can be one solution. That is where the circle and line touch only at the tangent point. When asking for the Intersection, the system will report the one solution in your inspection report. This point corresponds to node ID number 3 from the table above.

However, when performing repeated inspections this condition is rare. When Geomet Junior determines the two features do not repeat the touching in only the one selected point, or may not intersect, the solution will default to the mid point and miss distance.

## Circle / Line - Default Reporting

When teaching a part for auto-inspection, variances to the part during manufacturing may affect the reported intersection solution. For example, the two features may intersect resulting in 5 possible solutions during the self-teach phase, but later during the inspection routine they fail to intersect resulting in 3 possible solutions.

If the original solution to report was node #4 or #5 when they intersected, they will report as node #3 during inspection.

# Chapter 7 – Constructions

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## Angle

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The Angle routine determines the angle between two reference features. Angle works with the following combinations:

Line ⇒ Line	Line ⇒ Plane
Plane ⇒ Plane	Cone ⇒ Plane
Cylinder ⇒ Plane	Cone ⇒ Cone
Cylinder ⇒ Cylinder	

The Angle Command is activated by:

Keyboard: f

Menu: Construct ⇒ Angle

The Angle command requires two compatible features to create a solution. Should it determine the features do not follow the compatibility rules an error message will display and the command will abort.

The reported value between two features where one or more features are 2D results in a single projection value. For example, the angle between a 2D XY Line and ZX Plane, results in an angle reported in the XY PCS base plane.

	2D Line	3D Line	Plane	Cylinder	Cone
Angle derived from :	Projected Line Vector into the PCS	Line Direction Vector	Normal Vector	Axis	Axis

The angle between two 3D features, such as a plane and cylinder reports the theta angle, or if elected, the 3 projection angles.

To switch between theta and projection angles, highlight the angle feature in the inspection report and right-click to activate the menu. Choose [*Projection Angles*] when the current state is theta, or choose [*Theta*] when the current state is projection angles.

Reported angles can be shown either as degree.decimal format or degree-minutes-seconds.

# Chapter 7 – Constructions

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## Distance

---

The Distance Command is activated by:

Keyboard:     s

Menu:           Construct ⇒ Distance

Features must share a common axis and are contained in the current Part Coordinate System. For example a 2D XY Circle shares a common axis of Y with a 2D line reporting the Y-axis pierce value. The XY Cylinder Axis Pierce Point shares both the X and Y with the reported position of a 3D Sphere.

Should the distance routine determine there are no shared axes between the two features, an error will be reported. The Distance routine utilizes the current Reporting Format under the following conditions.

### Reporting Formats

**Cartesian:** Calculates the results in X, Y, and/or Z values that are parallel to the current Part Coordinate System.

**Polar:** Calculates the results in Radius and project angle components of 2D and 3D distance solutions. Should the distance routine determine only a 1D solution is possible, the reporting format will default to Cartesian.

Special considerations should be taken when using the Distance function. For example the distance between two -Z planes is calculated along the Z-axis of the current Part Coordinate System. This may not reflect the desired results when the data points used to calculate the planes are taken a distance from the PCS Origin. Any parallel deviation between the planes will accentuate the distance value when projecting to the Z-axis of the PCS.

The chart below illustrates the feature characteristics used in distance reporting.

Feature Type	Reporting Characteristics	Reporting Axis
1D Point	Reported position along the Current PCS Axis.	1D
2D Point	Projected 2D Point in the reported PCS Base plane.	2D
3D Point	Center XYZ Reported Position.	3D
2D Circle	Projected 2D Point in the reported PCS Base plane.	2D
2D Line	Projected PCS Axis Pierce Point.	1D
3D Line	PCS Base Plane Pierce Point.	2D
Plane	Project PCS Axis Pierce Point.	1D
Cylinder	PCS Base Plane Pierce Point.	2D
Cone	PCS Base Plane Pierce Point.	2D
Sphere	Center XYZ Reported Position.	3D



# Chapter 7 – Constructions

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## Feature Recall

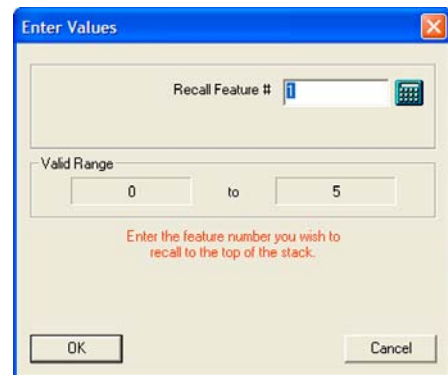
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The Feature Recall Command is activated by:

Keyboard: h

Menu: Construct ⇒ Recall Feature

The Feature Recall Tool is designed to copy an existing feature and append it to the inspection report. The newly created feature is considered a constructed feature and is not measured during the inspection.



Some of the benefits of recalling a feature is that the original feature is not manipulated where the recalled feature can be changed to show other attributes or even to project it into a different PCS.

Care should be taken where recalling features into a different PCS from which it was originally built in. For example to recall a 2D feature and force it to be projected into a skewed PCS can result in erratic results.

## Feature Recall Tool

Enter the number of the entity into the Feature Recall Tool to recall to the top of the inspection stack. To complete the recall procedure, press the <Ok> button and a new feature will be appended to the inspection report. Should you try to recall features into a different PCS, you will be prompted with instructions. These instructions will guide you to force a recall or recall the reported position as a 3D Point that will eliminate projection errors.

## On Demand Recall

You can select a feature in the inspection report and right click to activate the sub menu. Select [*Recall Feature*] or [*Recall Features*] if more than one feature is selected. This will perform the recall on demand.

# Chapter 7 – Constructions

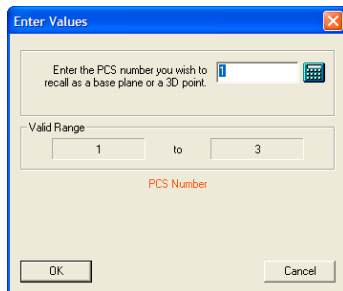
## Recall PCS Base Components

The Recall PCS Base Components Command is activated by:

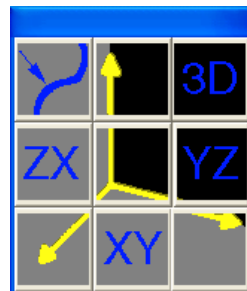
Keyboard: shift + H

Menu: Construct ⇒ Recall PCS Base Components

Part Coordinate Systems contains 3 orthogonal planes that define the XY, YZ and ZX base planes. There is also a 3D Point that defines the origin. These components can be recalled as constructed features.



Select a PCS



Choose Component

When you activate the command you will be prompted to choose a PCS by its number. *If there is only one PCS, this step will be skipped automatically.* The next tool will allow you to choose one of the PCS components. Your choices are:

Button	Description
XY	Recalls a XY Plane
YZ	Recalls a YZ Plane
ZX	Recalls a ZX Plane
3D	Recalls a the Origin as a 3D Point

The features created are compatible with all construction and tolerance tools.

# Chapter 7 – Constructions

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## Construct New Features

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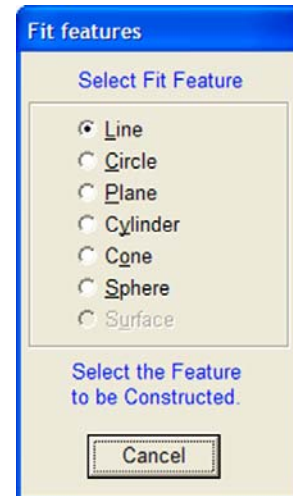
The Construct Features Command is activated by:

Keyboard: g

Menu: Construct ⇒ Line, Construct ⇒ Circle, Construct ⇒ Plane

To perform the Construct Command, start by measuring or recalling compatible features. For example capture a series of circles around a bolt hole pattern. Then fit a circle through those measured circles to determine the location of the bolt hole pattern as a single entity.

To perform the construct, press the <g> key to activate the Construct Features dialog. Click on the desired feature. In this example, click on the Circle bullet. You will be prompted for the number of features to use in the construction. Press <Ok> and Geomet Junior will create a new Circle feature in your inspection report.



A constructed feature can have tolerance attached and be used in PCS creations and even other constructions.

# Chapter 7 – Constructions

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# Chapter 8 – Support Tools and Features

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## Chapter 8 – Support Tools and Features

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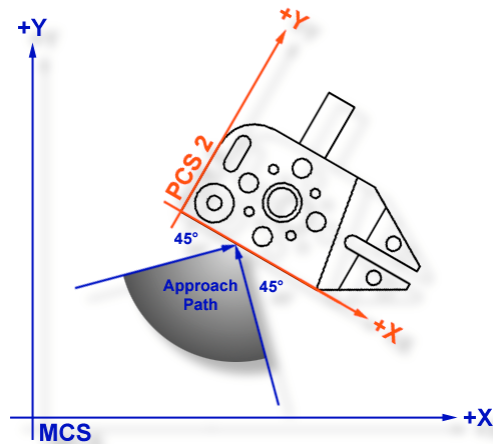
# Chapter 8 – Support Tools and Features

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# Chapter 8 – Support Tools and Features

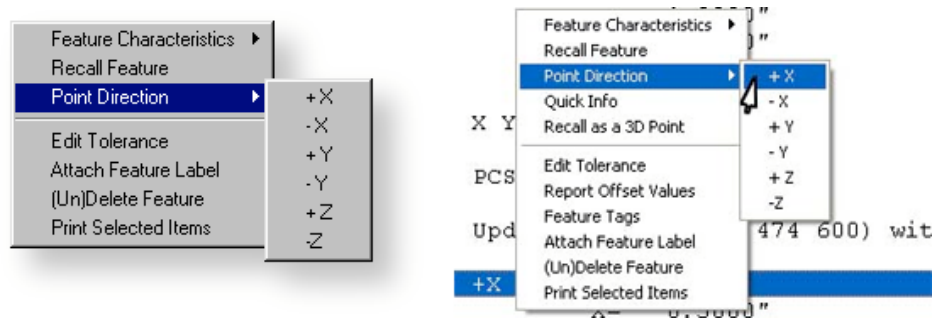
## Understanding Auto Direction Sensing

Using auto direction on 1D Points can lead to erroneous reported values if used incorrectly. Auto direction relies on a smooth approach, from you the operator, in capturing of a data point. The process of determining the approach vector involves the CMM interface card to maintain a rolling IJK vector based on the last five reported values. The interface card updates the current position in the MCS on a programmable time interval from 20 to 200 milliseconds.



Auto Direction Approach vector

When you are approaching your work piece, it is required that you make contact while remaining in a  $\pm 45^\circ$  approach, see figure above. In this example, if we remained in the approach zone we will capture a data point that will be reported as a +Y point. If the operator did not remain in the approach zone the 1D Point might report a + or - X Point from which we will have to correct the probe compensation error. Most common occurrence of an erroneous data point comes from operators who approach the surface, and then pause during the approach and attempt to make contact under extremely slow speeds, which causes variations in the path toward the surface.



1D Point Correction Sub-menu (both styles shown)

## Chapter 8 – Support Tools and Features

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To correct the reported direction of a 1D Point, highlight the feature by left clicking on it, then right-click to bring up the feature menu, *as shown in the previous figure*. Select *[Point Direction]*, which will offer a sub-menu, with all six probing directions available. Choose the correct 1D Point direction and your part inspection will update with the correct 1D Point. *Note: Once a feature has been referenced it can not be changed or edited. For example, if a feature was used in the construction of a PCS, it will be locked from changes. This is identified by the inclusion of a '1' next to the feature number, example " 12<sup>1</sup> ".*

Using Auto-Direction with multi-point features such as circle, lines and planes can also incorrectly report feature characteristics. This occurs when capturing data points inconsistently or by capturing data points at a high rate. As previously mentioned, the calculation of the direction vector for the probe works off the speed of the interface and should that rate of point capture be too high, the changes in direction going toward, then backing off the data point will create a poor direction vector.

Since touch probes can be adversely effected by speed so can the auto-direction tool. We suggest the use of a smooth consistent approach speed when capturing data points.

### Activate Auto Direction Sensing

Activate the Auto Direction sensing by going to the System Options, <F9> or *[System⇒System Options]* from the drop down menu. Place a check next to **Enable Auto Sensing**. If your CMM interface does not supports Auto Direction Sensing, the check mark will clear automatically.

During the inspection process you may require to control the Auto Direction sensing manually. This can be accomplished through the Feature Measurement Toolbar or by pressing the <u> key on the keyboard. The Geomet Junior Status banner located on the bottom of the window will indicate the state of the sensing option.

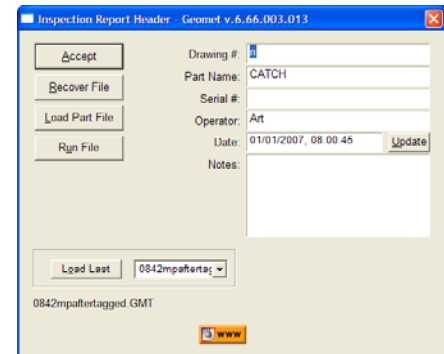


# Chapter 8 – Support Tools and Features

## Program Header

The Program Header displays when Geomet Junior is first started, a new file has been requested or when opening a file. The program header provides the necessary fields to update the report header for the inspection.

To activate the program header once the inspection report has been started can be accomplished through the drop down menus [*Report Controls* ⇒ *Report Header*] or by double clicking in the report header area of the displayed inspection.



There are additional functions the report header provides.

### <Load Last>

Maintains a listing of the last five previously opened files which is located in a drop down list next to the Load Last button. Once you select the file from the list, press the button <Load Last> to open that file.

### <Run File> - Junior Plus Only!

With an inspection file already opened, the <Run File> button enters auto-cycle mode. To auto-cycle a file can also be done from the drop down menus [*File* ⇒ *Run*].

### <Load Part File>

This operation performs the same function found in the drop down menus, [*File* ⇒ *Open*]. A test is performed to ensure you save any changes to the inspection report already open.

### <Recover File>

Geomet Junior maintains a backup file of your current inspection report while in self teach mode. With the completion of a program step, the complete inspection program is written to the hard drive as a backup. Should any unexpected problem occur that causes potential loss of data, such as a power failure, the Recover File process will read in the backup file. You should then be able to continue your inspection.

A note of caution on CMMs that do not have a home position, you should run the complete program after a recover to rebuild the Part Coordinate Systems before continuing your inspection.

# Chapter 8 – Support Tools and Features

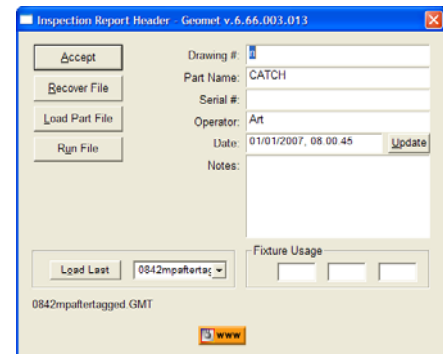
## Fixture Usage Data Fields – Geomet JuniorPlus!

Geomet JuniorPlus allows the tracking of up to 3 unique inspection identifiers for a part being inspected. We call these identifiers “Fixture Usage” from the original purpose where a fixture ID was added to the inspection report.

An example on using these Fixture fields would be to identify what machining center a production part was manufactured on. The manufacturing department may have many machining centers all making the same part. We had one company that used over 50 machining centers all making the same part!

When ready to measure, the operator could type in the note section of the header the machining center ID. Unfortunately the notes section of the header does not provide any sorting capabilities. The Fixture Usage fields do. When inspecting the production, enter the machining center ID in the Fixture Usage fields and then sorting can be done to group all production inspected on the machining center it was produced on.

This is helpful when performing SPC on production. By default, Fixture Tracking is not active. To activate fixture support, place a check next to **Enable Fixture Reporting** on the Geomet JuniorPlus System Options page.



# Chapter 8 – Support Tools and Features

## Restart Program Header - JuniorPlus Only!

At the end of an inspection run, the Restart Options dialog will appear. There are 5 options available after the inspection run.

### <Restart>

Restarts the current inspection starting from step 1.

### <Run Steps>

This command works with both manual and DCC systems. When you select this function, the Feature Selection tool will display the features in the inspection report. Choose the feature that Rerun will continue from. Geomet Junior will then remove all steps from the last feature, up to and including the feature you have selected.

On a DCC system, a Target Tool will appear to guide you safely to the starting point. When you have placed the CMM at this starting point, press <Continue> and the inspection will continue under DCC control from that location.

### <New>

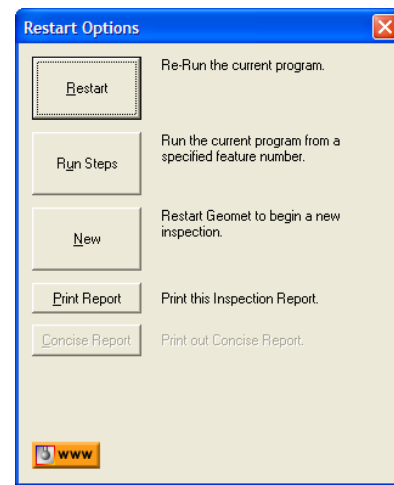
Starts a new inspection prompting you to save your current inspection file.

### <Print Report>

Performs an On Demand printout of the complete inspection report in standard format.

### <Concise Report>

This function is reserved for Geomet 101 and above.



# Chapter 8 – Support Tools and Features

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## Text Features

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Geomet Junior offers several text and prompt support features for use within the inspection program. This support varies based on inspection needs and includes the ability to pause the inspection program during execution to allow the viewing of an image or to change a manual-indexing probe. Choose from a topic below for expanded support.

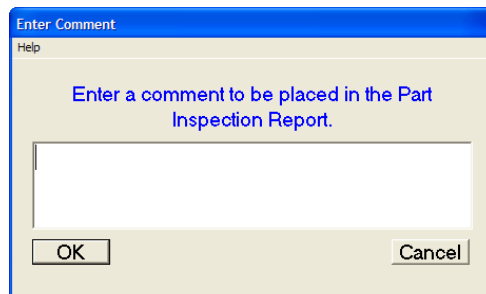
## Basic Text

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Keyboard: y

Menu: Measure ⇒ Text

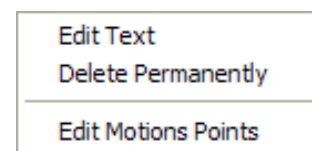
The Basic Text routine permits comments to be written to the inspection report as a feature step. This text is entered during the self-teach operation. When executing the part program, the text is placed in the inspection report and proceeds to the next step. During execution, the text can not be edited.



*Manual Step Sample Output*

## Edit Text Features

All text features can be edited to revise the text or PE tag. To start the editing process, highlight the text statement in the inspection report and activate the feature sub-menu by right clicking, *see figure*.



Choose <Edit Text> and the appropriate text dialog will appear from which you can then edit the text.

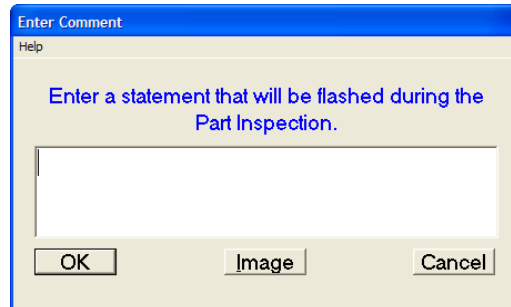
# Chapter 8 – Support Tools and Features

## User Prompt with Image Support

Keyboard: shift + Y

Menu: Measure ⇒ User Prompt

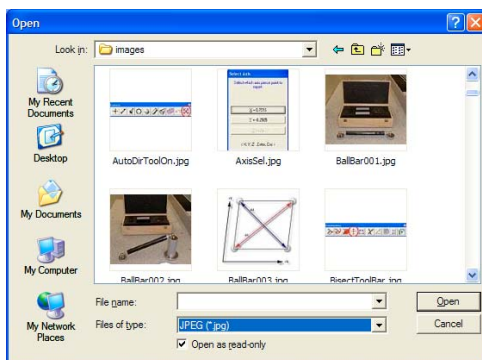
The User Prompt permit comments to be written to the inspection report and images to be displayed during the part program execution.



*User Prompt Opening Dialog*

The advantage a User Prompt has over the Basic Text function is that it suspends execution of the part program until the operator accepts the user prompt. This can be very helpful when the operator must interact with the inspection process. For example: The User Prompt may suspend execution and prompt the operator to insert a thread gage before measuring the location of a threaded hole.

To use the Image support, press the <Image> button. A standard Windows file location dialog will appear which you use to locate the image (BMP, JPG) to view.



*Open File Selection*



*User Prompt with attached Image*

Once the image is loaded, the full path name is inserted in the text entry control. You can type over this pre-entered text. If you want to preserve the path and file name, position the cursor behind the text line and advance to the next line by pressing <Ctrl+Enter>.

## Chapter 8 – Support Tools and Features

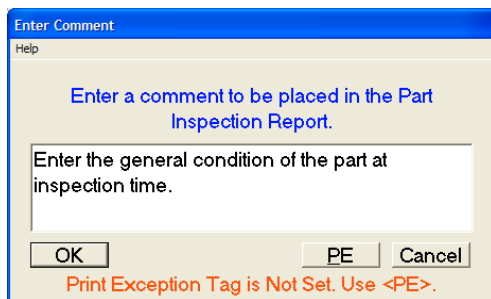
Images that are larger than the available area in the dialog box will automatically be reduced to fit. Images that are smaller are displayed in their actual size. The <ReSize> button will stretch smaller images to fit the available area. Geomet Junior maintains a link to the actual image file, *therefore the image file should not be moved from its original location on the hard drive.*

When the inspection program is run, execution will pause when the User Prompt is encountered. Execution will resume when the operator presses the <Ok> button.

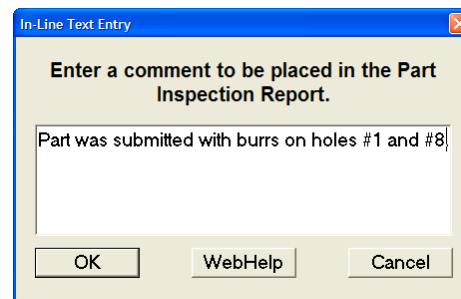
### In-Line Text Entry – JuniorPlus Only!

Keyboard: alt + Y

In-Line Text Entry allows the user to suspend execution of a part program and enter text. The behavior of the In-Line text feature is similar to the User Prompt (without image support). When the pause in program execution occurs, the operator then has an opportunity to enter new text. This text becomes part of the final inspection report.



*Enter instructions for In-Line Text*



*During run time.*

In the examples above, the image on the left is the setup dialog for In-Line text. Here the programmer would enter instructions, which at run time, will instruct the operator to add comments responding to the request.

The image on the right is what the operator would see. Only upon completion, will the inspection continue to the next step.

4 Part was submitted with burrs on holes #1 and #8.

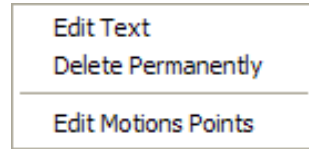
*Text entry made in the final inspection report.*

## Chapter 8 – Support Tools and Features

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### Edit Text Features

All text features can be edited to revise the text, and if applicable, the attached image. To start the editing process, highlight the text statement in the inspection report and activate the feature sub-menu by right clicking with your mouse. If only one feature is highlighted, the edit text dialog will appear. If more than one feature is highlighted, the sub-menu does not provide access to editing the text feature.



# Chapter 8 – Support Tools and Features

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## Report Control Center – JuniorPlus Only!

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Keyboard: F8

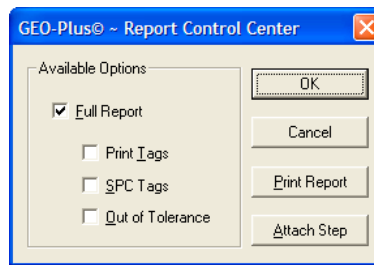
Menu: Report Controls ⇒ Report Control Center

The Report Control Center performs two main operations. The first is manual control to print reports using the standard print format, but controlling whether Print Exception, SPC Tags or Out-of-Tolerance conditions are set. The second function is to add an automatic Print feature to the inspection report.

### On Demand Printing

Activate the Report Control Center from the drop-down menu [*Report Controls⇒Report Control Center*], when or press the function button <F8>.

To control the displayed and printed report, place a check next to the report option.



*Report Control Center*

To view or print only features that have been tagged under Print Exception, place a check next to Print Tags. To combine tags, you can place multiple checks against an option.

### Program Action Step

Configure your report by placing checks on the options to be included in the printed report. Press the <Attach Step> button and an action feature will be added to the inspection report. This new feature will automatically print the configured report at the designated place in the inspection run.



# Chapter 8 – Support Tools and Features

## Print Exception / SPC Tags - JuniorPlus Only!

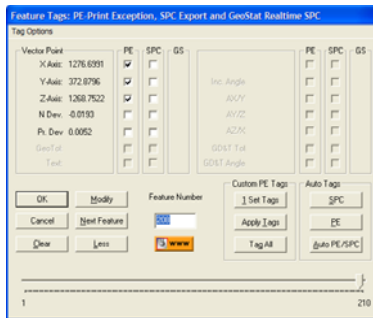
Keyboard: p

Menu: GeoPlus ⇒ Feature Tag

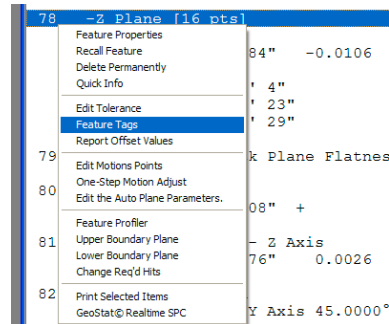
Feature Attribute Tags provide tools to customize printouts, assign feature characteristics for ASCII exporting and build GeoStat database records. The most common use for Tags is to produce inspection reports that contain only the feature values you require.

### Applying Feature Attribute Tags

The Feature Tag dialog provides the necessary tools to assign attribute tags. To activate Feature Tags, highlight the feature in the inspection report and right-click to activate the feature sub-menu. Choose *[Feature Tag]*. Optionally you may use the keystroke <p> or menu options.



Feature Tag Control Panel



Right Click Activation

The Feature Tag dialog will appear configured to the highlighted feature. Within the dialog, there are three columns of check boxes that are defined as:

**PE:** Print Exceptions. When a check is placed against an attribute, the Report Control Center will add that feature and attribute to the printed inspection report. Only tagged features will be printed allowing control over the printing process. The symbol " • " is placed next to the attribute in the full displayed inspection report indicating it has been tagged.

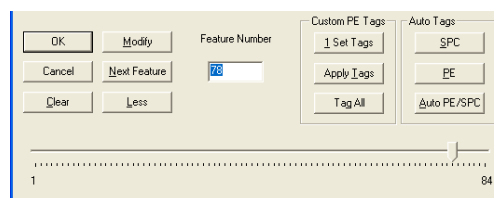
**SPC:** ASCII Export Control. When a check is placed against an attribute, Geomet Junior will export this attribute to an ASCII text file. The exporting process is automatic during an inspection run, or can be done manually through the drop-down menu selection *[File ⇒ Export ⇒ Export ASCII SPC Data]* The symbol " § " is placed next to the attribute in the full displayed inspection report indicating it has been tagged for SPC exporting. The configuration of the exporting formats is controlled in the System Option, SPC Format page <F9> or *[System ⇒ System Options]*.

## Chapter 8 – Support Tools and Features

**GS:** GeoStat Exporting. These attribute controls are available when the Helmel GeoStat program is active on your system. When selecting an attribute for export to the GeoStat Database, a control header is displayed where the SPC header control can be updated. For more information on using GeoStat, please review the GeoStat Manual.

Button	Description
<b>Modify</b>	Commits the current changes made to attribute tags to the current record.
<b>Next Feature</b>	Retrieves the next feature from the inspection report and displays its current values and attributes.
<b>Clear</b>	Clears all flags on the current feature, commits the changes with the Modify button.
<b>More / Less</b>	Expands the Feature Tag dialog to show a slider which can be used to scroll through the features in the inspection report.
<b>1 Set Tags</b>	Activates a Feature Tag Default tool that allows customized default setting for using the one-touch controls, Apply Tags and Tag All.
<b>Apply Tags</b>	Applies the attribute tags to the current, highlighted feature for Print Exception control based on the default tags set in the Feature Tag Default under 1 Set Tags.
<b>Tag All</b>	Applies the attribute tags to all features in the inspection report for Print Exception control based on the default tags set in the Feature Tag Default under 1 Set Tags.
<b>SPC</b>	Applies SPC tags to all reportable attributes on the current highlighted feature. Saves the changes and moves to the next available feature.
<b>PE</b>	Applies Print Exception tags to all reportable attributes on the current highlighted feature. Saves the changes and moves to the next available feature.
<b>Auto PE/SPC</b>	Applies SPC and Print Exception tags to all reportable attributes on the current highlighted feature. Saves the changes and moves to the next available feature.

### Selecting Features



*Report Control Center*

There are several methods to move between inspection report features while in the Feature Tag dialog. Using the <More> button will expand the dialog to show a slider control, *see example above*. With your mouse, move the pointer, which will retrieve and display a feature in the tag dialog. If you want to hide the slider control, press the <Less> button.

## Chapter 8 – Support Tools and Features

Using the keyboard left and right arrows will move the highlighted feature and update the tag dialog. The left arrow moves to the previous feature with every press. The right arrow moves forward. You can also type in a specific feature number in the **Feature Number** control.

The <Next Feature> button behaves the same as the right arrow. NOTE: Use <Modify> to commit the changes before moving to another feature.

### Auto Tags Group

<SPC>, <PE>, <Auto SPC/PE>

This group of controls provides a single function to add checks for all attributes of the current selected feature. Using a 3D Point in Cartesian format as an example, press the <PE> button and two actions will occur. The first action will place a Print Exception check on the X, Y and Z reported values. The second action will move the feature pointer to the next feature available for tags.

### Custom PE Tags Group

This group of controls applies a previously defined template of tags that controls which attributes will receive a Print Exception tag. The application of this template can be on a single feature, or the entire inspection report with one action.

<1 Set Tags>

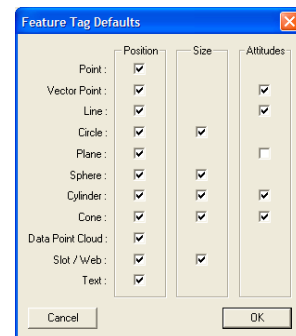
This command provides access to the Feature Tag Defaults Tool, which is used to build a Print Exception template shown at right. There are three selectable attributes for features. These are Position, Size and Attitudes.

The Position column controls the PE flags for X, Y, and Z reported positions in Cartesian and the Polar-Radius, Polar-Angle in Polar mode.

The Size column controls the PE flags for all reported Width, Radius and Diameter sizes.

The Attitudes column controls the PE flags for all reported 2D and 3D projection angles and Normal Vectors of features.

The Feature Tag Defaults Tool can also be started outside of the Feature Tags tool through the menu [*GEO-Plus* ©⇒*Set Feature Tag Defaults*].



## Chapter 8 – Support Tools and Features

### <Apply Tags>

Selecting this command will apply the PE template on the current feature. Using the template shown above on a measured plane will place a PE tag on the Pierce Axis and will not place PE tags on the reported angles. After applying the tags, the feature pointer will move to the next feature available for tags.

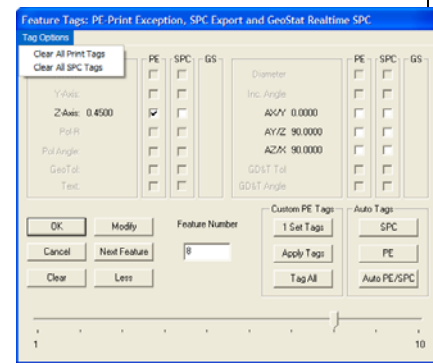
### <Tag All>

This command will parse the entire inspection report and apply the defined PE template to every feature. The command will not place tags on any feature that does not show results. This includes features measured before a valid PCS is established.

### Tag Options Menu

Through this menu there are two commands. The first command [*Clear All Print Tags*] will remove all Print Exception tags in the entire inspection report.

The second command [*Clear All SPC Tags*] will remove all SPC tags in the entire inspection report.



# Chapter 8 – Support Tools and Features

## Report Offset – JuniorPlus Only!

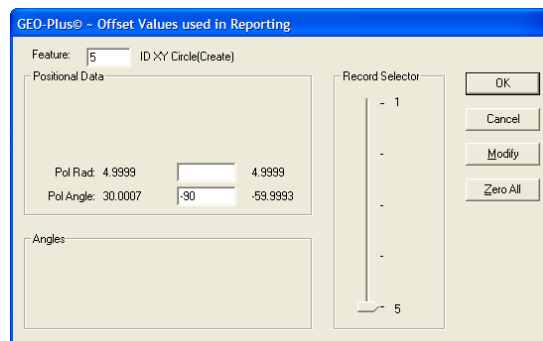
Keyboard: ctrl + y

Menu: GeoPlus ⇒ Apply Report Offset

The Report Offset Tool is used to apply a reference value to a reported attribute on any feature. One example is the rotation of an angle to match the drawing. This allows the printed inspection report to match the drawing. Using an example of a 2D XY Circle, we will apply an offset to the angle.

ID XY Circle [16 pts]			
Cartesian Format		Polar Format	
ID=	0.5000"	ID=	0.5000"
X=	4.3300"	Pol-R=	4.9999"
Y=	2.5000"	Angle=	30.0007°

Here we show the Cartesian and Polar formats for reference. The angle of 30.0007° is referenced off the x-axis going counter clockwise. The drawing references the angle off the y-axis and has a nominal value of 60.0°. To make a correction to the reported value, we can add a nominal offset value to the reported angle.



*Report Offset Tool*

As shown in the Report Offset Tool, we entered a -90 in the **Pol Angle:** control. The result to the reported angle is shown to the right.

ID XY Circle [16 pts]			
Before		After	
ID=	0.5000"	ID=	0.5000"
Pol-R=	4.9999"	Pol-R=	4.9999"
Angle=	30.0007°	Angle=	-59.9993°

The Report Offset can be applied to any feature and any reported position. It is carried forward to inspection runs.

# Chapter 8 – Support Tools and Features

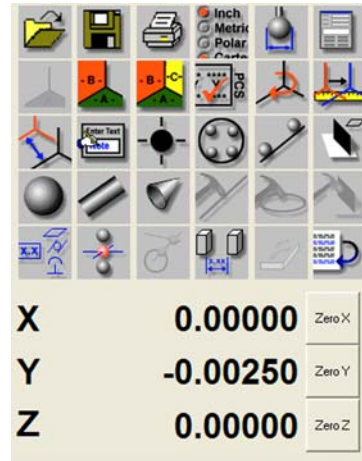
## Junior Digital Readout

Keyboard: ctrl + d

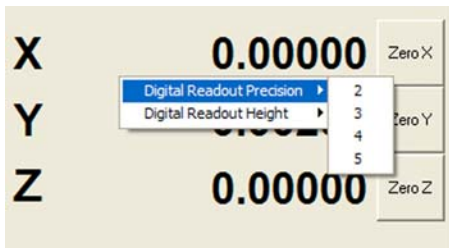
Menu: View ⇒ On Screen DRO

Geomet Junior offers an on screen Digital ReadOut. This DRO is configured to show the location in the current Part Coordinate System or in the Machine Coordinate System on demand.

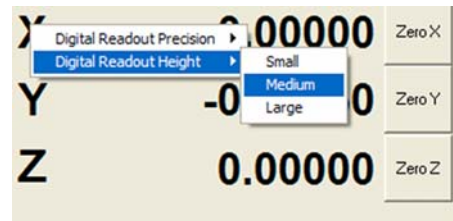
During the inspection process, the DRO will automatically reconfigure itself to work in the latest PCS or ICS and in the current reporting format, Inch or Metric.



To change the precision depth shown on the DRO, right click on the DRO to activate the popup sub menu and move your mouse over the *[Digital Readout Precision]* option and choose a new decimal place value. This value will become the new default.



Setting Precision



Setting DRO Text Size

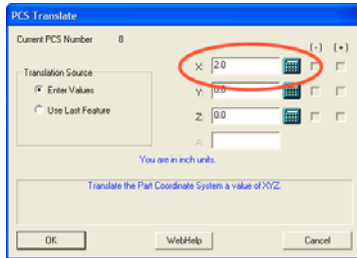
To change the size of the text, click on the DRO to activate the popup sub menu and move your mouse over the *[Digital Readout Height]* option. Choose from one of the three options. The font size you choose will become the new default.

# Chapter 8 – Support Tools and Features

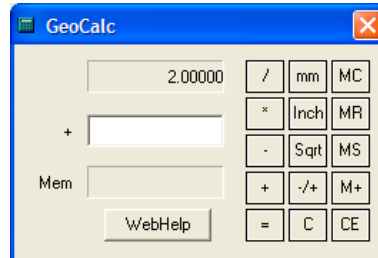
## In-Line Math Calculator

Geomet Junior offers an In-Line Math calculator on supported Dialog Boxes. This allows solving of simple math formulas when the operator enters data.

When a supported dialog box appears that has In-Line Math functionality it will be identified by having a small calculator icon next to the supported control, *see figure below*. Not all dialog boxes support the In-Line Math Calculator.



DRO Sub Menu



Setting Precision Depth

When you see this icon, the edit control directly to the left will offer simple math solving function. To use, begin by entering your formula in the edit control. For example enter "2.0" in the edit control, *as shown above*. Next we press the addition key "+" and Geomet Junior recognizes a math function is being requested and displays a small calculator. NOTE: The In-Line Math Calculator will activate when pressing one of the following:

- Plus <+>
- Minus <->
- Multiply <\*>
- Divide </>

The initial value of "2.0" is passed into the calculator and the math symbol "+" is displayed to the left of the lower edit control. Enter in the number to be added to the upper number and press any of the math keys, "+ - \* / or =" which will solve the current operation and transfer the new value into the upper display awaiting another calculation.

To return the solution to the originating data field, press <Enter>.

## Metric / Inch Conversion

The current value displayed in the upper display will be converted into metric (mm) or inches by pressing the corresponding button. The In-Line math Calculator makes no assignment to the values as they are calculated. By pressing the <mm> button, the upper value will be multiplied by 25.4 and when pressing <inch>, the upper values are divided by 25.4.

## Chapter 8 – Support Tools and Features

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Complete Table of In-Line Math functions:

	Description
<b>+</b>	(Plus) Solves the function $X + Y$ and returns the result in X.
<b>-</b>	(Minus) Solves the function $X - Y$ and returns the result in X.
<b>*</b>	(Multiply) Solves the function $X * Y$ and returns the result in X.
<b>/</b>	(Divide) Solves the function $X / Y$ and returns the result in X.
<b>=</b>	(Equal) Solves the current operation and transfers the result back to the X position. This does not close the Calculator.
<b>mm</b>	Converts the upper value (X) by multiplying it by 25.4.
<b>inch</b>	Converts the upper value (X) by dividing it by 25.4.
<b>Sqrt</b>	Converts the upper value (X) by determining its square root.
<b>-/+</b>	Changes the sign of the lower value (Y).
<b>MC</b>	Clears any value stored in memory.
<b>MR</b>	Recalls the value stored in memory in the lower value (Y).
<b>MS</b>	Replace any value in memory with the upper value (X).
<b>M+</b>	Add the upper value (X) to the current value in memory.
<b>C</b>	Clear X and Y, does not clear memory.
<b>CE</b>	Clear the current lower value (Y).



# Chapter 8 – Support Tools and Features

## Inspection Program Editing Tools

Some Geomet Junior functions are active only in the self-teach and offline modes. These tools are designed to modify the inspection program for feature placement, feature modifications and report customizations.

### Undo

Keyboard: Ctrl + U

Menu: Modify ⇒ Undo

The Undo command removes the last entry in the inspection report, and resets any state changes that may have occurred. This command can be used repeatedly to remove many features. It does not have a Redo option and therefore any features removed can not be restored, *see Edit History for advanced Undo options.*

### Delete

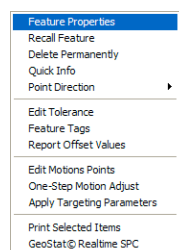
Keyboard: i

Menu: Modify ⇒ (Un)Delete

The Delete command marks a feature as being deleted in your inspection report. A feature marked as delete is not acted upon in an inspection run. The Delete command verifies that the feature has no references attached to it. These include whether the feature was used in a recall, construction or is part of a PCS component. When a feature has been marked as Deleted, The Delete command will un-delete the feature and make it active again.

### Accessing the Delete Command

There are several methods that can be used to activate the Delete Tool. Through the keyboard, press < i >. To work directly in the inspection report, highlight the feature and right click to activate the feature submenu and select [*Feature Properties*].



Right Click Activation



Feature Properties



Delete Tool

# Chapter 8 – Support Tools and Features

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## Deleting a Feature

To delete a feature, activate the Delete tool. Enter a Feature Number that specifies the feature to be deleted. Press the <Ok> button and the feature will be changed in the inspection report and marked as deleted.

If you are deleting the feature through the Feature Properties tool, place a check next to “Deleted”.

## Un-Deleting a Feature

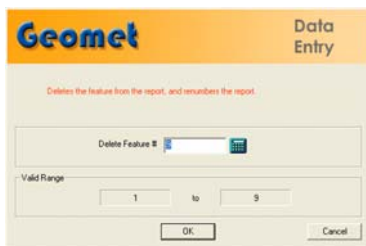
To un-delete a feature, activate the Delete Mode. Enter a Feature Number that specifies the feature to be un-deleted. Press the <Ok> button and the feature will be changed in the inspection report back to its original state.

## Delete Permanently

---

Menu:           Modify ⇒ Delete Permanently

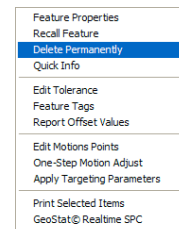
The Delete Permanently command removes a feature in your inspection report. Unlike the Delete Command, the feature will be removed and the remaining features will move up and be renumbered. The command verifies that the feature has no references attached to it. These include whether the feature was used in a recall, construction or is part of a PCS component.



Delete Permanently Tool



Validation Warning



Right Click Activation

To remove a feature, activate the Delete Permanently mode. Enter a Feature Number that specifies the feature to be removed. Press the <Ok> button and the feature will be validated to ensure there are no references attached it. If approved it will be removed from the inspection report and all features after that will be renumbered.

Removing a feature can also be done through the use of the mouse by highlighting the feature in the inspection report and calling the submenu by right clicking. Choose [*Delete Permanently*] to complete the operation.

NOTE: If the feature has references attached to it, Geomet Junior will prompt the operator with a Validation Warning. The Delete Permanently command can not delete any features that have references attached to it.

# Chapter 8 – Support Tools and Features

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## Delete All After

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Menu:           Modify ⇒ Delete All Records After...

The Delete all Records After... command prompts for a feature number that will become the last feature in the report. All features after that position will be deleted.

### Deleting Features from a Starting Point

To delete all features after a specified feature number, activate the Delete All After Mode. Enter a Feature Number, which specifies the last feature to keep, and all features after this number will be deleted. Press the <Ok> button and the inspection report will update to reflect the command.

Geomet Junior will prompt you to confirm your request.

*Tip: If you highlight your feature in the inspection report then activate the Delete All After tool, the feature number will transfer into the dialog automatically.*

NOTE: When this command has been executed, the features are permanently removed. Only through the use of the Advanced Edit History Tool can they be retrieved.



# Chapter 8 – Support Tools and Features

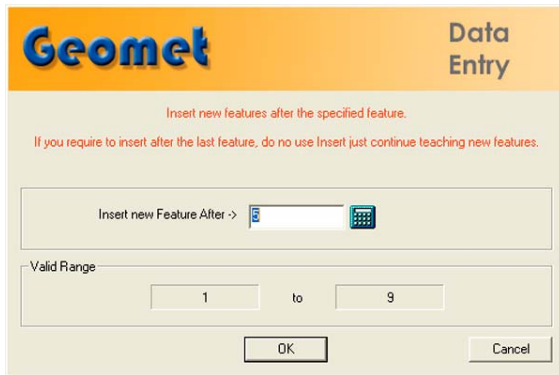
---

## Insert

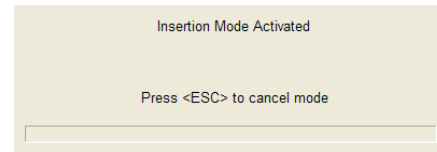
---

Keyboard: shift + I

Menu: Modify ⇒ Insert



*Selecting a feature to insert after*



*Insert Active Notice*

## Inserting a New Feature

To insert a new feature, activate the Insert Mode. Enter a Feature Number that specifies where the insert will take place, *see figure above*. The new feature will be after the feature number you have entered. Press the <OK> button and the Insert Notice will appear. When a new feature has been inserted, Geomet Junior updates all feature numbers and record links to ensure references to features remain intact.

Features that can be inserted:

- Measured Feature
- Constructed Feature
- Text and User Prompt
- Distance, Angle, Bisector and Intersect

Features that are blocked include:

- PCS Components
- Stylus Changes

Cancel the Insert Mode by pressing the Escape key.

*NOTE: When inserting a new feature with a motion map attached to it, care should be taken to ensure proper start and end IPs. After the new feature has been added, review your motion map.*

## Chapter 8 – Support Tools and Features

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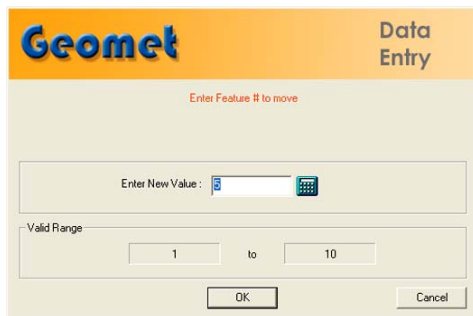
### Move

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Keyboard:   ctrl + i

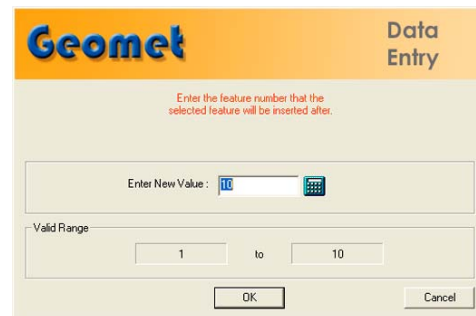
Menu:       Modify ⇒ Insert

The Move command allows the repositioning of a feature to another location within the inspection program. Assurances are provided to prevent moving to another PCS, or when the current probe is not the same as the feature's active probe.



The screenshot shows the 'Geomet Data Entry' dialog box. At the top, it says 'Enter Feature # to move'. Below this is a text input field labeled 'Enter New Value:' with a numeric keypad icon. Underneath is a 'Valid Range' section with two input boxes containing '1' and '10', separated by the word 'to'. At the bottom are 'OK' and 'Cancel' buttons.

*Selecting a feature to move*



The screenshot shows the 'Geomet Data Entry' dialog box. At the top, it says 'Enter the feature number that the selected feature will be inserted after.'. Below this is a text input field labeled 'Enter New Value:' with a numeric keypad icon. Underneath is a 'Valid Range' section with two input boxes containing '1' and '10', separated by the word 'to'. At the bottom are 'OK' and 'Cancel' buttons.

*Select a new position*

To move a feature, enter a number of the feature to be moved, *see figure above*. Press the <Ok> button then enter the location in the inspection report the feature will be moved to. Press <Ok> and Geomet Junior will validate your request and perform the move.

When the feature has been moved, Geomet Junior renumbers all feature numbers and record links to ensure references to features remain intact.

*TIP: Should you want to permanently delete a feature, such as feature number 15 of a 50 step inspection program. Start by moving the feature to the end of the inspection report. Once this has been accomplished, Press <Ctrl + u> which is the Undo command.*

# Chapter 8 – Support Tools and Features

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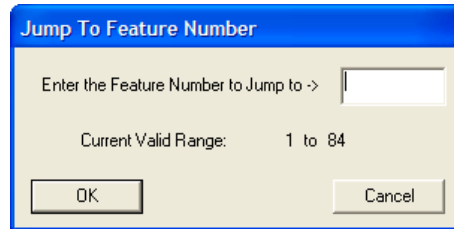
## Jump to Feature Number

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Keyboard:   ctrl + i

Menu:       Modify ⇒ Insert

The Jump to Feature Number command repositions the report view by placing the requested feature at the top of the display.



*Jump To... Entry Dialog*

## Jump to a Feature Number

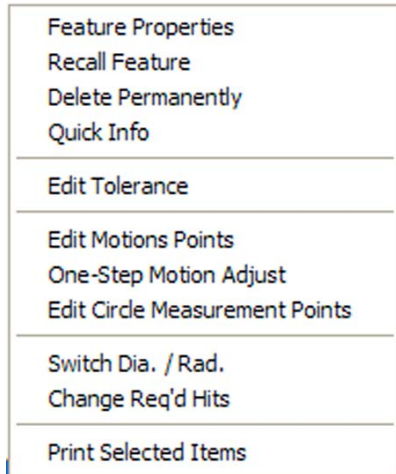
To reposition the inspection report to show a specific feature number, activate the Jump to command, <Ctrl + g>. Enter the feature number that will become the top feature in the display. Press <Ok> and Geomet Junior will scroll the inspection report to ensure the requested feature number is visible.

*NOTE: There is a special use condition for the Jump To Command during a part inspection run, see Re-Run Inspection Steps.*

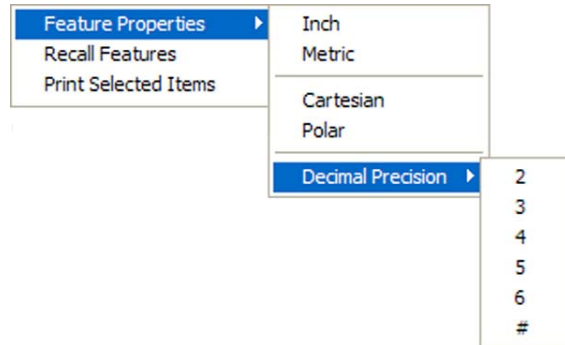
# Chapter 8 – Support Tools and Features

## Feature Properties

Feature Properties tools in Geomet Junior allows the changing of states, access to tolerance values and other feature specific information. To activate the tool, highlight one or more features and in the report area, right-click your mouse.



Single Feature Selection Submenu



Multiple Feature Selection Submenu

### Single Feature Selection Submenu

When only one feature has been selected in the inspection report, activating the Feature Properties tool provides an expanded set of commands, *see left figure above*.

The expanded Feature Properties tool is constructed with common commands, *see left figure above*, and feature specific commands, *see right figure above*. The common tools are shared with all features. The feature specific commands change to adapt to the selected feature.

# Chapter 8 – Support Tools and Features

## Single Feature Properties Tool

The Feature Properties tool is available when **one** feature is selected and provides a single source to control several characteristics of the selected feature.

### Feature Label

Enter a feature label that will replace the default name for that feature. For example: a measured plane is provided the standard name "-Z Plane", to change the name enter a label such as "Left Plane, PCS Base". This provides a more descriptive text to identify features.

### <Remove>

When a feature label has been applied, the <Remove> button returns the feature name to its standard label.

### Feature States Group

Within this group there are several reporting states that can be set for the selected feature. Choose the state by clicking on the bullet next to the choice or placing a check next to the command.

### Deleted

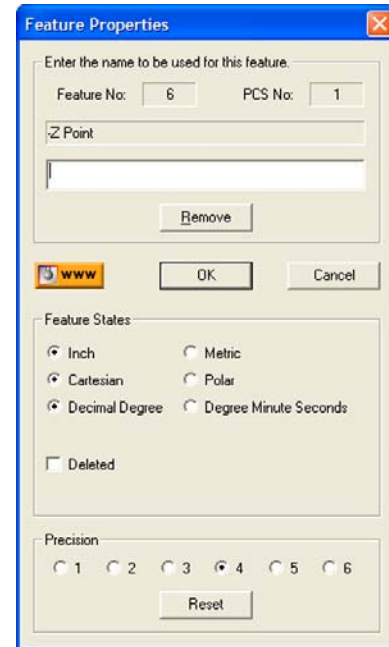
The feature Deleted flag controls the inclusion of this feature into the inspection report. This check box is acted upon when pressing the <Ok> button.

### Precision

Select a new precision value to be used when displaying and printing the selected feature.

### <Reset>

The <Reset> command returns the decimal place precision to the current default setting as defined in the [System Options⇒Tolerance] page.





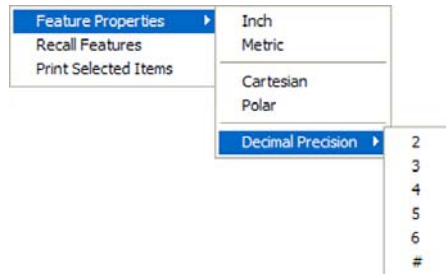
# Chapter 8 – Support Tools and Features

## Multiple Feature Selection Submenu

The Feature Properties can be changed on multiple records using the right-click Sub-Menu command, *see Multiple Feature Property Submenu*. This method does not provide controls to specific feature attributes.

A menu appears when you select Feature Properties, *see Reporting States*. This menu provides access to report states and precision values.

To select a new precision value, select Decimal Precision and choose a new value, *see Precision Setting*. To reset the precision value, select <#>.



*Precision Setting Example*

Geomet Junior will update all highlighted features with your requested changes.

*NOTE: If the highlighted features are mixed reporting states or precision values, this command will over write all settings to the common choice being made.*

### **[Recall Features]**

When the Recall Feature command is selected, each selected feature will generate its own programming step, or transaction file entry which is appended to the inspection report and will be operated on as a unique entity by other Geomet Junior functions. For example, if features 16, 25, 26 and 32 are highlighted in an 89-step program, they will be appended as 90, 91, 92 and 93.

As in all Geomet Junior functions, feature validations are applied to ensure credible recalls. These include ensuring the features being recalled are from the same PCS as the current PCS to name just one. Feature links will be updated to reflect any changes.

### **[Print Selected Items]**

This command will generate a printed report consisting only of the highlighted features. This is not a programmable step and is acted upon immediately.

# Chapter 8 – Support Tools and Features

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## Report Navigation Keys

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There are several key presses that compliment the standard Windows interface to scroll and reposition through the displayed inspection report. In Windows, a list, or report that exceeds the boundaries of the display will provide scroll bars normally located on the right and bottom of the view. Using these scroll bars requires the use of the mouse that controls the positioning by sliding the "Scroll Box". For further assistance on using scroll bars, please review Help in Windows.

Geomet Junior provides shortcut key presses to control the positioning of the inspection report in the available area on the display.

Geomet Junior Inspection Report Navigation Keys	
<b>Down Arrow</b>	Moves the inspection report down one line.
<b>Up Arrow</b>	Moves the inspection report up one line.
<b>Left Arrow</b>	Moves the Inspection report to the left one character.
<b>Right Arrow</b>	Moves the Inspection report to the right one character.
<b>Home</b>	Scrolls the report to show the Header (focus required).
<b>Ctrl + Home</b>	Scrolls the report to show the Header (focus not required).
<b>End</b>	Scrolls the report to show the last feature (focus required).
<b>Ctrl + End</b>	Scrolls the report to show the last feature (focus required).
<b>Ctrl + g</b>	Jump to a specific feature number.

*NOTE: Windows sends all key presses to the Window or Dialog that has "Focus", considered the current topmost active window. For example, if you have Geomet Junior and another program, such as Excel active, the program that has "Focus" will receive all key presses. If you press the <Home> key when the inspection report is not the current "Focused" control, no response is seen.*

To illustrate, open a long inspection report and click your mouse in the graphic area. Press <Home> or <End> and the inspection report does not move. That is because the graphic window has the current focus. Click your mouse in the report area and repeat the key presses and the report will scroll according to your commands.

# Chapter 9 – Reverse Engineering

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## Chapter 9 – Reverse Engineering

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# Chapter 9 – Reverse Engineering

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# Chapter 9 – Reverse Engineering

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## Introduction

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Geomet Junior offers many tools to assist in reverse engineering. These tools include feature data point scanning and exporting measured features and data clouds as IGES entities.

Our Reverse Engineering tools have been developed to facilitate producing accurate dimensional geometric CAD representations of unknown or undocumented parts. Identifying prismatic features such as circles, planes, cones and other defined geometric features combined with data clouds can then be exported into a file format that a CAD system could read. The CAD system will then analyze the information and form the solid objects or motion paths for CNC tools.

## Reverse Engineering for Surface Generation

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The capturing of data points over an unknown surface utilizing a Coordinate Measuring Machine produces a data point cloud of XYZ values. The values represent the ball center of the stylus attached to the CMM. Touch probes are triggered devices that do not provide information as to where on the stylus ball the actual tangent point of the surface contact occurred.

Therefore, utilizing the data cloud in reverse engineering requires that the CAD system must perform an offset surface command before the final solid is created. To assist the CAD system, Geomet Junior offers controlled data point collection tools and the exporting of fitted B-Spline Curves through the data points.

# Chapter 9 – Reverse Engineering

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## Summary of Reverse Engineering Tools:

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**Manual Free Scan** - Capturing of discrete data point clouds utilizing manual or DCC CMMs. Includes support for electronic touch and hard probes.

**GeoTracer** – Hard probe drag scanning used on manual CMMs.

**Cardinal Spline Generation** - A cardinal spline is a series of individual curves between points joined to form a larger curve. The spline is specified by an array of points and a tension parameter. A cardinal spline passes smoothly through each point in the array; there are no sharp corners and no abrupt changes in the tightness of the curve. By passing through every point, there are no missed points that can cause errors when fitting a surface over the splines.

**Exporting IGES Entities** - Export tool used to create an IGES file useful when sending data to a CAD system.

# Chapter 9 – Reverse Engineering

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## Manual Free Scan

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Keystroke: /

Menu: Measure ⇒ Perform Selected Scan

This method requires the operator to perform the actual capturing of data.

### Capturing a Data Cloud

The operator manually captures data points by making contact with the surface. Points are entered either using an electronic touch probe, or depressing the foot switch when using hard probes. The XYZ recorded data represents the ball center of the stylus.

### Controlling the Data Cloud

This method does not produce a controlled capture of data. It relies on the operator to capture the data cloud in some uniform procedure. If capturing with a manual CMM, it is helpful to lock an axis, such as the x-axis, and capture data points moving in the Y direction. Then unlock the X-axis and reposition to a new X location and repeat the process to create a new column of data.

Creating columns of data points will be easier to manipulate by a CAD system if it is required to build a surface.

When sufficient data points have been captured, press the < F5 > function key to record the data points.

# Chapter 9 – Reverse Engineering

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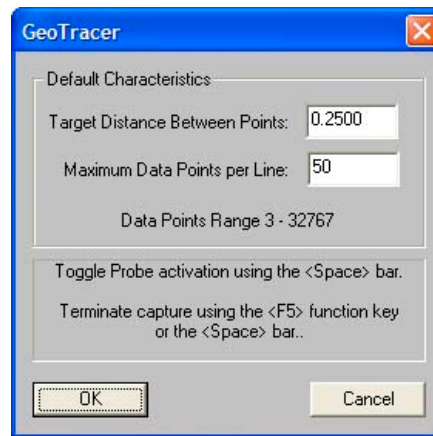
## GeoTracer

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Menu: Measure ⇒ GeoTracer

GeoTracer is one member of the Geomet Junior Suite of Reverse Engineering Tools. GeoTracer is designed to capture large data point clouds using a hard ball probe by dragging the probe over a surface.

When activating the GeoTracer tool, you will be presented with a dialog there you set the performance characteristics.



*GeoTracer Setup Tool*

### **Target Distance between Points:**

The value entered becomes the length Geomet Junior will use to establish the minimum distance between data points. When GeoTracer is in motion, the CMM sends a constant stream of data points to Geomet Junior. The first data point captured will be stored and all incoming data points will be compared to the first point until the distance between points exceeds the target distance. Once that minimum distance has been met, the second point will be captured and the process repeats itself.

### **Maximum Data Points per Line:**

The value entered here will limit the size of a single data cloud that is stored as a single feature. Once the data cloud size equals this value, Geomet Junior will create a new feature in the inspection report that contains the captured data points. Geomet Junior will then recycle the GeoTracer allowing you to continue capturing data without stopping. The purpose of limiting your data cloud size is only for convenience to limit how much data will be included in one feature.



# Chapter 9 – Reverse Engineering

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## Capturing Data with GeoTracer

When you close the GeoTracer parameter dialog, you will be prompted to capture data points.



*GeoTracer Probe Disabled Prompt*

When the prompt appears, the capturing of the data points is suspended allowing you time to move the CMM into position on your part. This is indicated by the **\*\*\* Probe Disabled \*\*\*** statement next to the Current Status prompt.

When you are ready to capture data, press the <space bar>, or depress the optional foot switch. Geomet Junior will now capture data when you start moving your probe across the part. Pressing the space bar again will cause Geomet Junior to return to a Disabled Probe state and create a feature with the captured data points.

## The Captured Data Cloud

The data points being captured will be the XYZ location of the probe ball center. Since probes do not offer vector feedback informing the host measuring software where the contact point was on the ball, a determination of surface points is not possible. This condition can be corrected by exporting the data clouds to most of the popular CAD software systems and then constructing a surface followed by offsetting that surface by the probe radius.

## Useful Tips

If your intent is to take the data clouds and export them to a CAD system, it is helpful to organize how you capture the data clouds. Most manual CMMs offer locking mechanisms on the X, Y and Z-axes. This allows you to lock one axis and drag the probe over your part to form a single line of data points. When you reach the end of your captured data point line, press the <space bar>, this will create a feature in the inspection report. Next, remove the lock and move to a new location and reset the lock repeating the drag operation to create a parallel set of data points.

# Chapter 9 – Reverse Engineering

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## Performance Considerations using GeoTracer

The quality of the data points can be affected by the speed of the CMM while capturing the data points. A CMM interface captures the XYZ scale values based on a timed cycle. Some interfaces cycle 30 times or more per second, such as the Helmel ProCounter series. At this cycle speed you will capture a consistent set of data points while dragging your hard probe at normal speeds between 2" (51mm) and 5" (127mm) per second which translates to capturing approximately 20-50 points per second.

If your CMM interface cycles at a lower rate, such as most interfaces on Direct Computer Control (DCC) CMMs, the cycle can be slowed down to as little as 3 cycles per second. On this style CMM the actual reading of the XYZ scales is performed by the motion controller and forwarded to the host measuring software as a status update. At the slower cycle rate, the drag speed required to produce a uniform set of data points must be reduced to speeds around 1" (25mm) per second.

Should the drag speed be too fast the spread between data points will be greater than the requested distance set in the GeoTracer Parameters. If you find undesirable results in the spread of your data points, slow down the drag speed.

# Chapter 9 – Reverse Engineering

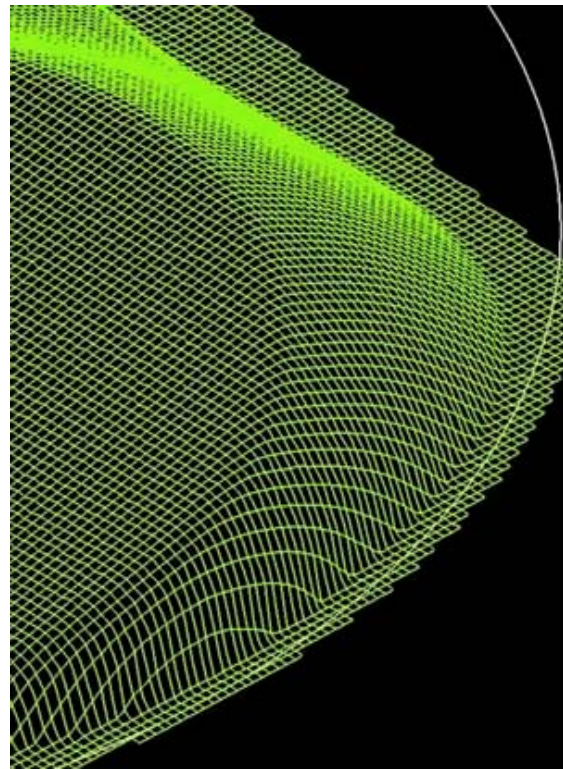
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## Cardinal Spline

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A cardinal spline is a series of individual curves between points joined to form a larger curve. The spline is specified by an array of points and a tension parameter. A cardinal spline passes smoothly through each point in the array; there are no sharp corners and no abrupt changes in the tightness of the curve. By passing through every point, there are no missed points that can cause errors when fitting a surface over the splines.

The tension of a cardinal spline determines the fitting of each curve section in regards to the data points. The range for the tension value is 0.0 to 1.0 where 1.0 would deliver straight lines between the data points and 0.0 would produce the most flexible curves fitted through each data point.

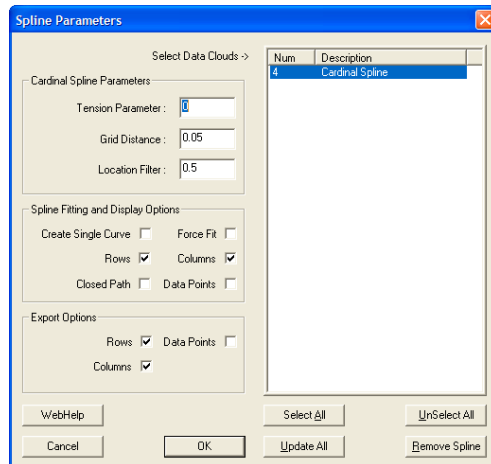


### Starting the Cardinal Spline Tool

The Cardinal Spline feature works on data clouds captured through the various scanning methods available in Geomet Junior. To activate the feature, locate the data cloud feature in the inspection report and highlight it using the left click of the mouse. Then right click to bring up the sub menu. Locate [*Cardinal Spline*] in the list and click on it.

# Chapter 9 – Reverse Engineering

## Setting the Cardinal Spline Parameters



*Cardinal Spline Setup Tool*

There are three parameters used to tune the fitting process for splines. These are: Tension, Grid Distance and Location Filter. Understanding these parameters will greatly enhance your success in creating splines from data points.

### Tension Parameter

This value controls how the spline is fitted between the data points. The valid range is 0.0 to 1.0 where 0.0 produces the largest radius between data points and 1.0 will produce straight lines between data points. We recommend that 0.0 be used as a default.

### Grid Distance

This is the setting used when the original data points were scanned. Geomet Junior carries it over from the scanning operation. However, on earlier Geomet Junior systems, this value was not included in the original scan features and should be entered manually.

When applying Cardinal Splines to data clouds that do not conform to a uniform row / column configuration, undesirable results may occur. In this condition, Geomet Junior allows the selection of "Create Single Curve" and "Force Fit" which is explained later in this document.

# Chapter 9 – Reverse Engineering

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## Location Filter

Geomet Junior starts building rows and columns first by sorting the data points into row and column order. The location filter is applied when Geomet Junior moves down a column and 'looks' for the next data point. For example: if the column has a start point with a "Y" value of 1.000", it would look down the column and expect to find the next point also with a "Y" value near 1.000". Since scanning operations do not deliver exact position, the data point under the start point might have a "Y" value of 1.012". The Location Filter is a factor of the grid distance where 0.15 would yield a search zone of  $0.15 * \text{Grid Distance}$  ( $0.15 * 0.05 = .0075$ ). This value determines the zone around the original "Y" value of 1.000" and the column sorting would not include the next point at 1.012.

In data clouds that have well-defined row and column structures, the Location Filter can be low, such as 0.25. In poorly defined patterns, use a value between 0.5 and 0.9.

When the value is set too high, the splines created can "jump" to neighboring points from other columns.

## Spline Fitting and Display Options

Under the group designated as "Spline Fitting and Display Options", you can establish the spline methodology and fitting behaviors.

## Create Single Curve

This option will take all your data points without regard to rows and columns and fit the curves through each point in the same order as the points were captured. This option is designed to work with data points captured with GeoTracer where you capture data points in a line with distinct start and finish end points. When this option is checked, the display and export of one spline for this feature will occur.

## Rows / Columns

Row and Column selections are available when Single Selection is not chosen. They are designed to work with data points gathered under the automatic scanning tools in Geomet Junior. These scanning tools capture the data points in organized Row and Column formations that can be extracted to deliver uniform splines. When selecting Row and/or Columns, Geomet Junior will attempt to build straight lines in the XY plane of the captured data points. Then rows and columns are extracted and used to form the splines. It is important that these rows and columns are organized in controlled positions. *See Setup Parameters above.*

# Chapter 9 – Reverse Engineering

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## Force Fit

This option is used when Rows and Columns are active. When calculating, some data points might be skipped if they do not fall within the parameter settings. This can cause a row to contain 2 or more splines. When selecting Force Fit, all data points identified in the row or column will be used to fit one spline. Another use for Force Fit is when there were exclusion zones used in data point scanning. This will fit the spline over the exclusion zone.

## Closed Path

When this option is checked, Geomet Junior will attempt to close the path from the last data point to the first.

## Data Point

When selected, this option will display the complete set of data points in addition to any splines selected for showing.

## Export Options

These options, combined with Spline Fitting and Display Options control the export characteristics. The selections of Row and Column for export are available when Create Single Curve is NOT selected. **NOTE: selecting Row and Columns in the Display group does not automatically create exported rows and columns!**

*NOTE: Cardinal Splines is exported in the IGES format only!*

## Rows

This selection will create and export splines derived from the data points that conform to rows. The rows exported are controlled by the selections of Force Fit and Closed Path.

## Columns

This selection will create and export splines derived from the data points that conform to columns. The columns exported are controlled by the selections of Force Fit and Closed Path.

## Data Points

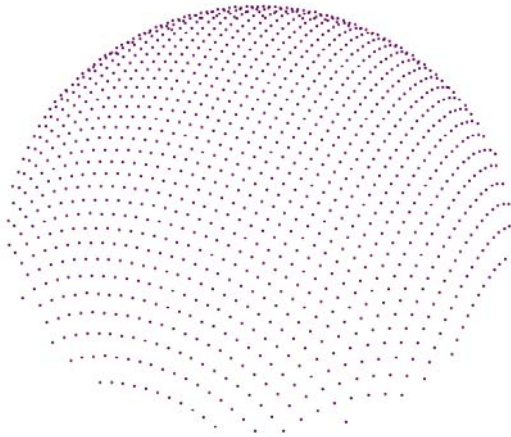
This selection will export the data cloud in addition to any row and column selection already made.

## Chapter 9 – Reverse Engineering

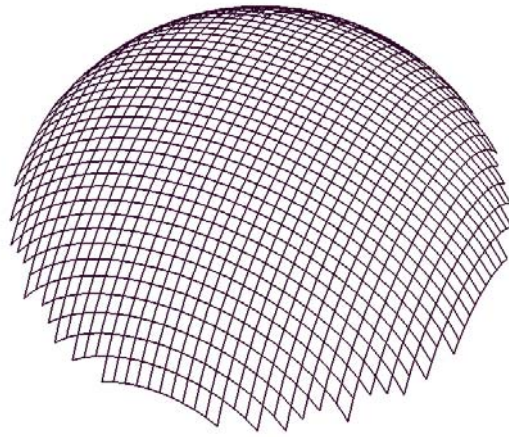
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### Executing the Cardinal Spline

Once the parameters have been set, highlight from the list of data clouds the features you want the Cardinal Spline function to work with. Process the request by press <Ok> to build the Cardinal Splines.



*Captured Data Points*



*Fitted Cardinal Splines*

The illustration above shows the application of Cardinal Spline to a raw set of data points that have been captured with Radial Boundary Contour using a grid spacing of 0.020".

### Removing Cardinal Splines

To remove the Cardinal Splines from a feature, highlight the feature and press the <Remove Spline> button.

# Chapter 9 – Reverse Engineering

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## Exporting

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Menu: File ⇒ Export ⇒ Export

Geomet Junior can export features and data points in three formats.

ASCII and DXF: Exports data point clouds and 3D Point entities. On features, such as a circle, only the data points used to calculate the feature would be exported.

IGES: This format exports all features based on the following table.

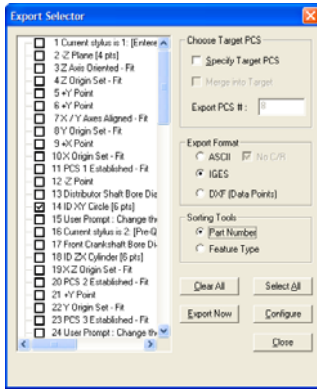
Summary of IGES Supported Features	
Type	Definition
100	Circular Arc Entity
104	Conic Arc Entity
108	Plane Entity
110	Line Entity
116	Point Entity
126	Rational B-Spline Curve Entity
128	Rational B-Spline Surface Entity
144	Trimmed (Parameteric) Surface Entity
158	Sphere Entity
190	Plane Surface Entity
196	Spherical Surface Entity
504	Edge Entity
508	Loop Entity
510	Face Entity



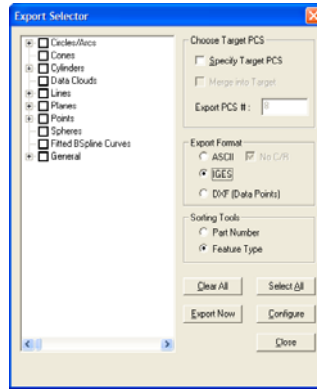
# Chapter 9 – Reverse Engineering

## Exploring the Export Tool

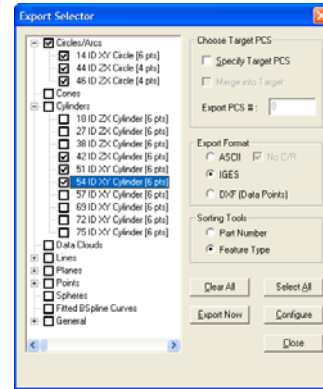
The Export Tool displays a feature list of your current inspection. This list can be sorted between Part Number or into common feature groups such as Circle and Planes.



Sorted by Feature Number



Sorted into Groups



Selecting by Groups

## Selecting Features for Exporting

Selecting features can be done in a random fashion or by using <Select All>. When sorted by Feature Number, the selection process is accomplished on a feature-by-features basis by placing a check next to the feature. When sorted by Groups, the selection process can be done on a single feature basis by expanding a group using the <+> button and checking the feature. To select all features within a group, place a check next to the group name.

## Setting the Decimal Precision

Setting the precision is done through the <Configure> button. Always set a reasonable precision that will allow a well-defined exported feature. The default for this value is 5.

## Basic Export

With the selection of features, you can now proceed to the export function. Press <Export> and the standard Windows Save-As dialog will appear. Locate the folder and assign a file name to your export and press <Save>.



# Chapter 9 – Reverse Engineering

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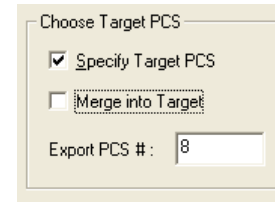
## Enhanced Export Tools

There are two options available that will enhance the exporting of features. These options control the Part Coordinate System during the export process.

Under normal conditions, all features are exported in the original position within the CMM envelope, commonly referred to as the Machine Coordinate System. All features will retain the position and orientation to other features and in most cases this is sufficient. However, you may want to export into a specific PCS making the position and orientation local to the inspected part.

**Specify Target PCS:** This option allows a PCS to be specified that all features would be projected into. This is commonly used when you want a coordinate system locally on your part. When exported the misalignment to the MCS is removed and the exported features are aligned true to the selected PCS.

**Merge into Target:** This option allows merging of all features that were originally built in other PCSs into a common PCS for export. The result is an assembly that can combine all features into a single file. Those features may have been measured on the side, bottom or any orientation on the part.

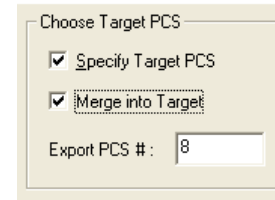


Choose Target PCS

Specify Target PCS

Merge into Target

Export PCS #: 8



Choose Target PCS

Specify Target PCS

Merge into Target

Export PCS #: 8

# Appendix 1 – Technical Notes

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## Technical Notes

Multi-Point Feature and CMM Inherent Errors ..... App 1 - 3

# Appendix 1 – Technical Notes

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# Appendix 1 – Technical Notes

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## Multi-Point Feature and CMM Inherent Errors:

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Applies to: All Levels of Geomet Junior  
Last updated: Monday December 13, 2005.

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# Appendix 1 – Technical Notes

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## Introduction

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Technical Note #2 - Multi-Point Feature Inherent Errors  
Published October, 14, 2003

Edward R. Yaris - Software Development Manager,  
Helmel Engineering Products, Inc.

## Commonly found Errors

- CMM Calibration Errors
- Probing Errors
- Operator Influences
- Data Point Spread

## System Errors

In all multi-point features, the ability to report accurate and repeatable results are subject to the quality of the gathered data points. Influencing your measured results will be the stacking of inaccuracies within your measuring system generated by the commonly found errors listed above.

## Coordinate Measuring Machine

### Scale Error

The CMM has inherent inaccuracies such as axial linear error and mechanical limitations on squareness, parallelism and perpendicularity. Every CMM has a scale attached to each axis of movement. This scale can be a mechanical / optical or laser configuration. In the case of a mechanical / optical there exists positioning error which CMM manufacturers will attempt to compensate for through hardware or software.

For example when a scale is installed, it will be compared to a master scale or laser. The CMM will be positioned along the scale at different points and the reported position will be compared to the master. If the position reported by the laser was 10.00000 and the CMM reported 9.99875 The difference will be the linear inaccuracies of the scale at that position. In a single linear compensation, a scale factor will be applied to the CMM's position feedback to correct for the error. However, this method of compensation works with the overall average and does not correct for local inaccuracies along the scale.

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## Single Variable Linear Scale Compensation

Figure 1 demonstrates the Position Error measured compared to a Master Scale or Laser. The scale along the left side illustrates the deviation error.

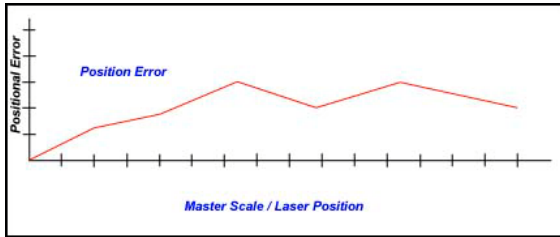


figure 1, Original Position Error

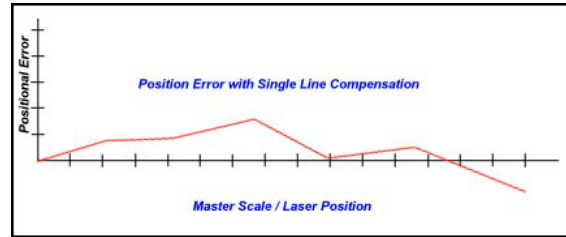


figure 2 – Single Linear Compensation

After single line compensation has been applied the deviation error has been minimized to create a more accurate position.

One limitation in single line compensation is that the variances along the scale can not be individually removed. Therefore the single line compensation method only averages out the entire scale without regard to multiple position errors. When the CMM is positioned along the scale, some error characteristic will still be built in.

## Non-Linear Scale Compensation

Another method to minimize scale-positioning error is the Non-Linear method. This method builds a table of compensation values that can be measured and created along the various undulations along the scale. It requires that the CMM has a reproducible home position for all axes. The chart below illustrates a non-Linear method applied to the same scale shown above. The error has been reduced further.

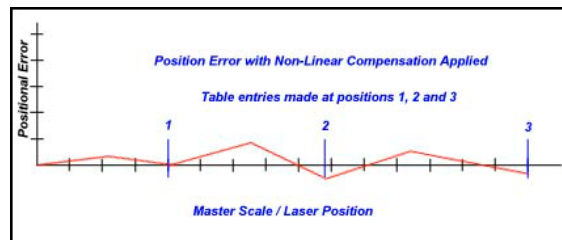


figure 3, Non-Linear Compensation Applied

As with any linear compensation method, if the scale is not mapped out over every position, then an error will always be present influencing your results.

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## Mechanical Intrinsic Accuracy

The next error that a CMM can have is called intrinsic accuracy, the mechanical accuracy of the CMM. These include Squareness, Perpendicularity and Parallelism of the structure of your CMM. If the X-axis is not perpendicular to the Y-axis, then when the probe is moved along the X-axis a deviation in Y will occur. To test for this, place a certified square down on the CMM base. Place a .0001” or better indicator on the probe bar and lock the Z and X-axes from moving. Move the CMM in the Y-axis with the Indicator in contact with the square. Set the square edge parallel with the Y-axis travel until no movement is shown on the indicator. Unlock the X-axis and reposition the indicator so it contacts the square and lock the Y-axis. Move the indicator along the X-axis and you should not see movement on the indicator dial.

Repeat this procedure in the front and back location on your CMM to ensure the X to Y-axis relationship is perpendicular throughout the measuring envelope. An additional test would be to raise the square to the highest point within your measuring cube and repeat the procedure.

Should you see a deviation, then your CMM is **not square** in the XY plane. Any measurements taken will have an inherent inaccuracy.

The Z-axis should be perpendicular to the CMM base. To test this, place a .0001” or better indicator on the probe bar. Place a certified square on the CMM base with the surface parallel to the Y-axis. Lock your X and Y-axis with the indicator in contact with the square. Move your Z-axis up and down, you should not see any movement on the indicator. Now repeat the test with the surface of the square parallel to the X-axis.

Should you see a deviation, then your CMM is **not square** in the ZX and / or YZ plane. Any measurements taken will have an inherent inaccuracy.



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## Ball Bar Test for CMMs

One method to accurately evaluate axis to axis relationships is found in the B89.4.1, Methods for Performance Evaluation of Coordinate Measuring Machines published by ASME International. This Standard establishes requirements and methods for specifying and testing the performance of coordinate measuring machines (CMMs) having three linear axes perpendicular to each other and up to one rotary axis positioned arbitrarily with respect to these linear axes. In addition to clarifying the performance evaluation of CMMs, this Standard seeks to facilitate performance comparisons among machines by unifying terminology, general machine classification, and the treatment of environmental effects.

The Ball Bar consists of a temperature-stabilized bar with two high precision spheres mounted at each end, *see figures 4 and 5*. The length between the spheres is not necessary to be known. In the B89.4.1 specification there is a recommended length based on the size of the CMM. The Ball Bar is positioned within the measuring area of the CMM in 28 different positions as described in ASME B89.4.1.



*figure 4, Ball Bar Test Set*

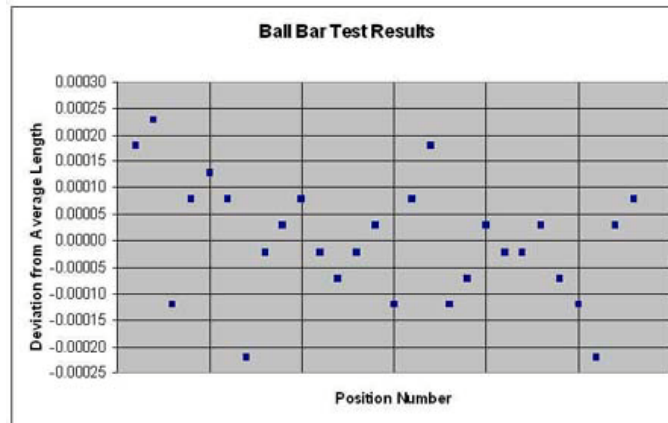


*figure 5 – Shown in Elevated State*

The process of gathering data involves the measuring of each sphere and calculating the direct line distance between them. One advantage of this method over other methods, such as a step gage, is the averaging effect of the probe lobe errors. In any given direction around the traditional touch probe, there exists a lobing error that can be measured, but not effectively removed from a feature calculation. By capturing data points evenly around the sphere, the lobe error variations are not removed, but averaged out to obtain a closer size and location reporting of the actual sphere.

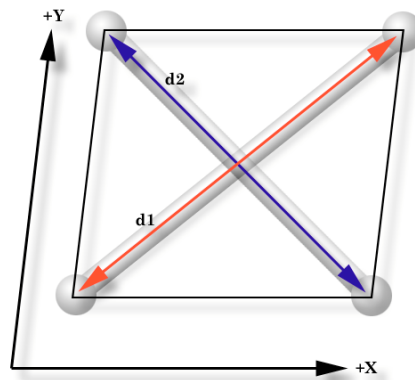
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Once all 28 positions have been calculated, they can be entered in an Excel spreadsheet. The average of all 28 positions is first obtained and a companion column of actual - average is calculated. These values are then plotted, *as shown in figure 6.*



*figure 6, Ball Bar Results*

The Maximum and Minimum values are found from the deviation column. The spread between these values is considered the working tolerance. This value is often reported as the volumetric accuracy of a CMM. It should be noted that the length of the ball bar is often a small fraction of the actual measuring area. Therefore, the reported working tolerance only reflects the area the cubic size of one ball bar length in the X, Y, and Z and should not be used to define the entire CMM.



*figure 7, X / Y Squareness Deviation*

In figure 7, we can visualize how to interpret the Ball Bar tests. We can see the direct effect of a squareness deviation of the X versus Y-axis. The measured distance of the lengths, d1 and d2, should be equal when the CMM has been properly setup. As the illustration shows, d1 being greater than d2 which demonstrates that the relationship between the X and Y-axis are not

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perpendicular. When properly interpreted by a trained calibration engineer, all 28 positions will effectively provide a picture of the intrinsic characteristics of your CMM.

Many CMM manufacturers have abandoned building intrinsic accuracy in favor of 3D software compensation. This allows building of a CMM with little attention to the accuracy of the assembly. The accuracy is accomplished by mapping the CMM with a known standard, such as a laser, then providing 3D compensation algorithms to correct the inherent errors. However using only a laser does not remove all the inherent inaccuracies within the entire measuring cube.

There is no correct answer as to which method delivers a more accurate CMM. In both cases, the ability to perform field calibrations often becomes an economic cost the user must absorb. To perform a field calibration by mapping the CMM with a laser system is a higher cost than adjusting for intrinsic accuracy.

### Probe System Errors

Every probe system introduces inaccuracies to your data point gathering. These include capture speed, lobe errors, stylus lengths and probe contact pressure. Understanding the errors within the probe system can be very difficult. Most electronic touch probes have no index position when installed on a CMM and can rotate to a new location moving the lobe error. Additionally, electronic touch probes are a simple switch and can not determine the approach vector at the point of contact. This simple fact makes it very difficult to map out probe errors.

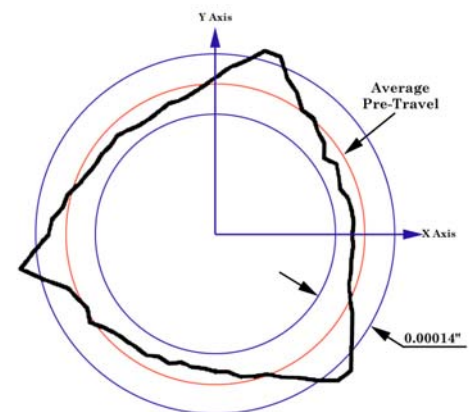


figure 8. Lobe Error Example

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Lobe errors are mechanical limitations to the probe head. Lobes can have an error in excess of .0001” deviation when capturing a point moving at 0° compared to capturing a point at 60°. As shown in figure 8, the lobe error pattern is triangulated based on the mechanical layout of the kinematics probe alignment, see figure 9. The touch probe can be described as having low and high force directions when capturing a trigger, see figures 10 and 11.

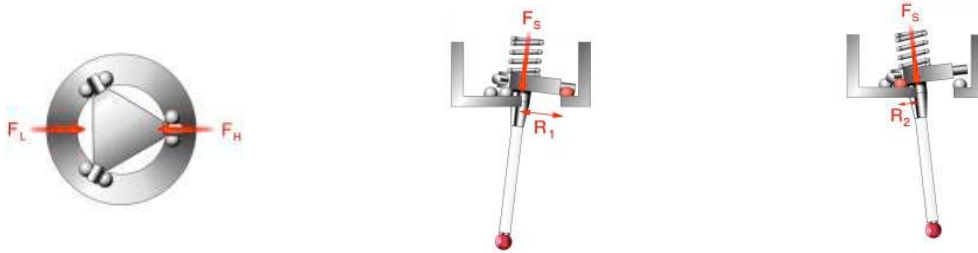


figure 9, Force Direction      figure 10, High Force Direction      figure 11, Low Force Direction

Stylus lengths will add additional error to your system. A short length of about 10mm will not influence your data points, however a 100mm length will increase the error 10 fold to the lobe deviation. If you need to extend your stylus, we recommend the Renishaw PEL family of extensions. These are extensions that mount between the probe head and probe body.

When the Trigger Force pressure is set too high, the probe error will increase exponentially! Most mechanical probes allow you to adjust the tension applied to the trigger mechanism, *see manufacturers technical manual*. Some touch probe models, such as the Renishaw TP20, offer interchangeable modules with a preset trigger force. By increasing the pressure, you force the probe to trigger at a higher pressure that introduces stress and deflections in the stylus tip and extension.

Strain-gauge or piezo designed probes, such as the Renishaw TP200, minimizes the lobe error by eliminating the mechanical kinematics design. However, these gauges are susceptible to speed changes and the actual contact speed should be stable and consistent. Probes that use this technology should not be considered for manual CMMs.

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## Operator Influences

Finally the operator will provide the greatest error. If the operator captures data points with an inconsistent speed, repeatability errors are introduced. To test for speed difference, lock the Z and X-axes on your CMM. Place a part on your CMM and measure a +Y point. Increase the speed at which your capture points. At a certain speed you will begin to see variances in the reported results.

Other operator related issues include where you hold the CMM. If you have a large CMM, probing while holding the probe bar just above the probe will act differently that when you are holding as far up the probe bar as possible. The probe bar is a lever, and by moving that lever you are placing strain on the superstructure of the CMM. If you gather data points before the CMM has ‘settled’ you will get unreliable data points.

## Data Point Spread

When measuring multi-point features, how you spread the data points will be the single greatest influence on the accuracy and repeatability of the feature. For example, if you capture data points on a circle using only a 15° sweep, the results are unreliable and not repeatable. If those same points were captured over a 300° sweep, the results would be accurate, *see figure 12*. The same holds true for Planes spheres, cylinders and cones. Cylinders and cones require a proper spread over the length otherwise the axis of the feature will not be reliable.

Arc(Degrees)	Center Error	Radius Error
180	0.00014	0.00000
120	0.00028	0.00014
90	0.00048	0.00034
60	0.00104	0.00090
30	0.00409	0.00395
20	0.00914	0.00899
10	0.03549	0.03535
5	0.12823	0.12810

*figure 12, Circle Errors*

Imagine capturing two points on a line only .25” apart with a probing error of .0001”. The resulting line would have a repeatability error of .040” over 5.000” or 0.4584 degree! If that line were used as part of the Part Coordinate System, then all subsequent features would have questionable accuracy.